

SWATH DESIGN MODEL
FOR COAST GUARD APPLICATIONS

Peter Bruce Fontneau

DUDLEY KNOX LIBRARY
NAVAL POSTGRADUATE SCHOOL
MONTEREY, CALIF.

SWATH DESIGN MODEL
FOR COAST GUARD APPLICATIONS

by

PETER BRUCE FONTNEAU

B.S. Webb Institute of Naval Architecture
1968

M.S. The George Washington University
1971

SUBMITTED IN PARTIAL FULFILLMENT
OF THE REQUIREMENTS FOR THE
DEGREE OF OCEAN ENGINEER

and the

DEGREE OF MASTER OF SCIENCE
IN NAVAL ARCHITECTURE AND MARINE ENGINEERING

at the

MASSACHUSETTS INSTITUTE OF
TECHNOLOGY

May, 1976

SWATH SYNTHESIS MODEL FOR COAST GUARD APPLICATIONS
BY
PETER BRUCE FONTNEAU

Submitted to the Department of Ocean Engineering on May 7, 1976, in partial fulfillment of the requirements for the degree of Ocean Engineer and the degree of Master of Science in Naval Architecture and Marine Engineering.

ABSTRACT

A computer design model for preliminary design studies for the Small Waterplane Area Twin Hulled ship (SWATH) with special applications to the missions of the United States Coast Guard is developed.

The SWATH ship is described. Its application to missions requiring a stable platform and/or helicopter capabilities are discussed. The development of a computer design methodology is reviewed. Estimating relationships required for the design are developed based on existing designs and design studies. A listing of the program, examples of the input and output formats and a user's guide are provided.

This model is applicable to SWATH ships of 100 to 300 feet in length and of 300 to 5000 tons displacement intended for use by the Coast Guard.

The results of the computer model are compared with existing Coast Guard vessels and an earlier Navy design for a SWATH Coast Guard Cutter. General agreement with the Navy design program is shown in principal dimensions.

Thesis Supervisor: Philip Mandel
Title: Professor of Naval Architecture

ACKNOWLEDGEMENT

First, the author is indebted to the United States Coast Guard for providing the opportunity and financial support for continuing his post graduate education for a second time. The assistance, supportive and friendly atmosphere created during this work and the guidance and provocative questions provided by Professor Philip Mandel is appreciated. Phyllis Balba, who typed the manuscript under considerable pressure, is to be praised for her efforts. Without the support of my wife, Karin, this work could not have been completed.

TABLE OF CONTENTS

	<u>Page</u>
ABSTRACT	2
ACKNOWLEDGEMENT	3
TABLE OF CONTENTS	4
LIST OF FIGURES	5
LIST OF TABLES	7
I SWATH OVERVIEW	8
II WHERE CAN THE COAST GUARD USE A SWATH SHIP? . . .	12
III INTRODUCTION TO THE COMPUTER DESIGN MODEL . . .	15
IV SWATH MODEL DEVELOPMENT	18
V GENERAL DESCRIPTION OF PROGRAM	23
VI DESCRIPTION OF THE PROGRAM	32
6.1 Introduction	32
6.2 MAIN Program	40
6.3 Subroutine XECUTE	54
6.4 Subroutine DIM	64
6.5 Subroutine HPCALC	72
6.6 Subroutine EPLANT	77
6.7 Subroutine LIQ	85
6.8 Subroutine MACHBX	92
6.9 Subroutine VOLUME	97
6.10 Subroutine WEIGHT	114
6.11 Subroutine VCG	130
6.12 Subroutine COST	137
6.13 Subroutine OUTPUT	145
VII EVALUATION	150
VIII CONCLUSIONS AND RECCMMENDATIONS	161
REFERENCES	165
Appendix A. USER'S GUIDE	168
Appendix B. PROGRAM LISTING	180
Appendix C. SAMPLE OUTPUT	235
Appendix D. WEIGHT BREAKDOWN	249

LIST OF FIGURES

<u>Figure</u>		<u>Page</u>
1	PROGRAM CONTROL ORGANIZATION	24
2	PROGRAM LOGICAL ORGANIZATION	25
3	TRIAL DISPLACEMENT VS. LENGTH	44
4	LENGTH/KGTRIAL VS. LENGTH	45
5	MAIN SUBROUTINE FLOW CHART	46
6a	XECUTE SUBROUTINE FLOW CHART	61
6b	XECUTE SUBROUTINE FLOW CHART	62
6c	XECUTE SUBROUTINE FLOW CHART	63
7	LENGTH/DIAMETER VS LENGTH	67
8	C _{IL} VS C _{WP}	68
9	DIM SUBROUTINE FLOW CHART	71
10	HPCALC SUBROUTINE FLOW CHART	76
11	AIR CONDITIONING LOAD VS NAC x CN x 10 ⁻⁵	80
12	HOTEL LOAD VS. NUMBER OF ACCOMMODATIONS . .	81
13	OTHER AUXILIARY LOAD VS. CUBIC NUMBER x 10 ⁻³ .	82
14	EPLANT SUBROUTINE FLOW CHART	84
15	LIQ SUBROUTINE FLOW CHART	91
16	MACHBX SUBROUTINE FLOW CHART	96
17	DECKHOUSE VOLUME VS. (LBP) ³	100
18	ARRANGEMENT AREAS	105
19	ARRANGEMENT AREAS	106
20	ARRANGEMENT AREAS	107
21	ARRANGEMENT AREAS	108
22	ARRANGEMENT AREAS	109
23a	VOLUME SUBROUTINE FLOW CHART	110
23b	VOLUME SUBROUTINE FLOW CHART	111
24	VEHICLE DENSITY VS. WEIGHT GROUP 1 WEIGHT FRACTION	118
25	WEIGHT GROUP 2 VS. SHAFT HORSEPOWER	123
26	WEIGHT GROUP 300 VS. RATED KW/GENERATOR . . .	124
27	WEIGHT GROUP 5 VS. ENCLOSED VOLUME	126

LIST OF FIGURES (Continued)

<u>Figure</u>		<u>Page</u>
28	WEIGHT GROUP 6 VS ENCLOSED VOLUME	127
29	WEIGHT SUBROUTINE FLOW CHART	129
30a	VCG SUBROUTINE FLOW CHART	134
30b	VCG SUBROUTINE FLOW CHART	135
31	COST INDICES VS. TIME	138
32	LABOR RATES VS. TIME	139
33	COST SUBROUTINE FLOW CHART	142
34	OUTPUT SUBROUTINE FLOW CHART	147

LIST OF TABLES

<u>Table</u>		<u>Page</u>
I	SWATH Model Limitations	21
II	Data Base for SWATH Model Development	34
III	Electrical Load Data	77
IV	Fuel Rate Assumptions	87
V	Machinery Sapce Data	93
VI	Arrangement Area Data	104
VII	Vertical Center of Gravity Data	133
VIII	Stabilization of Variables	154
IX	Comparison of Design Outputs	156
A-I	Payload Description Data	179

CHAPTER I

SWATH OVERVIEW

The overall purpose of this thesis is to develop a computer design model for preliminary design studies for a particular alternative hull form which has been suggested for use in various missions of the Coast Guard. First the concept of the Small Waterplane Area Twin Hull (SWATH) hull form and its possible uses in these missions must be described.

The conventional monohull displacement hull form has been the sole configuration used by naval services and commercial ventures in the marine field for hundreds of years. Only in the last quarter of a century have other types of marine transportation configurations been developed in an orderly and scientific manner. In that time the hydrofoil boat has been developed into sea-capable small ships, the air-cushion vehicle and surface effect ship have been developed and conceptual designs for small ships studied and there has been increased interest in ships in which motions were controlled by reducing the size of the waterplane. The Small Waterplane Area Twin Hull (SWATH) ship has been the subject of a major effort by the United States Navy to develop such a small waterplane area ship.

The SWATH ship which has been the subject of the Navy studies and is the subject of this study can be described as a pair of torpedo-like hulls submerged underwater and connected through the water surface to a box-like bridge structure by one or two struts per hull. The SWATH ship is fitted with twin propulsors in the after ends of the lower hulls

and with various control surfaces similar to the diving planes of a submarine which can be used to control the SWATH's motions and attitude underway.

The low waterplane area ship concept is not new however, but until the 1960's it had received little attention. One of the first single-hulled low waterplane ships was patented by Lundborg^{(1)*} in 1880. A twin-hulled low waterplane ship was patented by Blair⁽¹⁾ in 1930. A patent for a twin-hulled floating structure was granted in 1946⁽¹⁾. In the late 1950's a shark-form was proposed by the Navy and studied at MIT by Mandel⁽¹⁾. This hull form was similar to the Lundborg patent. In the late 1960's several student design projects⁽²⁾ and a proposal by Frankel⁽¹⁾ were based on the twin hull low waterplane area concept. In 1969 the Netherlands Offshore Company launched a 1200 ton twin hulled drilling rig called DUPLUS^(1, 3). Litton Industries developed the TRISEC concept⁽¹⁾ during the LHA program concept design phase. TRISEC was a low waterplane area ship with non-cylindrical lower hulls, large lifting foils attached to the lower hulls, variable draft and a single large strut per hull.

Starting about 1969 the Naval Undersea Research and Development Center (NUC) and the Naval Ship Research and Development Center (NSRDC) began studies on the low waterplane concept. NUC^(4, 5) designed a small test platform with two struts per hull and a displacement of 200 tons; NSRDC^(6, 7) continued to extend the data previously gathered on catamarans with the rational step to the low waterplane ship. These design efforts

*Numbers in parentheses refer to References listed at the end of this thesis.

and studies led to the development of a series of computer based conceptual design studies for SWATH ships⁽⁸⁾ and one full size prototype, the 80 foot, 190 ton SSP.

The SWATH ship has several advantages in operations. Because the size and locations of the waterplanes of the SWATH can be varied easily, a SWATH design may be optimized for minimum ship motions over a range of headings and ship speeds. Although the additional wetted surface area of the SWATH leads to higher frictional resistance values, the smaller waterplane area tends to reduce wave making resistance especially at high speeds. The low waterplane area and the fact that much of the ship's volume is well above the water in a box-like bridge structure also means that there will be little effect on speed and motions from a seaway. The large box structure leads to efficient utilization of payload space due to the rectangular plan of the spaces and to low production costs for the box. The large box also lends itself for utilizing large deck areas for helicopter landing areas or handling deck machinery or equipment packages.

As is the case with all design alternatives, the SWATH ship may have some disadvantages for the user. Because it is a different type of ship shape and because it will require more structural materials it may be a more expensive ship to build. The lower cost of its box structure and the smaller size vehicle required to meet desired seakeeping requirements when compared to a typical displacement hull may mitigate against higher cost arguments. The SWATH ship also tends to have a larger draft for a given ship size due to the necessity of submerging the hulls to gain the advantages of small waterplane area. The draft may be adjusted

while entering and leaving port by a variable ballast system if this is required and economically feasible.

The missions of ships are varied and the SWATH ship can be seen as providing a platform for several missions. As a stable ocean platform which could be fitted with a well (in the box) amidships and a suitable crane system, the SWATH seems well suited for oceanographic or underwater exploratory missions. The relatively deeply submerged hulls of the SWATH and the lack of wave making and bow emergences could make the SWATH a good platform for carrying sophisticated sonar equipment in an anti-submarine warfare mission. With the increasing sophistication of weapons systems, a stable platform can be useful for accurate location of targets. The SWATH might be called upon to carry radar or electronics equipment requiring a more stable platform. Certainly the large deck area of the SWATH box can be used as a helicopter landing platform and the SWATH could be used as a base for a helicopter detachment engaged in coastal surveillance and patrol or in patrolling or searching an off-shore area. The superstructure of such a ship could incorporate a hanger large enough to provide for intermediate level maintenance of the helicopters.

It is the possibility of using the SWATH ship as a mobile aircraft landing area which presents the most interesting application to the Coast Guard's changing missions and which is a primary motivation for developing the design model for SWATHs for Coast Guard applications.

CHAPTER II

WHERE CAN THE COAST GUARD USE A SWATH SHIP?^(9, 10)

Over the last twenty years the Coast Guard's missions have changed and its areas of responsibility have increased considerably. After the Second World War, sea duty meant weather patrols. Later Coast Guardsmen were sent to Vietnam to provide gunfire support and investigate and board hostile shipping. Now the enforcement of laws and treaties mission and the extension of our territorial waters along with the generally increasing offshore activity will require a Coast Guard presence further off our coasts for a larger part of the time.

Coast Guard air and sea forces have traditionally cooperated in carrying out Coast Guard missions in Search and Rescue, pollution control, fisheries patrol and icebreaking. Some of the newer cutters are equipped to handle helicopter landing and refueling in good weather but for the most part helicopters must return to a base ashore at the end of the mission or to obtain spare parts or do maintenance. The need for a truly helicopter capable ship will become more important as the area of responsibility increases and close coverage of changing areas along the coast becomes necessary. To provide this type of coverage with rotary wing aircraft of limited range, bases of their operation must be moved close to the operating area--helicopter bases must be moved to sea. These helicopter bases must be small enough and cheap enough to meet Coast Guard operational and budgetary constraints, yet provide a stable platform, adequate landing and maintenance area and quarters for an aircrew. The SWATH concept may provide an answer to this set of mission requirements.

The new mission of a Coast Guard patrol and enforcement vessel with helicopter capability might include provisions for speed sufficient to maintain position with a commercial fishing fleet, endurance for a three week operational patrol and a self sustained air group consisting of three or more helicopters. These requirements can be stated as a speed slightly in excess of 20 knots, a large helicopter landing deck, hanger, machine shops and parts storage areas for helicopter maintenance and repair, and an embarked crew for helicopter maintenance and repair, as well as the air crew.

Since there would be additional duties of such a ship either as a part of regular operations or as a vessel of opportunity, other equipment would also be desirable. Some type of weapons system would be fitted, perhaps including a medium calibre gun and associated fire control system. To be useful in a Search and Rescue mission, surface and air search radars would be required, and the ship should be able to tow a disabled vessel. If an anti-submarine warfare mission is envisioned, a sonar system should be fitted. Oceanographic equipment might also be fitted.

If a ship which incorporated all of the features listed above were constructed, it could be used for patrol and surveillance, law enforcement, search and rescue, oceanographic studies or anti-submarine warfare, and it could be efficient in all of these missions if it were a SWATH ship. A SWATH ship could move easily to the area of the patrol or search and deploy its helicopters for a coordinated search far from any land bases. If the location of the search was changed the SWATH could move to the new area while the search continued and land its helicopters at the new search datum point. Due to its improved seakeeping, the SWATH

ship could employ its helicopters in rougher weather than could a similar sized displacement ship, thus permitting search or surveillance in deteriorating weather. With its installed sonar, stable platform characteristics and deployed helicopters the SWATH ship could be very impressive as part of an anti-submarine task group.

Thus, a SWATH ship appears to have many desirable characteristics for Coast Guard applications. The preliminary design phase of a new class of Coast Guard cutters should include an investigation of an alternative or several alternatives to the conventional displacement hull; the SWATH should be among these alternative concepts. To provide an efficient means of evaluating SWATH designs and comparing them to conventional designs one should design a computer ship design model. The next chapter provides an introduction to this ship design tool.

CHAPTER III

INTRODUCTION TO THE COMPUTER DESIGN MODEL

As more applications of the high speed digital computer are found in the ship design process, the naval architect has found it useful to develop a series of computer aided ship design tools known as ship synthesis models. Given a set of design requirements and a ship synthesis model, the ship designer can generate a feasible starting design which can be used as a baseline for future design studies or he can make minor changes in the ship's requirements to see how the ship's characteristics are changed.

The computer design model is particularly useful in the conceptual and early preliminary design stages. The computer generated ships can be used to evaluate trade-offs early in the design process. Sets of principal characteristics of the feasible designs as functions of the input cases and estimates of various operating parameters can be used effectively in the evaluation of designs worthy of further design effort as well as furnishing the designer with the necessary baseline data for further design studies.

However, the outputs of the computer model are not optimum ships. Optimum design, even a very good design, requires many feasibility studies and trade-offs. These studies and trade-offs would require considerable time and the efforts of several designers if they were accomplished by hand and often a number of good alternatives will be overlooked because of the feelings of the design staff that the idea is not particularly good and the lack of time to investigate all alternatives. The computer is the only way to make many studies quickly and economically.

Since its output is directly related to the estimating parameters within the model, the computer ship synthesis model gives consistent and rapid answers. Proper documentation indicates how the estimating relationships were derived and the limits assumed for validity. Only a change to the program itself can change the relationship of the output to the input parameters. By providing for the program to accept several groups of data and calculate answers for these data, the designer can get quick answers to changes in requirements and to the "what if" question. This ability to respond rapidly to changes in requirements or input parameters and the fact that each decision within the computer program is made consistently means that a manager can readily evaluate the impact of a particular requirement on the ship design as a whole and make a rational decision on how to proceed--to fix the ship dimensions and requirements and proceed to more detailed design or to ask for more information from the computer model.

Both the United States Navy and the Coast Guard have ship synthesis models which they can use. During the 1960's and early 1970's the Navy developed several models including the DD07 model used as a basis for Goodwin's⁽¹¹⁾ Cutter Model which extended the Navy destroyer model down to 150 foot Coast Guard vessels and included Coast Guard standards. Many of the estimating relationships used in the model under development here for the Coast Guard SWATH have come from this source. The Coast Guard also is interested in developing design models for other types of special purpose ships. A Buoy Tender model is now being developed at Coast Guard Headquarters with some inputs from a similar student project at MIT. Although the entire ship system for an icebreaker is not included in a ship synthesis model, there are several aspects of icebreaker design

which have had computer applications such as resistance calculation and costs.

The object of this study is to develop a simple model for SWATH ships in Coast Guard applications. The usefulness of the SWATH concept in a Coast Guard application was discussed in the previous chapter. The Coast Guard's in-house design capabilities would be enhanced by adding the SWATH model to the Cutter Model. Because of the similarity of purpose it is desirable that the format of the SWATH model resemble that of the Cutter model and the options, input parameters and output information be similar. Chapters V and VI describe such a model.

CHAPTER IV

SWATH MODEL DEVELOPMENT

The basis for all computer ship synthesis models is the development of estimating relationships which can be written into the program. The relative accuracy among studies and the ability to compare various alternatives rapidly is more important than absolute accuracy of the result. For this reason estimating relationships are based on existing design data, the published literature and in the case of the SWATH, on summary data of U.S. Navy conceptual and preliminary design studies⁽⁸⁾.

In developing the estimating relationships used in this model, the author has been guided by: a) dependence of the estimating relationship on the most significant input variables; b) compliance with present Coast Guard design practices; c) reasonableness of the results; and d) shortcut estimates often resulting in linear relationships. As there is relatively little data on the SWATH configuration available, comparison of recent Coast Guard designs and the Navy SWATH designs to gain estimating relationships applicable to both has been attempted when design principles indicated this was a reasonable approach. Some relationships are merely developed from drawing a "mean" line through scattered data. Thus, the estimating relationships which are developed are rather crude and the model can only be expected to estimate at the ship systems level. Therefore, the outputs of the model will include such elements as total structural weight, total volume of machinery and required electrical generating capacity. Total arrangements area is computed in the program but no attempt to arrange the areas in the ship is made. Because the

SWATH tends to have a rather box-like arrangeable area there should be many alternatives for the engineer to consider in validating the computer output by hand. No attempt is made by the program to calculate trim either, because this calculation would be influenced considerably by arrangements.

The SWATH model will check a set of input variables to determine if they form a feasible solution to the ship design problem. The model checks for a balance between weight and displacement, for a balance between space required and space available, for a balance between energy required and energy available, for acceptable levels of longitudinal and transverse metacentric height and checks to insure dimensions within the range of reasonable SWATH design. The requirement for a weight displacement balance is important in this type of ship because of its low waterplane area and reduced ability to carry loads without large changes in draft. The volume balance may force the addition of a second level in the box structure--an enormous additional volume which has an impact on the weight. Metacentric height checks will form the basis for the strut shape and separation. These variables also affect resistance calculations.

The inputs required for the SWATH model are in general a description of the vehicle mobility performance parameters and a selection of various options to be used. The payload description must be sufficiently detailed so that the weight, relative vertical center of gravity, required deck area, electrical power requirements and cost are available for compilation by the model. The size of the crew must also be input to the model. Vehicle mobility performance can be described by the maximum calm water speed,



endurance speed and range. The options of the model include varying length, the type of machinery, the hull material, the margins and whether the horsepower is to be computed or if the maximum speed for a given horsepower is to be determined. A full description of the program inputs and available options for the SWATH model is contained in Chapter VI which describes the program and its development in more detail and in Appendix A which is a users guide for the program.

The output generated by the SWATH model must be suitable to demonstrate the feasibility of the design. Tabulated data and ratios are available for the engineer to use in validating the design without further calculation. The output lists the areas to be arranged and make it possible for a design team to lay out a rough arrangement and verify that there is sufficient space for all the requirements. The output also provides the engineer with some method of assessing the optimality of the solution based on some criterion. Often the only important optimality criterion is acquisition cost; for this reason the SWATH model includes a simple cost estimating routine for the first ship acquisition cost. The output of the model can be used as a baseline for carrying on the preliminary design phase. Either an optimal design can be chosen and the data used for the input to the preliminary design team or a series of designs can be run to produce a range of results from which optima can be gleaned by cross plotting.

However, it is important to emphasize that the SWATH model will produce a feasible solution only and that it is not an optimum solution. The manual design process allows the engineer to guide the selection of alternatives which appear to be attractive. An interactive computer design



process would allow the engineer to guide the computer in doing the lengthy calculations. The model does not allow this interaction but by entering several data sets which seem attractive, letting the computer do the solution and then letting the engineer evaluate the results and request more alternatives in a later computer run, the model can almost be used as the interactive tool, and the engineer will sense the optimum parameters.

It is also important to emphasize here that this model is limited in the cases which it can cover. Its basic limitations are listed in the table below:

TABLE I
SWATH MODEL LIMITATIONS

Ship Size	
Length	100-300 feet
Overall Beam	30-100 feet
Displacement	300-5000 tons
Performance	
Speed	6 - 33 knots
Structural Design	
Number of Decks in Box	1 or 2
Material	Steel or Aluminum/Aluminum Deckhouse
Number of Struts/Hull	1
Hydrodynamic Design	
Hull Type	Cylindrical/Ellipical Nose/Parabolic Tail

The remainder of this thesis is arranged as follows:

Chapter V gives an overview of the SWATH model and explains the options of the program.

Chapter VI goes into more detail on each of the subroutines of the program and explains the derivation of estimating relationships. This chapter is not necessary for the understanding and use of the program and may be skipped by a user who is not interested in the details of the program.

Chapter VII gives an evaluation of the program and a comparison of its output with existing Coast Guard design and Navy SWATH design for Coast Guard applications. Chapter VIII contains conclusions and recommendations.

Appendices A and C contain information on the input format with a guide for punching input data cards and a sample of the output format, respectively. Appendix B is a listing of the program.

Before using the program it is recommended that at least Chapters I through V, VII and VIII and Appendix A be read. Chapter VI will be valuable to those who wish to study the evolution of the program or to change it.

CHAPTER V

GENERAL DESCRIPTION OF THE PROGRAM

This chapter is intended to give the reader and potential user of the SWATH model an overall description of the computer program and the method of executing the feasibility solution but it does not discuss the details of the development or use of the subroutines or estimation methods used in calculations. The reader is referred to Chapter VI for more detail on the subroutines. This chapter, however, gives an indication of how the subroutines are used in the total program.

An attempt has been made in the development of this SWATH model to use the same program organization and input data set information as was used by Goodwin⁽¹¹⁾ in the development of the cutter model. Program execution is controlled by Subroutine XECUTE unless data for a new case is to be read into the program. Subroutine XECUTE calls the subroutines as needed and the appropriate calculations are made to return data for storage until the feasibility study is completed and the data is ready for output. This subroutine also controls the checking of some data, notably horsepower requirements, against the range of validity of the model, printing out error messages and providing the iteration loops for weight and center of gravity. The control of program execution is shown schematically in Figure 1.

A logical organization of the program is shown in Figure 2. Note that Subroutine XECUTE is omitted from this figure as it merely guides the execution of the various subroutines as the program moves around the logic-loop. The inputs, types of calculations accomplished and the outputs from each of the program segments will now be described in general terms.

FIGURE 1: PROGRAM CONTROL ORGANIZATION

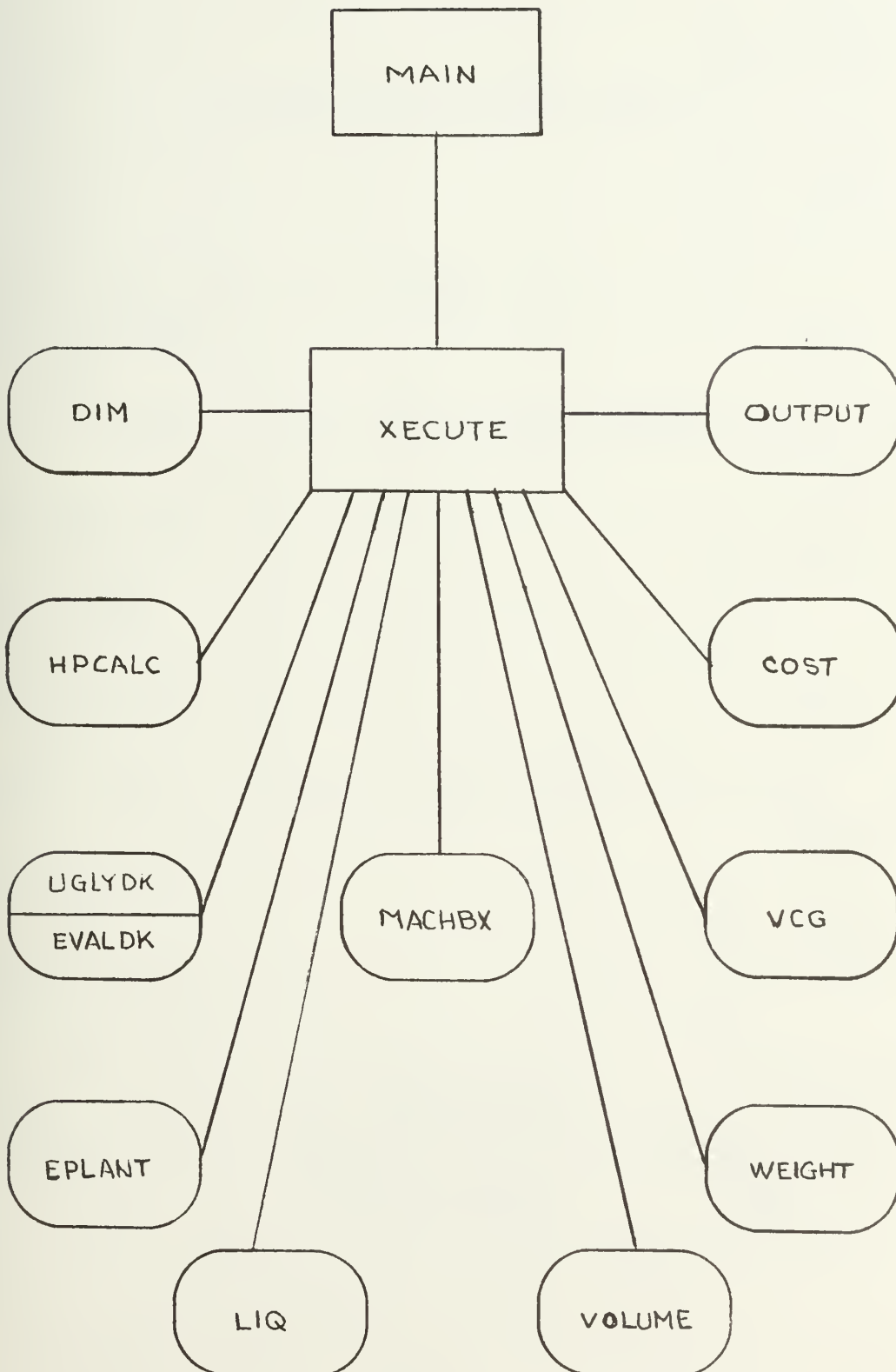
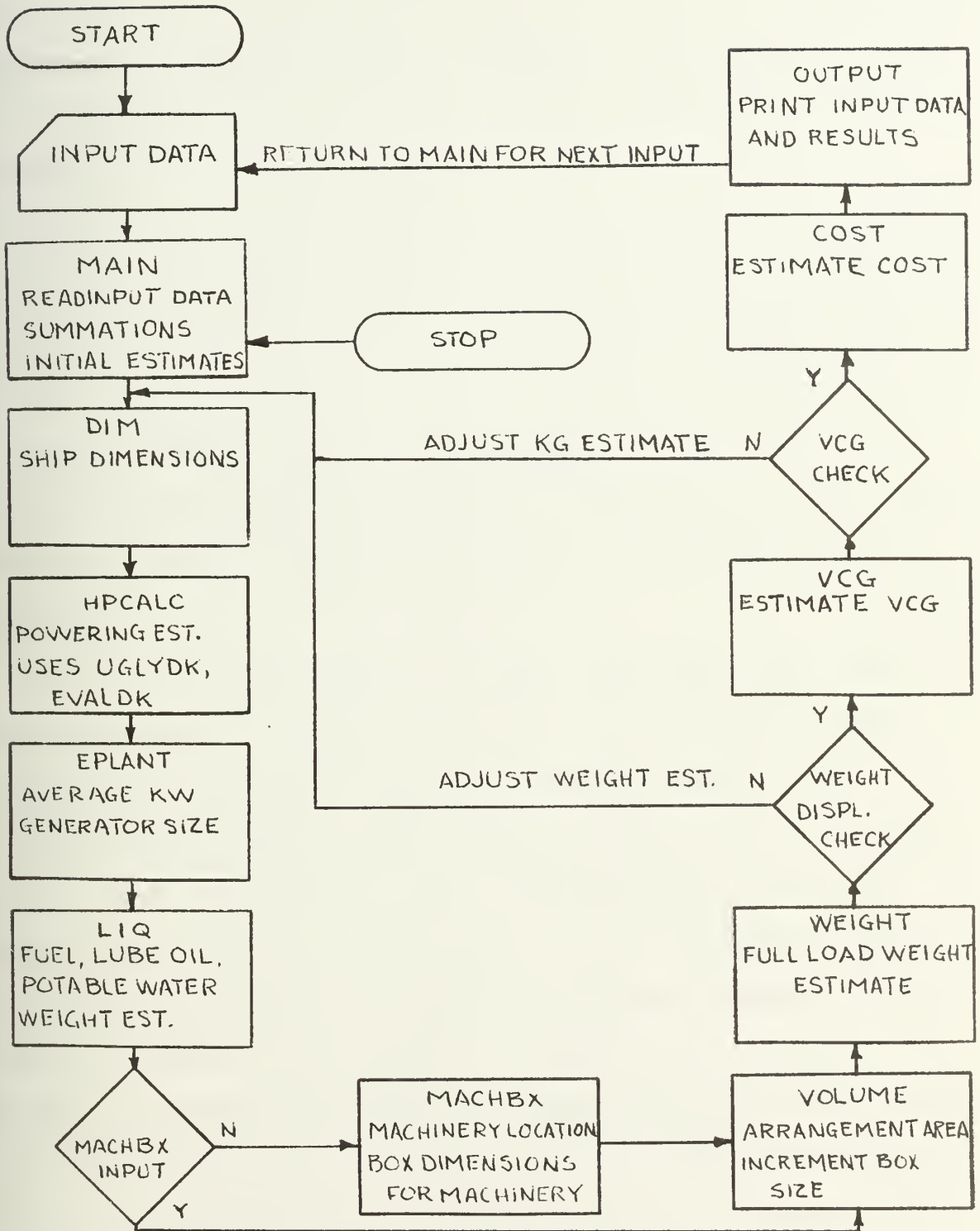


FIGURE 2: PROGRAM LOGICAL ORGANIZATION



The program begins with the reading of data in the MAIN program. The primary purpose of MAIN is to read in the input data set, but MAIN also is used for summing payload item weights, area requirements and costs. The initial estimates of displacement, vertical center of gravity location and cubic number are made by MAIN.

Once the input data set has been read and stored and initial estimates have been made in MAIN, Subroutine XECUTE is called. XECUTE then controls the execution of the program until a feasible solution is output or until a program constraint is violated. In either of these cases control will then be returned to MAIN for the reading of another data set if one exists or the termination of the program if there is no more data. XECUTE controls the program stepping through the other routines shown in Figure 2.

The first subroutine called by XECUTE is Subroutine DIM, which provides the basic dimensions of the entire ship. Its inputs are the desired length of the ship and its approximate displacement. The subroutine sizes the hulls and struts, checks to make sure that submerged volume equals displacement, checks longitudinal metacentric height against SWATH practice, checks transverse metacentric height against SWATH practice, adjusts the dimensions to insure acceptable values of metacentric heights, positions the struts on the hulls and generates an initial size for the box structure connecting the hull-strut combinations. This dimensional information is stored for use in other subroutines.

Two options are available for the next calculation, speed and power prediction. For both options the program first computes points on a speed-power curve which are stored for future recall. The program

then uses a spline cubic curve fitting subroutine, UGLYDK, to pass a curve through the points of the speed-power curve. For the first option, if the maximum speed for the ship has been specified and the horsepower required to meet this speed is desired. Another subroutine, EVALDK, is called which evaluates the horsepower curve at the given speed. EVALDK is called again to provide the value of horsepower at endurance speed. These two values, maximum horsepower and endurance horsepower are then returned to storage. If, on the other hand, the speed made good for an input horsepower value is desired, the program will compute this speed using an initial estimate and an iterative procedure. The control of this iteration is in Subroutine XECUTE. In this option the endurance speed is an input so the required horsepower is evaluated in the same manner as for the first case.

The generation of the horsepower curve is based on a potential flow and empirical method developed by Chapman⁽¹²⁾ and simplified and modified for use in this model. The evaluation of the horsepower curve is done using the spline cubic curve fitting routines of Kerwin⁽¹³⁾.

The next subroutine, EPLANT, calculates the size of the electrical plant to be installed. The required inputs are the size of the crew, the estimate of cubic number and the input values of electric loads. The average electric load is calculated and the required generator size is determined. These values are stored; the average load will be used for determining the fuel requirements of the generators and the generator size will be output.

Then the weights of fuel oil, lubricating oil and potable water are calculated in Subroutine LIQ. The endurance horsepower required

calculated by HPCALC, the number of crew, and the endurance range are inputs. If the specifications of the machinery plant are inputs, the calculations for fuel weight will be based on those inputs. If only the machinery type is input, lubricating oil requirements and fuel oil requirements will be estimated based on the machinery type and the horsepower range.

If the machinery plant is specified, the location and size of the main machinery spaces will be given and the program will skip to the VOLUME Subroutine. If the maximum speed is an input, however, the program will call Subroutine MACHBX and the location and dimensions of machinery spaces will be estimated. The inputs to this subroutine are the dimensions of the ship, the machinery type and the horsepower. Based on the size of main machinery components and the horsepower, the prime movers and propelling units are placed in the hulls or in the box and the dimensions of the spaces are estimated.

The next subroutine called calculates the volume which is required and adjusts the ship dimensions to provide sufficient volume to meet the requirements. Because the SWATH volume is primarily in the hulls and the box, both of which are simple geometric shapes, the volume calculation for this type of ship is not as complex as that for a conventional displacement ship. Machinery and tankage are assumed to occupy the hulls. The struts are not desirable as arrangement area because they are long and narrow, so it is assumed that one platform deck is available in the struts and that the remainder of the strut volume is uptakes, access, overflow tanks or non-arrangeable voids. The box and deckhouse are useable for arrangement volume without restriction. The

inputs to the subroutine are the ship dimensions, crew and the weights calculated previously. First the liquids are accounted for in tankage volume. The machinery space volume in the hulls is then determined. Steering gear and control fin machinery spaces are provided in the hulls. The total hull volume available is checked against that required and additional volume is provided in the struts for overflow tanks if the hulls are too small. If the overflow tanks are also too small the program returns an error. Then the deckhouse volume, box volume and strut volume are calculated. The volumes are converted into arrangement areas by dividing by an average deck height. No sheer is assumed in these calculations. The deckhouse is checked to make sure it meets the requirements. The remaining machinery space volume is placed in the box as an arrangement area requirement. All other arrangement area requirements are determined and summed. The required arrangement areas are calculated based on empirical data from other designs and on input area requirements. By varying the size of the deckhouse or by adding another deck to the box structure, the available area can be made larger than the required area. In the SWATH configuration excess area is quite likely because the additional deck in the box should extend from end to end to gain structural strength. Partial raised decks are not considered in this model. If too large a deckhouse or more than two decks in the box are required an error message is generated and the program cycles for new input data.

Once the volume of the ship has been calculated, the weights of light ship weight groups and the load items can be determined. Because of the lack of data on SWATH ships only one digit weight estimates are made in

this model and they are printed out in the output. The most important variable at this time is the full load displacement which must be compared with the initial estimate. If the difference is more than 9 tons, a new estimate of displacement is made and the program returns to the DIM subroutine to estimate new ship dimensions. Once the weight and displacement check, the program continues to estimate the vertical center of gravity.

Subroutine VCG makes this estimate. Centers are taken as fractions of the total depth of the ship to the main deck. The estimated KG is compared with the original estimate and a new estimate is made until there is agreement within one foot. KG location and metacentric height have both been checked by this point in the calculations so the test point on KG is set rather high to avoid overconstraining the problem.

After the vertical center of gravity balance has been made, the lead ship cost is estimated using a cost estimating procedure developed from "Flanagan's Method"⁽¹¹⁾ with modifications for the additional cost factor for aluminum construction and the additional machinery types of the model. This is accomplished by Subroutine COST which returns a cost breakdown by weight groups and additional costs for miscellaneous items as well as the total cost.

Finally, Subroutine OUTPUT is called. This routine takes all the values which have been calculated in the program as input and prints out the input data and the output of the feasibility study. After the output record is produced the program returns to MAIN and searches for more input data sets, reads the data and starts execution of the new case. This concludes a general description of the operation of the program.

The next chapter will present a more detailed description of the program and can be skipped without loss of too much continuity by a user not interested in how the program works. Because the SWATH is an unusual configuration, however, the naval engineer may find the background and derivation of the estimating relationships interesting.

CHAPTER VI

DESCRIPTION OF THE PROGRAM

6.1 Introduction

This chapter consists of thirteen parts, this introductory section and twelve sections describing in detail the derivation and use of various estimating relationships in the program. In this introductory section, the data base will be discussed and the organization of each of the following sections will be outlined.

The data from which this model was developed is from two major sources (8) and (11) which give the results of considerable ship synthesis using a Navy SWATH model and the Coast Guard Cutter Model, respectively. The Navy SWATH data was used for formulating estimating relationships peculiar to the SWATH and the Cutter Model was used for validation of other data against present Coast Guard practices and incorporation into the model where there was either good correlation or a good reason to accept Coast Guard estimates over Navy relationships, for instance in the deck area requirements for living spaces. There are also several other sources of SWATH data which were consulted in creating the data base for this model (3, 5, 14, 15, 16, 17, 18, 19, 20, 21). Table II gives a tabulation of the principal dimensions, operational specifications, optional features, weight estimates and several ratios used in developing the relationships of this model. The primary reference source for each ships' data is also listed in the table. These data were used for developing SWATH relationships. Throughout the remainder of this chapter graphs will be displayed which have been

plotted to reduce these data into simple, often linear curves. Other graphs in this chapter are taken from Goodwin⁽¹¹⁾ and show current Coast Guard designs and SWATH designs superimposed to test the applicability of these relationships to the SWATH design. If the data appear to fit well, Goodwin's relationships are used; if the data trends are the same but displaced, Goodwin's curves are modified to fit the data better.

The general organization of the sections on the individual subroutines will be similar. The subroutines will be described in the order in which they are called in the program. First the general purpose and approach for each subroutine will be defined. Then the required inputs will be listed. The majority of each section is devoted to the development of estimating relationships. The sources of the data, appropriate curves and the rationale of the development will be discussed. The important tests which the program must make to direct it in the proper execution of the solution will also be noted. However, each computer statement will not be described in order. It is assumed here that the reader has a basic knowledge of the FORTRAN computer language and can fill in the steps which are not described. The complete program listing is available in Appendix B for reference while reading these sections. A computer flow diagram of each subroutine is included along with the description of the program's relationships. Finally, the subroutine description will include an output list and a nomenclature list. The nomenclature list applies only to the subroutine under discussion in that section as similar variable names may be assigned to different variables in other parts of the program.

TABLE II
DATA BASE FOR SWATH MODEL DEVELOPMENT

SHIP FACTOR	1	2	3	4	5	6	7	8	9
Length	282	300	300	308	308	300	308	308	300
Displacement	5250	5560	5580	5720	5640	5580	5720	5640	4650
Hull Diameter	18.5	19.1	19.1	19.0	19.0	19.1	13.0	19.0	17.4
Draft	32.3	33.5	33.5	33.2	33.3	33.5	33.2	33.2	30.4
Speed									
Endurance									
Number Struts	1	1	1	2	2	1	2	2	1
Strut Length	180	180	200	80/90	80/90	200	80/90	80/90	180
Strut Beam	8.7	8.7	9.8	9.8	9.8	8.7	9.8	9.8	8.7
CWP	.941	.941	.909	.860	.860	.909	.860	.860	.941
Box Length	214	214	214	252	234	214	252	234	214
Box Beam	90	96	96	96	96	96	96	96	96
Box Depth	23	23	23	14	23	23	14	23	23
Hull Separation									
Air Gap	15	15	15	15	15	15	15	15	15
Horsepower									
Machinery									
Material	GT Steel 2	GT Steel 2	GT Steel 2	GT Steel 1	GT Steel 2	GT Alum 2	GT Alum 1	GT Alum 2	GT Alum 2
Decks	3.4	5.7	9.3	3.2	6.4	10.3	4.2	7.4	9.5
GMT	16.2	13.2	24.2	83.9	73.5	75.2	84.9	74.5	13.8
Group 1 Weight	1918	1922	1942	2092	2022	1343	1312	1364	1310
Group 2 Weight	393	393	393	366	366	393	366	366	393
Group 3 Weight	176	176	176	176	176	176	176	176	176
Group 4 Weight	191	191	191	191	191	191	191	191	191
Group 5 Weight	420	420	420	420	420	420	420	420	420
Group 6 Weight	294	294	294	294	294	294	294	294	294
Group 7 Weight	76	76	76	76	76	76	76	76	76

DATA BASE FOR SWATH MODEL DEVELOPMENT

SHIP FACTOR									
	1	2	3	4	5	6	7	8	9
Hull Volume	679464	731073	737427	597015	775286	737427	597015	775286	697709
Density Structure	7.27	6.77	6.78	9.03	6.72	4.69	5.66	4.53	4.84
WT1/Displ.	.42	.40	.40	.42	.41	.28	.26	.27	.32
Length/Diam.	15.2	15.7	15.7	16.2	16.2	15.7	16.2	16.2	17.2
Strut Length/Length	.64	.60	.67	.57	.57	.67	.57	.57	.60
Strut Beam/Diam.	.47	.44	.46	.52	.52	.46	.52	.52	.50
Draft/Diam	1.75	1.75	1.75	1.75	1.75	1.75	1.75	1.75	1.75
Ship Type	Med. ESC.	Med. ESC.	Med. ESC.	Med. ESC.	Med. ESC.	Med. ESC.	Med. ESC.	Med. ESC.	Med. ESC.
Reference	8	8	8	8	8	8	8	8	8

NOTES:

1) Dimensions in feet. Weights in tons.

Speed in knots. Endurance in
nautical miles.

2) CWP = waterplane coefficient of strut

GMT = transverse metacentric height

GML = longitudinal metacentric height

3) Machinery Types: GT = gas turbine

GT-E = gas turbine-electric

D-E = diesel-electric

4) Material Types: Steel = steel

Alum = aluminum

5) Ship Types:

Med. ESC. = Medium Escort (5000 tons)

SM, ESC. = Small Escort (2000 tons)

5) Ship Types (Continued)

PMR = Patrol Vessel

SSP = Semi Submerged Platform

(190 tons)

AGOR = 240 foot AGOR SWATH

CUTTER = 240 foot USCG Cutter

SSV72 = SWATH design

SSV72 = 1972 SWATH Supply Vessel
design

SSV75 = 1975 SWATH Supply Vessel

= design

SSSV75 = 1975 Semi Submerged

Supply Vessel design

MCM = SWATH Mine Counter -
measures Ship

TABLE II (Continued)

DATA BASE FOR SWATH MODEL DEVELOPMENT

SHIP FACTOR																		
	10	11	12	13	14	15	16	17	18	19								
Length	305	303	350	194	216	295	238	238	238	238								
Displacement	4610	5630	5680	2060	2040	2250	2090	2110	2135	2370								
Hull Diameter	17.4	19.1	17.8	13.9	14.0	12.0	13.0	13.2	13.2	13.8								
Draft	30.4	33.6	31.2	23.9	24.4	21.0	22.7	23.1	22.7	24.0								
Speed																		
Endurance	2	1	1	1	2	2	1	1	1	1								
Number Struts	80/90	200	250	156	52/52	67/67	182	182	182	182								
Strut Length																		
Strut Beam	8.7	8.7	6.0	6.5	6.5	5.0	5.0	5.0	5.0	6.0								
CWP	.876	.909	.903	.869	.788	.909	.811	.811	.811	.842								
Box Length	252	214	214	136	136	272	162	162	162	162								
Box Beam	96	96	96	94	94	94	80	80	80	80								
Box Depth	14	23	23	23	23	14	23	23	23	23								
Hull Separation																		
Air Gap	15	15	15	15	15	15	15	15	15	15								
Horsepower																		
Machinery																		
Material	GT Alum	GT Steel	GT Steel	GT Alum	GT Alum	GT Alum	GT Alum	GT Alum	GT Alum	GT Alum								
Decks	1	2	2	2	2	1	2	2	2	2								
GMT	3.4	9.2	5.7	23.8	3.3	2.4	4.0	4.0	4.0	4.5								
GML	24.1	24.1	48.2	17.0	18.1	110.6	20.7	20.7	20.7	23.1								
Group 1 Weight	1302	1953	2027	631	613	796	657	657	663	692								
Group 2 Weight	366	393	360	267	267	267	267	267	267	267								
Group 3 Weight	176	176	176	125	125	125	125	125	125	125								
Group 4 Weight	191	191	191	87	87	87	87	90	90	87								
Group 5 Weight	420	420	420	147	147	147	147	147	147	259								
Group 6 Weight	294	294	294	76	76	76	76	76	76	172								
Group 7 Weight	76	76	76	26	26	26	26	34	34	26								

TABLE II (Continued)

DATA BASE FOR SWATH MODEL DEVELOPMENT

SHIP FACTOR										
	10	11	12	13	14	15	16	17	18	19
Hull Volume	556292	739462	723640	396968	387593	453912	397719	399973	399382	416720
Density Structure	6.03	6.80	7.22	4.09	4.07	4.52	4.26	4.23	4.28	4.28
WT1/Displ.	.32	.40	.41	.35	.35	.41	.36	.36	.36	.34
Length/Diam.	17.5	15.9	19.7	14.0	15.4	24.6	18.3	18.3	18.3	17.25
Strut Length/ Length	.56	.66	.71	.80	.48	.45	.77	.77	.77	.77
Strut Beam/ Diam.	.50	.46	.34	.47	.46	.42	.39	.38	.38	.44
Draft/Diam.	1.75	1.76	1.75	1.72	1.74	1.75	1.75	1.75	1.72	1.74
Ship Type	MED. ESC.	MED. ESC.	MED. ESC.	SM. ESC.	SM. ESC.	SM. ESC.	SM. ESC.	SM. ESC.	SM. ESC.	SM. ESC.
Reference	8	8	8	8	8	8	8	8	8	8

TABLE II (Continued)

DATA BASE FOR SWATH MODEL DEVELOPMENT

SHIP FACTOR	SHIP									
	20	21	22	23	24	25	26	27	28	29
Length	248	155	200	81.25	240	240	200	196	196.9	260
Displacement	2045	786	1286	190	3032	3059	2850	3150	2400	3441
Hull Diameter	15.0	9.5	11.1	6.5	15	15.82	16X21	16X22		15.83
Draft	26.3	16.7	19.4	15.25	26.25	27.7	35	35	20.7	27.7
Speed		15	20	25	13	18.6	14	12	14	25
Endurance		2000+	2000+				9000	9000	5400	
Number Struts	1	1	1	2	1	1	2	2	1	1
Strut Length	189	112	131	23/24	200	184	40/40	40/40		
Strut Beam	6.8	5.5	5.5	3.8/3.6	7.5	7.5	10	10		
CWP	.856	.86								
Box Length	162	95	110	76.8	171	184	140	140		
Box Beam	80	54	59.2	45	82	85	105	105	68	
Box Depth	23	13	13	7.5	13	23	10	10		
Hull Separation										
Air Gap	15	12	12	6	20	15	46	46		
Horsepower		2800	10000	4200	4850	12880	6000	6000	7040	40000
Machinery		D-E	GT-E	GT	DIESEL	D-E	DIESEL	DIESEL	DIESEL	GT
Material	Steel	Steel	Steel	Steel	Steel	Steel	Steel	Steel	Steel	Steel
Decks	2	1	1	1	1	2	1	1	1	1
GM _T	4.2				11.56	4.01				
GM _L	26.7				46.35	20.2				
Group 1 Weight	1193	354	538	99	1130	1319				1188
Group 2 Weight	267	100	280	13	213	380				300
Group 3 Weight	125	11	11	3	74	105				53
Group 4 Weight	87	3	4	1	19	90				37
Group 5 Weight	259	80	100	30	417	283				380
Group 6 Weight	172	27	50	1	234	201				230
Group 7 Weight	26	0	0	0	1	17				5

TABLE II (Concluded)
DATA BASE FOR SWATH MODEL DEVELOPMENT

SHIP FACTOR	20	21	22	23	24	25	26	27	28	29
Hull Volume	443597	104690	144650	35724	347734	486256				
Density Structure	6.93	8.71	9.59	6.21	8.37	6.99				
WT1/Displ.	.47	.52	.48	.52	.43	.55				.40
Length/Diam.	16.53	16.3	18.0	10.8	16	15.17	12.5/9.5	12.25/8.9		16.43
Strut Length/ Length	.76	.72	.66	.58	.83	.77	.4	.4		
Strut Beam/ Diam.	.45	.53	.50	.57	.50	.47	.48	.46		
Draft/Diam.	1.75	1.76	1.75	2.35	1.75	1.75	2.19	2.19		1.75
Ship Type	SM. ESC.	PMR	PMR	SSP	AGOR	CUTTER	SSV72	SSV75	SSSV75	MCM
Reference	8	14	14	14	14	10	16	21	21	3

The program accumulates, stores and transfers values of variables by using labeled common statements. This is done because a great number of variables are required to define a solution case and because it saves on computer storage space. Thus, in the input and output lists for each subroutine a code indicating the transfer and storage of a variable in labeled common is given in the form LC(AA) to indicate storage in labeled common AA and the code SCDA is used to indicate a subroutine call dummy argument.

6.2 MAIN Program

6.2.1 Purpose and Approach

The MAIN program performs the functions of reading all the input data, summation and bookkeeping for payload items which have been input, making initial estimates of the displacement, vertical center of gravity location and cubic number as functions of the input values and calling the XECUTE subroutine which controls the execution of each design case. The XECUTE subroutine is described in the next section. After XECUTE has completed the analysis of a design case control is returned to MAIN. MAIN then checks for more input data and reads the data for another run or, on finding no more data, directs the computer to stop.

6.2.2 Inputs Required

In this program there are only two variables which are assigned values at the beginning of the MAIN program; all other variables are either read into the program from the data cards or are assigned values in the routines. The two exceptions to the rule noted above are the variables IREAD and IWRITE which are merely dummy variables for the device numbers of the card reader and the printer. Dummy variables

were used here to simplify conversion of this program for use on different computers. The values assigned in the program as listed in the Appendix are for use on the IBM 370 computer with FORTRAN IV G1 or WATFIV compilers. The inputs read from cards will be described in the next paragraph.

6.2.3 Program Development

The format of the input data deck is listed in the User's Guide, Appendix A. The first input card of the input deck is used as a control to signal the computer that there is more data to follow or that there is no more data and the run should terminate. An INDEX value of 0 causes termination. The second input which is read is a heading which may contain any descriptive information about the computer run. This heading will be printed for all outputs using the data set which follows. The next input is a counter which determines the number of Armament, Ammunition and Cargo descriptive cards which follow. A maximum of 20 of this type of input data cards is specified. The group of cards which follows this counter is the armament, ammunition and cargo payload data. It may be arranged in any way and items may be grouped on one card or separated. However, for each card with a weight entry, a vertical center of gravity entry must follow as the next entry on the same card; these entries should be expressed as a ratio of the depth to the main deck. Required areas in the hull and deckhouse for these payload items may be entered; if an area is not specifically required in the deckhouse, it should be entered as a hull area. The materials cost for the payload items should also be entered in thousands of dollars at the time of construction of the ship. The next input is another counter which is used to

count the number of electronics input cards which follow. Again the maximum value of electronics cards is 20. The electronics input card is similar to the armament card in that it contains descriptive data, weight, center of gravity, required area and cost data. Manning input data are read next. This program requires manning data as an input. Then cost indices for use in the COST subroutine are input. These consist of the estimated labor rate during ship construction and inflation indices for computing material costs. The ninth input required is a description of the mission including the endurance days for provisions, the weight and the center of gravity position of the aircraft fuel. Then an input indicating whether the program is to compute the maximum speed for an input value of horsepower (JOPT=2) or the horsepower required to attain a specified speed (JOPT=1) is given. If JOPT=1 is specified the next data card read includes the sustained speed, endurance speed, endurance range and propulsive coefficient data. For JOPT=2, the next card includes the installed horsepower, specific fuel consumption values, endurance speed and range, propulsion auxiliaries electrical load, weight of lubricating oil, dimensions of the machinery spaces required, and the acquisition cost. The twelfth type of data card allows various options to be selected. Four machinery types are provided as options: MTYPE=1 is diesel, MTYPE=2 is diesel-electric, MTYPE=3 is gas turbine and MTYPE=4 is gas turbine-electric. A value of MTYPE=0 will cause the computer to assume that the next input value is INDEX; this feature can be used to stop the program. The results of a MTYPE specification other than 0-4 are unpredictable. The second option is for hull material; MOPT=1 is a steel hull with aluminum deckhouse, MOPT=2

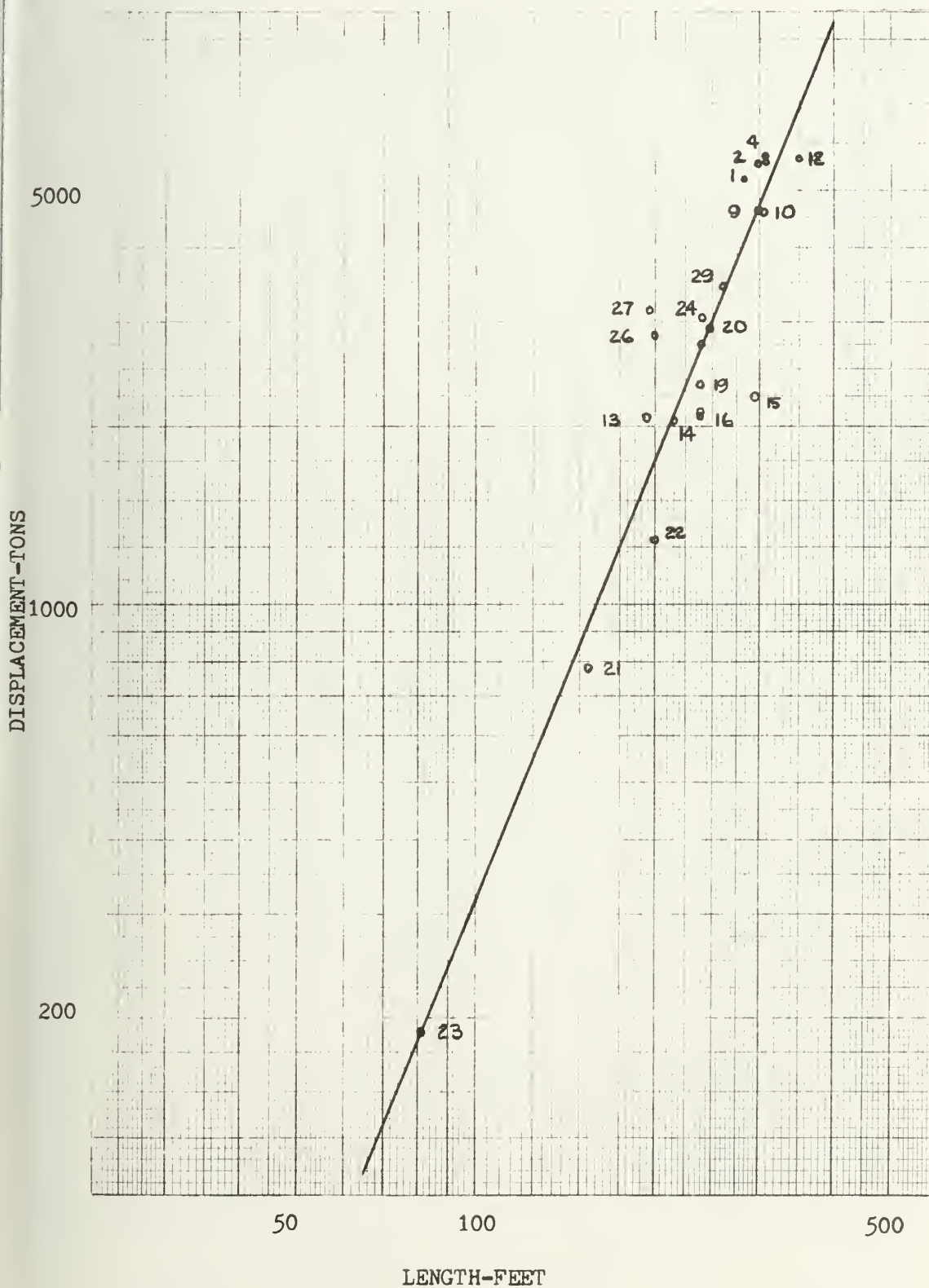
is for an all aluminum ship. The third option is a free surface correction term which can be used to influence the value of KG. The primary variable which can be varied in this option card is the ship length. The last option is for design and builders margin. Several option cards may be stacked together in an input deck; the program will interpret each as a new input case with the same payload description. A card with a MTYPE=0 entry is required to get to an entirely new data set. That completes the reading in of data.

MAIN also makes three starting estimates: displacement, vertical center of gravity and cubic number. Two approaches were applied to determining the estimating relationship for displacement. First, a mean design SWATH was hypothesized and its displacement calculated over a range of size. This equation was $DPTRY = .00015707 * LEN * LEN * LEN$. Comparison with the SWATH data shown in Table II indicated that this equation estimated well in the midrange but was not very good on the ends. The second approach, a logarithmic plot and a mean line through all available SWATH data produced the second relationship, $DPTRY = .004606265 * LEN^{2.427}$, which was used. See Figure 3. From limited vertical center of gravity data it appeared that KG/D did not vary widely and that it increased with length. Thus a mean line was drawn through the available data and the equation below was determined. See Figure 4.

$$KGTRY = LEN / (.0036786 * LEN + 5.5368)$$

During the study of the hypothetical mean SWATH mentioned above, a relationship was derived for total enclosed volume of the hull as a function of length and number of decks in the box. Since the first use of the cubic

FIGURE 3: TRIAL DISPLACEMENT VERSUS LENGTH



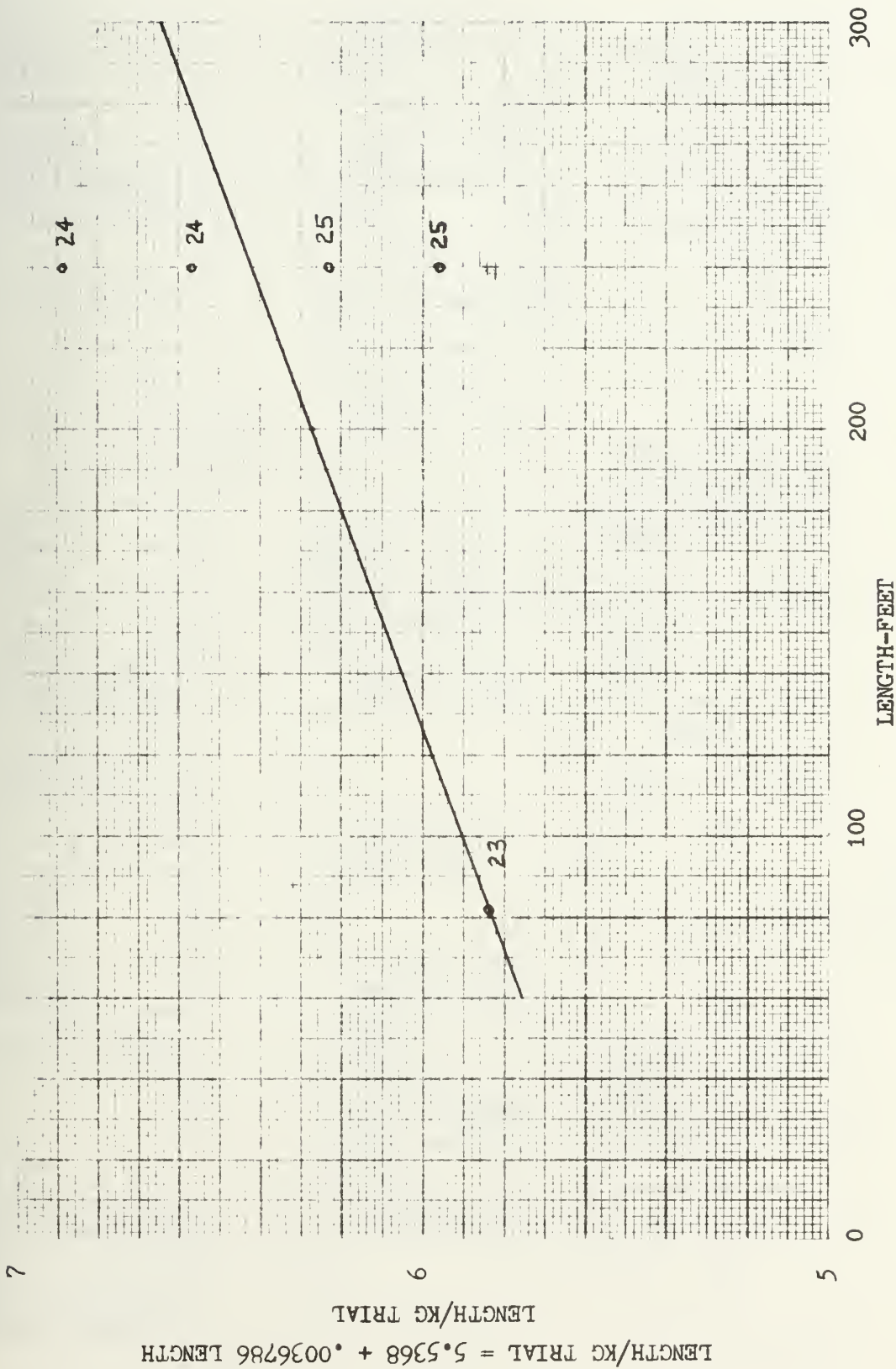
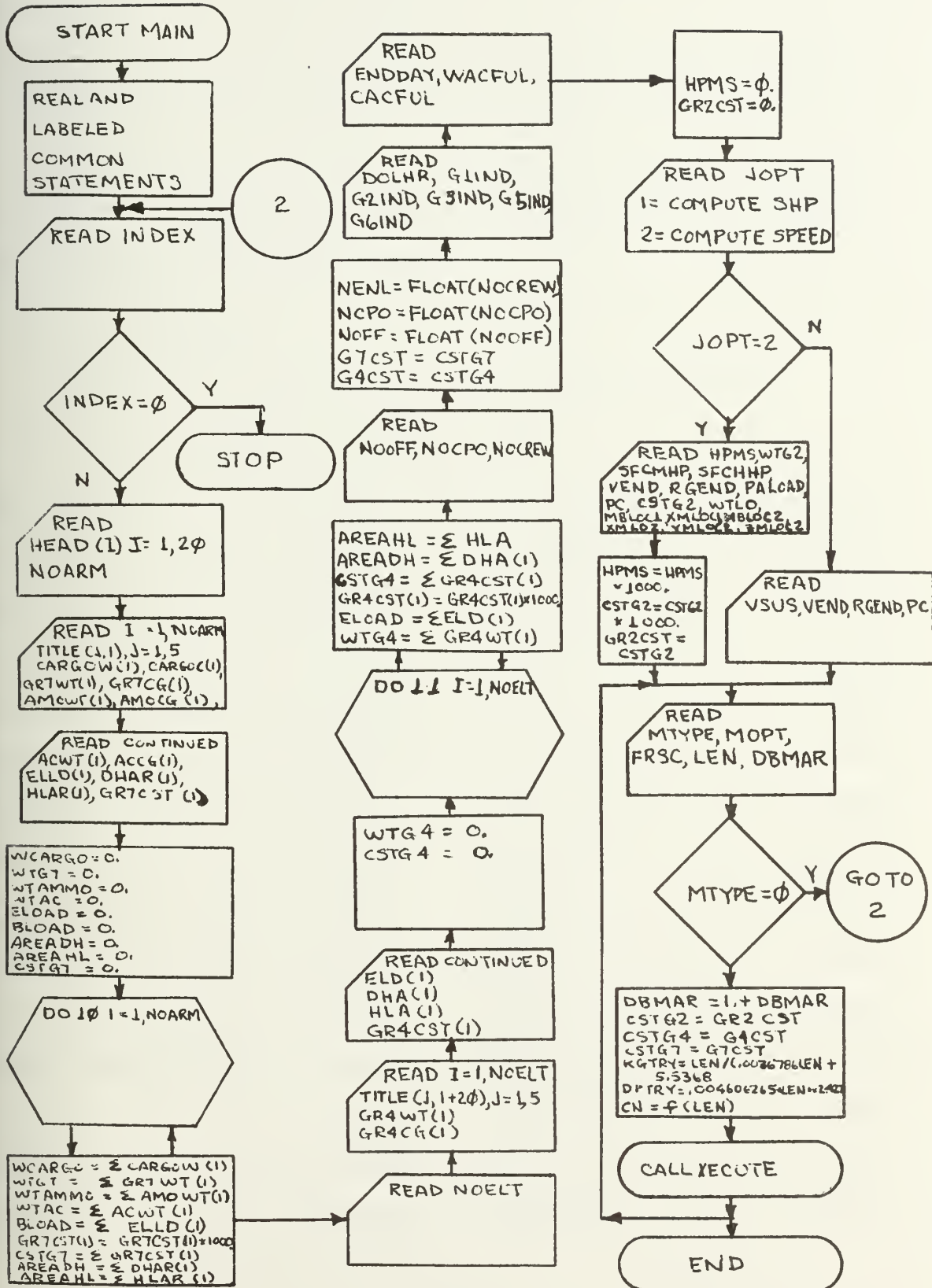


FIGURE 4: LENGTH/KG TRIAL VERSUS LENGTH

FIGURE 5: MAIN SUBROUTINE FLOW CHART



number is in electric plant sizing, it was felt that this relationship was sufficiently accurate and was used.

$$CN=165.048*LEN+6.196155*LEN*LEN+.005973*LEN*LEN*LEN$$

After making these estimates control of the program is passed to XECUTE. Only after a case has been calculated is control passed back to MAIN for more data reading.

6.2.4 Flow Chart

A flow chart for the MAIN program is shown in Figure 5.

6.2.5 List of Outputs of MAIN Program

ACCG (20)	LC(EE)	DHA(20)	LC(KK)
ACWT(20)	LC(EE)	DHAR(20)	LC(KK)
AMOCG(20)	LC(EE)	DOLHR	LC(NN)
AMOWT(20)	LC(EE)	DPTRY	LC(GG)
AREADH	LC(BB)	ELD(20)	LC(KK)
AREAHL	LC(BB)	ELLD(20)	LC(KK)
BLOAD	LC(DD)	ELOAD	LC(DD)
CACFUL	LC(HH)	ENDDAY	LC(AA)
CARGOC(20)	LC(EE)	FRSC	LC(GG)
CARGOW(20)	LC(EE)	G1IND	LC(NN)
CN	LC(BB)	G2IND	LC(NN)
CSTG2 (JOPT=2 only) . .	LC(MM)	G3IND	LC(NN)
CSTG4	LC(MM)	G5IND	LC(NN)
CSTG7	LC(MM)	G6IND	LC(NN)
DBMAR	LC(WW)	GR4CG(20)	LC(EE)



List of Outputs of MAIN Program (Continued)

GR4CST(20) LC(KK)	NOFF LC(AA)
GR4WT(20) LC(EF)	PALOAD (JOPT=2 only). LC(DD)
GR7CG(20) LC(EF)	PC LC(CC)
GR7CST(20) LC(KK)	RGEND LC(CC)
GR7WT(20) LC(EF)	SFCHHP (JOPT=2 only). LC(CC)
HEAD(20) LC(FF)	SFCMHP (JOPT=2 only). LC(CC)
HLA(20) LC(KK)	TITLE (5,40) LC(FF)
HLAR(20) LC(KK)	VEND LC(CC)
HPMS SCDA	VSUS (JOPT=1 only) . . . LC(CC)
JOPT LC(CC)	WACFUL LC(LL)
KGTRY LC(GG)	WCARGO LC(LL)
LEN LC(BB)	WTAC LC(LL)
MOPT LC(CC)	WTAMMO LC(LL)
MTYPE LC(CC)	WTG2 (JOPT=2 only) . . LC(WW)
NCPO LC(AA)	WTG4 LC(WW)
NENL LC(AA)	WTG7 LC(WW)
NOARM LC(FF)	WTLO (JOPT=2 only) . . LC(LL)
NOELT LC(FF)	

6.2.6 Nomenclature List

ACCG(20)	aircraft vcg/DT, DT = depth to top of box
ACWT(20)	aircraft weight, tons
AG	air gap clearance under box, feet
AKNOT(12)	speed curve values
AMOCG(20)	ammunition vcg/DT

Nomenclature List (Continued)

AMOWT(20)	ammunition weight, tons
AREADH	total input deckhouse arrangements area, sq ft
AREAHL	total input hull arrangements area, sq ft
AVGKW	average electrical load, KW
BBOX	beam of box, feet
BS	beam of strut, feet
BLOAD	total armament electrical load, KW
CACFUL	aircraft fuel vcg/DT
CARGOC(20)	cargo vcg/DT
CARGOW(20)	cargo weight, tons
CCARGO	total vcg of cargo inputs, feet
CCST	construction services cost, dollars
CGAC	total vcg of aircraft, feet
CGAMMO	total vcg of ammunition, feet
CGCREW	total vcg of crew, feet
CGFUEL	total vcg of ships fuel, feet
CGLO	total vcg of lub oil, feet
CGPE	total vcg of personnel effects, feet
CGPS	total vcg of personnel stores, feet
CN	cubic number, cubic feet
CSTG1	total cost of weight group 1, dollars
CSTG2	total cost of weight group 2, dollars
CSTG3	total cost of weight group 3, dollars
CSTG4	total cost of weight group 4, dollars
CSTG5	total cost of weight group 5, dollars
CSTG6	total cost of weight group 6, dollars

Nomenclature List (Continued)

CSTG7	total cost of weight group 7, dollars
CWP	waterplane coefficient
DB	depth of box, feet
DBMAR	design and builders margin
DCST	design cost, dollars
DH	diameter of hulls, feet
DHA(20)	electronics deckhouse area, sq ft
DHAR(20)	armament deckhouse area, sq ft
DHV	deckhouse volume, cu ft
DOLHR	labor rate, dollars/hour
DPTRY	displacement estimate, tons
DT	depth of ship to top of box, feet
ELD(20)	electronics electrical load, KW
ELKW	generator rated load, KW
ELLD(20)	armament electrical load, KW
ELOAD	total electronics electrical load, KW
ENCVOL	total volume of hull and deckhouse, cu ft
ENDDAY	number of endurance days for dry provisions
FRSC	free surface correction, feet
G1IND	cost index for weight group 1
G2IND	cost index for weight group 2
G3IND	cost index for weight group 3
G4CST	total material cost weight group 4, dollars
G5IND	cost index for weight group 5
G6IND	cost index for weight group 6

Nomenclature List (Continued)

G7CST	total material cost weight group 7, dollars
GR2CST	total material cost weight group 2, dollars
GR4CG(20)	group 4 vcg/DT
GR4CST(20)	material cost weight group 4, dollars
GR4WT(20)	group 4 weight, tons
GR7CG(20)	group 7 vcg/DT
GR7CST(20)	material cost weight group 7, dollars
GR7WT(20)	group 7 weight, tons
H	draft, feet
HEAD(20)	descriptive heading (alphanumeric)
HLA(20)	electronics hull area, sq ft
HLAR(20)	armament hull area, sq ft
HPMS	maximum sustained shaft horsepower
INDEX	control variable
IREAD	card reader dummy variable
IWRITE	line printer dummy variable
JOPT	input option variable for machinery
KGTRY	initial KG estimate, feet
LEN	length of torpedo-like hulls, feet
MCST	miscellaneous costs, dollars
MBLOC1	location of propulsion system index
MBLOC2	location of prime mover index
MOPT	material type option
MTYPE	machinery type option
NCPO	number of chief petty officers (real)
NENL	number of enlisted men (real)



Nomenclature List (Continued)

NOARM	number of armament input cards
NOELT	number of electronics input cards
NOFF	number of officers (real)
NOCPO	number of chief petty officers (integer)
NOCREW	number of enlisted men (integer)
NOOFF	number of officers (integer)
PALOAD	propulsion auxiliary electrical load, KW
PC	propulsive coefficient
RGEND	endurance range, nautical miles
SEP	separation of hull centerlines, feet
SFCHHP	specific fuel consumption at half horsepower, lbs/SHP-hr
SFCMHP	specific fuel consumption at maximum horsepower, lbs/SHP-hr
SHP(12)	shaft horsepower curve values
SHPE	shaft horsepower at endurance speed
SHPM	shaft horsepower at maximum speed
TITLE(5,40)	line titles (alphanumeric)
TOTCST	total lead ship cost, dollars
VEND	endurance speed, knots
VSUS	maximum sustained speed, knots
WACFUL	weight of aircraft fuel, tons
WCARGO	total cargo weight, tons
WFULLD	full load weight, tons
WLSHIP	light ship weight, tons
WTAC	total aircraft weight, tons

Nomenclature List (Continued)

WTAMMO	total ammunition weight, tons
WTCREW	total crew weight, tons
WTFUEL	total ships fuel weight, tons
WTG1	total group 1 weight, tons
WTG2	total group 2 weight, tons
WTG3	total group 3 weight, tons
WTG4	total group 4 weight, tons
WTG5	total group 5 weight, tons
WTG6	total group 6 weight, tons
WTG7	total group 7 weight, tons
WTLO	weight of lub oil, tons
WTPE	weight of personal effects, tons
WTPS	weight of personnel stores, tons
XF	longitudinal distance from stern to center of strut, feet
XLB	length of box, feet
XLS	length of strut, feet
XMLOC1	length of propulsor space, feet
XMLOC2	length of prime mover space, feet
YMLOC1	width of propulsor space, feet
YMLOC2	width of prime mover space, feet
ZMLOC1	height of propulsor space, feet
ZMLOC2	height of propulsor space, feet

6.3 Subroutine XECUTE

6.3.1 Purpose and Approach

Subroutine XECUTE controls the execution of each trial case input to the program. All of the program subroutines are called by this routine. XECUTE also generates a number of error messages. When the constraints of the data base are violated, when improper data is input, when a set of infeasible requirements or when no balance between assumed and calculated variables can be attained within a reasonable number of iterations, the subroutine calls for an output printing routine which prints the input data and the type of error which has been detected. If assumptions have been made to approximate a solution, a warning message is also printed along with the solution.

XECUTE calls up each of the subroutines listed in Figure 2 in order. The ship's dimensions are determined, the required horsepower calculated, liquids and electrical plant requirements determined, a volume balance is made and then a weight estimate is completed. Then XECUTE controls an iterative procedure to bring the weight estimate and displacement into agreement. After the weight-displacement check is made, another estimate and iteration procedure is used to balance the center of gravity location. After completing this balance, the routine directs the computation of the ship cost and, finally, printing of the answers.

6.3.2 Input List for Subroutine XECUTE

DPTRY LC(CG) JOPT LC(CC)
HPMS (JOPT=2 only) . . . SCDA KGTRY LC(GG)


```

LEN ..... LC(BB)   VEND ..... LC(CC)
MTYPE ..... LC(CC)  VSUS ..... LC(CC)

```

6.3.3 Program Development

This subroutine follows the approach used by many ship synthesis models in making an iterative solution to the design problem, but there are two differences - the method used for determining horsepower and the control over machinery selection.

First the DIM subroutine is called to determine the ship dimensions. The calling argument (R) is used to transfer values of excess KG. If the DIM routine cannot determine a suitable set of dimensions which meet the input requirements, the length is set equal to -10 feet and the XECUTE routine, sensing an error, prints an error statement.

The next routine called HPCALC is the longest and most complicated in the entire program. It also requires a large percentage of the total computation time in the program. Some control over the total running time and costs of the program is provided by limiting the number of HPCALC iterations to 5 by the statement:

```
IF(JNDEX.GT.5.OR.KNDEX.GT.5) GO TO 99
```

It was found that about 5 iterations are required for the geometry and horsepower requirements to stabilize during iterations. Although this test reduces the cost of the program by eliminating the HPCALC routine from the iteration after it is assumed that the horsepower remains relatively constant, it introduces an error in the final calculations. The user of the program receives a warning that this has occurred as part of the output.

HPCALC is a routine which calculates a set of points on a speed-power curve for the ship geometry which has been input. These values of speeds and horsepowers are stored in two arrays. SHP(12) and AKNOT(12). If any errors in the inputs to the HPCALC routine have occurred, an error message is generated.

Subroutine UGLYDK is called to pass a spline cubic fit to the set of data points generated by HPCALC. This routine was prepared by Kerwin and is in general use at MIT. It is considered to be part of the library for the program and will not be described in detail in this thesis. The arguments of the routine will be noted here, however.

CAL UGLYDK(10,1,1,AKNOT,SHP,ESL,ESR,AE)

The first argument is the number of input data points. The second and third are indicators for the method in which the ending slopes are treated by the routine: 1,1 indicates that the end slopes are to be tangents between the last two points at either end. The fourth argument is the array of input x values. The array of input y values, SHP, is the fifth argument. ESL and ESR are the left and right end slopes measured in degrees and these arguments are ignored when the second and third arguments are 1,1. AE is the one dimensional array of coefficients of the simultaneous equations solved to plot this curve. Subroutine UGLYDK calls Subroutine SIMQ, another Kerwin program considered as part of the library. This routine solves the system of simultaneous equations required to make up the spline cubic fit.

If the program is to calculate the horsepower required to sustain an input speed, Subroutine EVALDK is called next. This subroutine

is another of the Kerwin library routines. Its purpose is to evaluate the ordinate of a curve plotted by UGLYDK, given the abscissa value.

```
CALL EVALDK(10, 1, AKNOT, VSUS, SHPM, AE)
```

The first argument is the number of input data points; the second argument is the number of output values desired; the third argument is the x axis input value array; the fourth argument is the x axis value desired as an output; the fifth argument is the output y value, in this case the shaft horsepower; the last argument is the coefficient array generated by UGLYDK. The return from the call to EVALDK is the required value of horsepower. EVALDK is called for both the maximum sustained speed and endurance speed horsepower calculations. The maximum sustained speed is defined as the speed that can be made when the shaft horsepower is 80 percent of the maximum sustained horsepower. Therefore, the value returned for SHPM is divided by 0.8 and carried on to the rest of the program.

If the option to calculate the maximum speed for a given input shaft horsepower is exercised, two first approximations of speed are made, VMAX and VMAX1=0.95*VMAX, and EVALDK is applied to find the corresponding horsepower. Then a modified Newton-Raphson iteration is carried out using as an approximation of the slope of the horsepower curve.

$$d(\text{SHP})/d(\text{AKNOT}) \text{ at } \text{VMAX}, \text{ DELHP} = (\text{SHP1} - \text{SHP2}) / (\text{VMAX} - \text{VMAX1}).$$

The iteration stops when the difference between the two successive speed estimate values is less than one half percent of the best estimate. This method provides for relatively rapid convergence. The value of

endurance horsepower is computed using EVALDK in the same manner for this option as in the first.

The next section of the XECUTE routine determines whether the design trial case is still feasible with the machinery type specified and the geometry and horsepower requirements calculated. Diesel propulsion plants of more than 14000 shaft horsepower or in ships with hull diameters less than 14 feet are prohibited by this model. Diesel-electric and gas turbine-electric plants over 30000 shaft horsepower or with hulls too small to accept the propulsion motors are prohibited. Gas turbine propulsion is assumed to have the gas turbines mounted in the box for small horsepowers and in the hulls for large horsepowers. If the beam of the struts is too small for removal of the turbine components, this case must be prohibited. No plant above 70000 horsepower is permitted. If the machinery type selection, geometry and horsepower requirements are infeasible, an error message is printed out which suggests either specifying the machinery to be installed (JOPT=2) or gas turbine machinery. If the design trial case is still feasible, control is directed to the next subroutine.

Subroutine EPLANT is called to calculate the average electrical load and the size of the ship service generators.

Subroutine LIQ is called to calculate the weight of fuel, lubricating oil and potable water.

If the dimensions of the machinery space have been specified in the inputs using JOPT=2, subroutine MACHBX is not executed. If the machinery space size is not specified, MACHBX estimates the dimensions of the various machinery spaces.

Subroutine VOLUME is called next. This routine computes the required volumes and areas and balances the required and available areas. It adjusts the deckhouse size and the number of decks in the box to provide sufficient area. If insufficient area or volume is available, the value of LEN is set negative and an error message is generated by XECUTE.

Subroutine WEIGHT calculates all the weights which have not been input previously and determines the full load displacement. The returned value of full load displacement, WFULLD, and the displacement estimate, DPTRY, are used to generate the starting values for another Newton-Raphson iteration to determine the final displacement. The iteration is continued until the weight and displacement check within 9 tons or until the iteration has been completed 20 times. If the iteration is not converging an error message is generated.

Once the weight and displacement are sufficiently close, Subroutine VCG is called to calculate the vertical center of gravity location. An averaging procedure is used to make new estimates of the KG. The iteration proceeds until the difference in the estimate, KGTRY, and the returned value, CFULLD, is less than 1 foot. A limit of 20 iterations and an appropriate error message is provided. The wide value of the test is used because of the separation of the hulls controlling effect on stability. If excess stability occurs in the ship, it is still feasible but overdesigned. The program prints out a value of excess KG available.

After all balances have been completed, the cost of the ship is calculated by Subroutine COST.

Finally, the OUTPUT subroutine is called. A value of 1 in the second argument of the call prints the input data and an appropriate error message; a value of 2 causes both the input and output data to be printed. If an error message is generated, the program returns to MAIN for more input data.

6.3.4 Flow Chart

Figure 6 shows a flow chart for Subroutine XECUTE. Note the iteration for speed when JOPT=2 on the top of the second page of the figure, the decision on a feasible selection of machinery and dimensions at the bottom of the second page, the weight-displacement iteration on the bottom of the third page and the VCG iteration in the upper right quadrant of the third page.

6.3.5 Output List for Subroutine XECUTE

DPTRY..... LC(GG)
EXCKG..... SDCA
KGRTY..... LC(GG)
SHPE..... LC(CC)
SHPM LC(CC)

6.3.6 Nomenclature List

CFULLD	vertical center of gravity, KG, feet
DELHP	derivative of horsepower function
DP1	used to store DPTRY value, tons
EXCKG	excess KG, feet
FACTOR	derivative of weight function
JNDEX	vcg counter

FIGURE 6a: XECUTE SUBROUTINE FLOW CHART

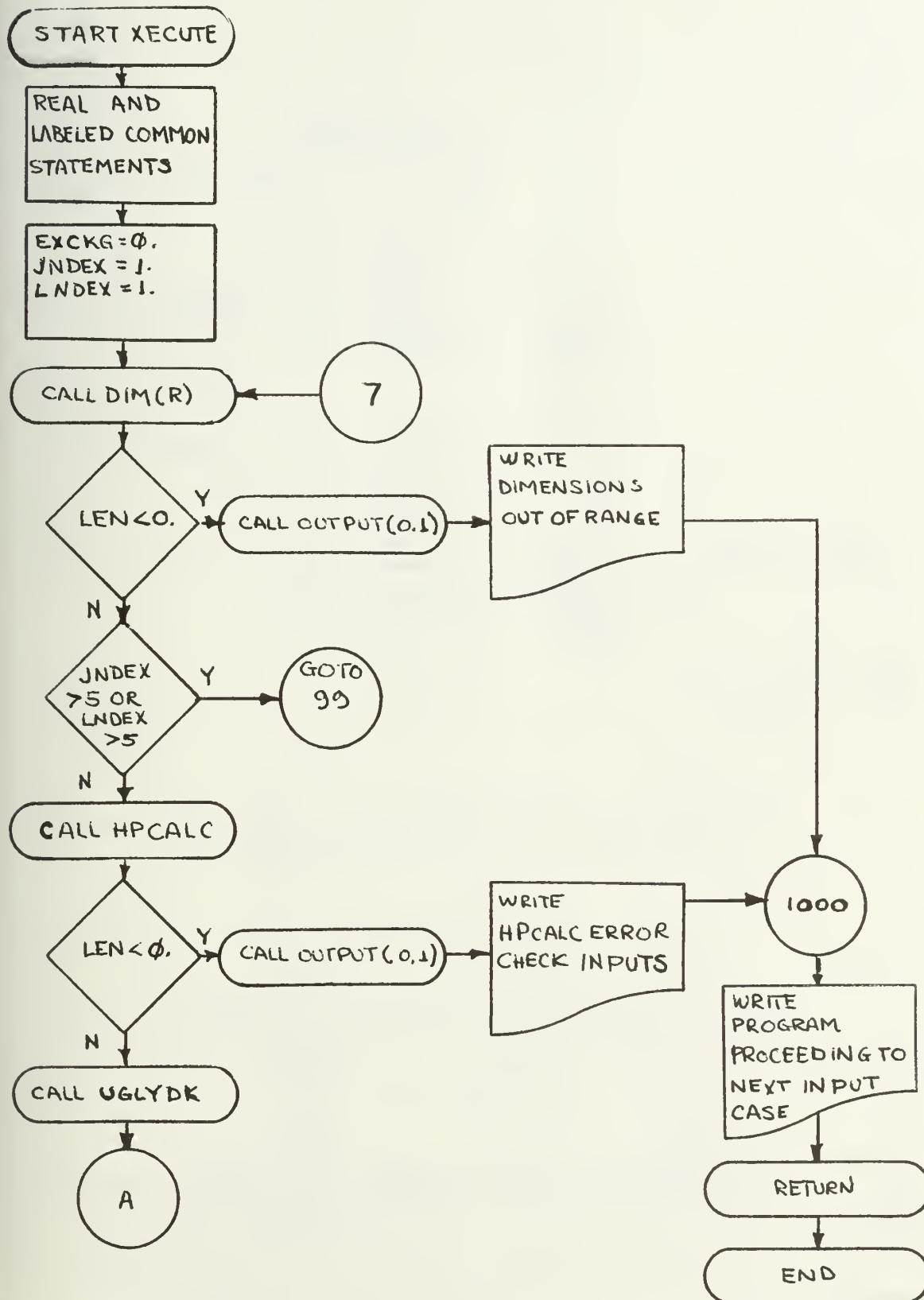


FIGURE 6b: XECUTE SUBROUTINE FLOW CHART-continued

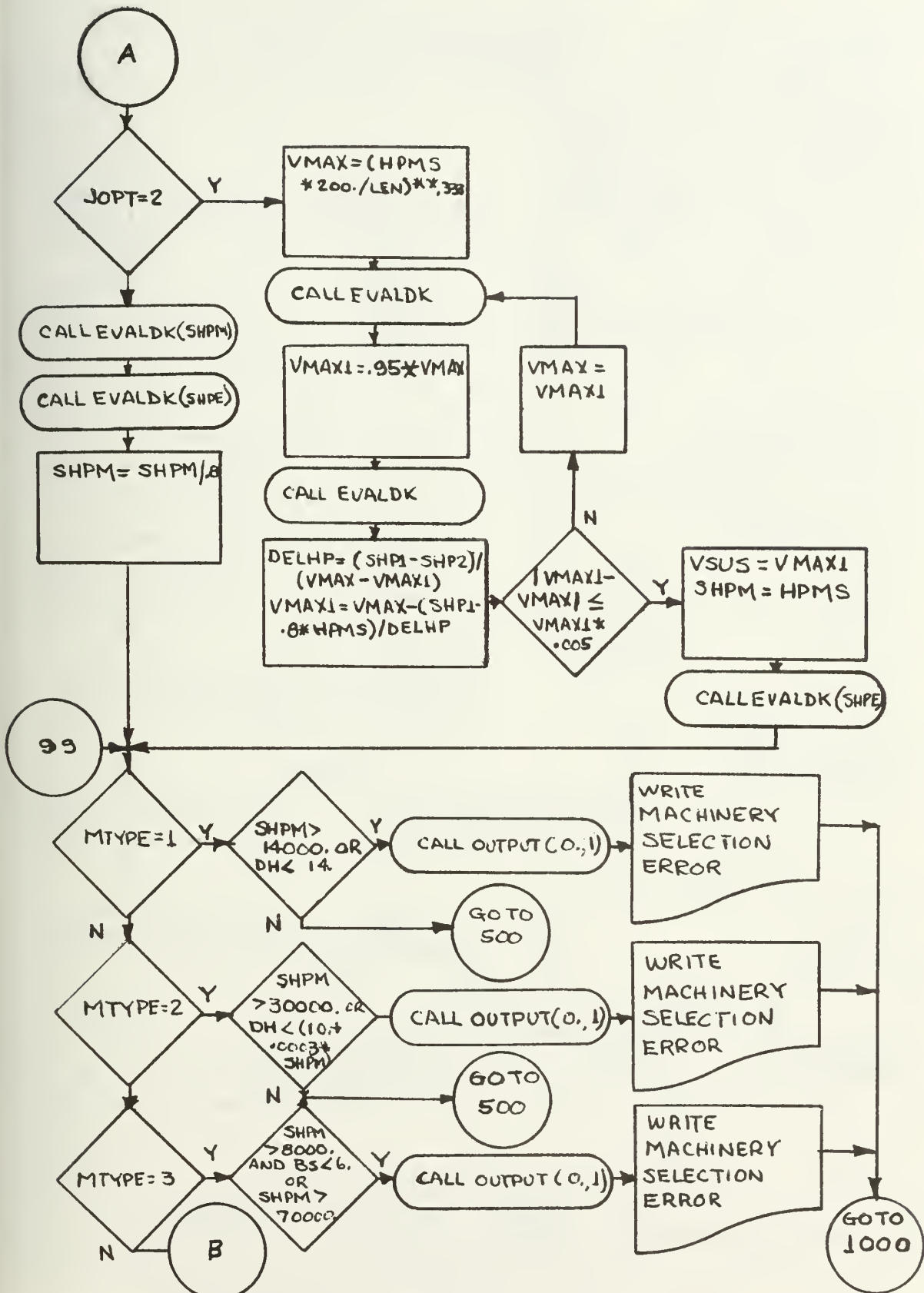
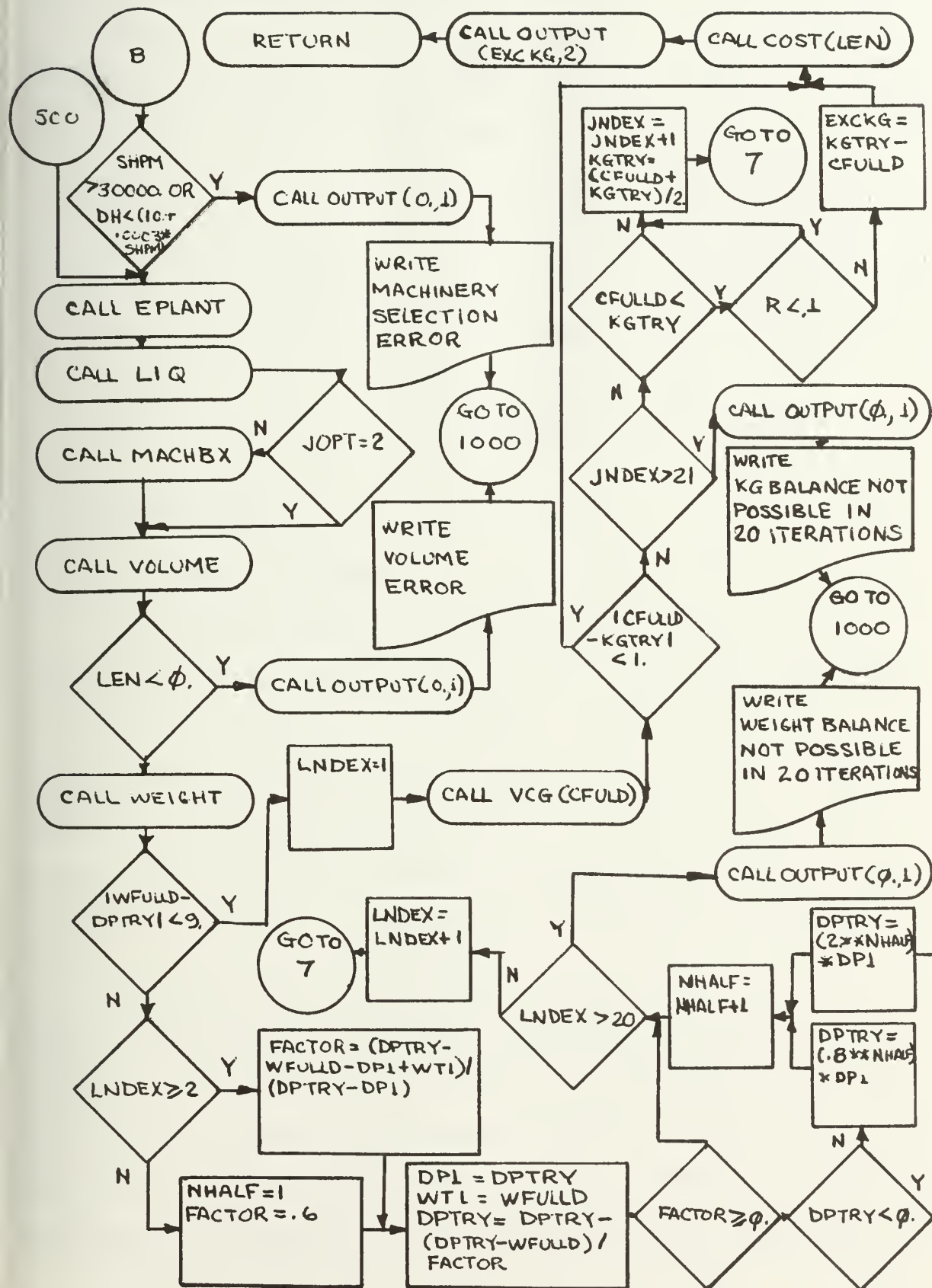


FIGURE 6c: XECUTE SUBROUTINE FLOW CHART-continued



Nomenclature List (Continued)

LNDEX	weight counter
NHALF	displacement trial counter
R	excess KG, feet
SHP	dummy used for shaft horsepower
SHP1	dummy used for shaft horsepower
SHP2	dummy used for shaft horsepower
VMAX	dummy used for speed, knots
VMAX1	dummy used for speed, knots
WT1	used to store WFULLD, tons

6.4 Subroutine DIM

6.4.1 Purpose and Approach

This routine determines the ship dimensions based on the input value of length and average SWATH geometry. The routine determines the diameter of the hulls, the strut length, strut width, waterplane coefficient and hull separation. The length, width, depth and air gap clearance of the box are also determined. Since the resistance determination made in Subroutine HPCALC requires the location of the strut on the hulls as an input, the DIM routine places the strut on the hull.

Several assumptions are necessary to prepare this subroutine. The hull is assumed to be of cylindrical form with an elliptical nose of length three times the diameter and a conical tail of length five times the diameter. Only one strut cases are allowed. This assumption was made considering two factors: the additional complexity involved in allowing more than one strut, and the results of several resistance

studies and preliminary design studies which indicate that in the service environment expected for vehicles designed by this model only single strut alternatives are desirable. The strut is sized with considerations for resistance and stability. Strut width is assumed to have the major impact on wave-making resistance and thus is increased slowly. The strut length is the primary variable assumed to influence longitudinal stability. The strut section is assumed to consist of parabolic nose and tail sections of lengths 3 and 5 times the strut beam, respectively, connected by a parallel mid section. The strut is wall-sided. Hull separation is assumed to be the primary variable influencing transverse stability. These simplifying assumptions result in rapid ship sizing. The box dimensions are assumed by this model to be 20 feet longer than the struts and of width equal to hull separation plus diameter. Air gaps are determined following SWATH design practice.

6.4.2 Input List for Subroutine DIM

DPTRY.....	LC(GG)	KGTRY	LC(GG)
FRSC	LC(GG)	LEN.....	LC(BB)

6.4.3 Program Development

This routine determines the diameter of the hulls, the volume of the hulls, checks for the displacement fraction of the hulls and then calculates a strut size which satisfies the stability requirements of the SWATH and attains a balance between the displacement of the ship and the assumed starting displacement. Then the box is sized and the strut location and air gap determined.

The diameter of the hulls is determined in two ways. Length/Diameter ratio versus length for ships in the data base are plotted in Figure 7. Using this relationship as a starting point, the diameter is determined. After the hull volume is calculated, the displacement of the hulls is required to be at least 65 percent of the trial displacement. If this test is not met, the hull diameter is incremented until the displacement of the hulls is at least 65 percent of the trial displacement. Length/Diameter ratio plotted versus speed-length ratio was investigated as an estimating method and found to give larger data scatter than the relation used.

Displacement balance and resistance considerations drive the calculation of strut dimensions. The strut size is incremented until the displacement checks. First the length of the strut is incremented until the ratio of strut length to hull length exceeds 0.80, a limit of good practice set in the model. Then the waterplane coefficient is incremented between values of 0.84 and 0.94. Only two ships in the data base fall outside these limits. To reduce the effect of hull dimensions on resistance, the beam of the strut is incremented last. The range of acceptable beams is from 4 feet, for structural and access considerations, to 55 percent of the hull diameter. There is only ship outside these limits in the data base; the SSP has a strut beam of 3.6 feet. If no displacement balance can be achieved within the limits of this increment loop, the program returns an error message.

After the displacement balances, longitudinal metacentric height is checked. A relation between waterplane coefficient and inertia coefficient for the assumed waterplane shape is plotted in Figure 8. An

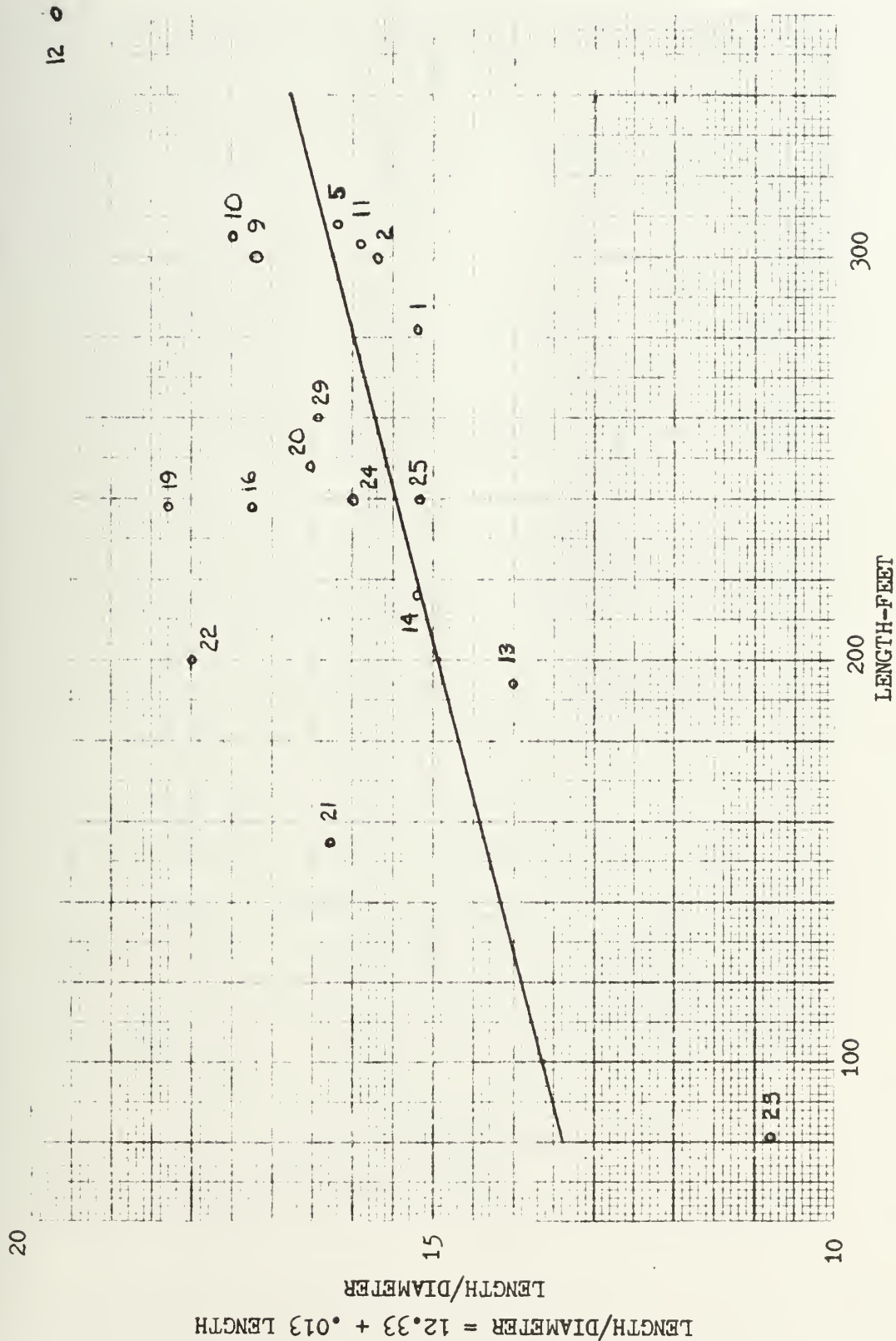
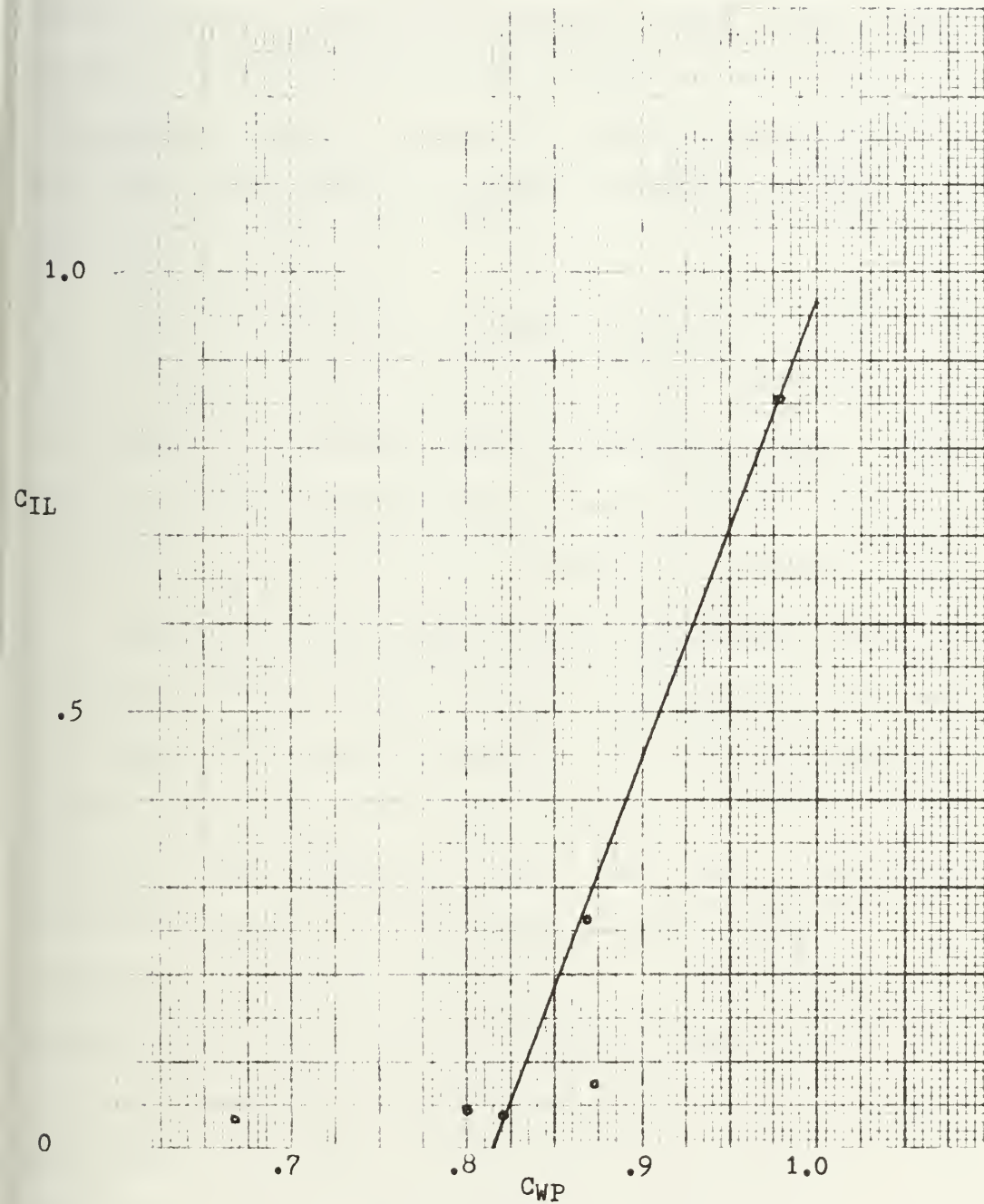


FIGURE 7: LENGTH/DIAMETER VERSUS LENGTH

FIGURE 8: C_{IL} VERSUS C_{WP}



$$C_{IL} = I_L / (\text{STRUT LENGTH})^3 \times \text{STRUT WIDTH}$$
$$C_{IL} = 5.2141 C_{WP} - 4.2491$$

estimate is made of the center of buoyancy location. BG is calculated from the trial KG value. No allowance is made for free surface in the determination of longitudinal metacentric height, GML. A test value of 0.1 times the length of the strut is assumed in this routine. If the test is passed, the program continues to calculate the transverse metacentric height as a function of the separation. If the test is failed, the program returns an error.

Transverse metacentric height is estimated using a relation given in (5). Separation of the hulls is varied from .22 to .40 times the length of the hulls, until the test value for metacentric height, .2 times the hull diameter, $.2*DH$, is exceeded. If a separation of more than $.4*LEN$ is required to meet this criterion, the program returns an error.

The final section of this subroutine calculates additional ship dimensions required in the remainder of the program. The value of excess KG, R, is computed using the same relationships previously applied. The strut is placed on the hull with its center at 52 percent of the hull length forward of the tail. This is an average value for existing SWATH designs. The box dimension relationships are representative of SWATH designs and are held fixed in this model. Minor variations in box size may make rather large changes in volume due to the box form. The depth of the box is initialized for a one deck ship. Air gap is determined as a function of length and is held constant at 15 feet for ships longer than 200 feet. This provides for reduced effects of wave slap and seaway leads up to sea state 5.

6.4.4 Flow Chart

Figure 9 shows a flow chart for Subroutine DIM.

6.4.5 Output List for Subroutine DIM

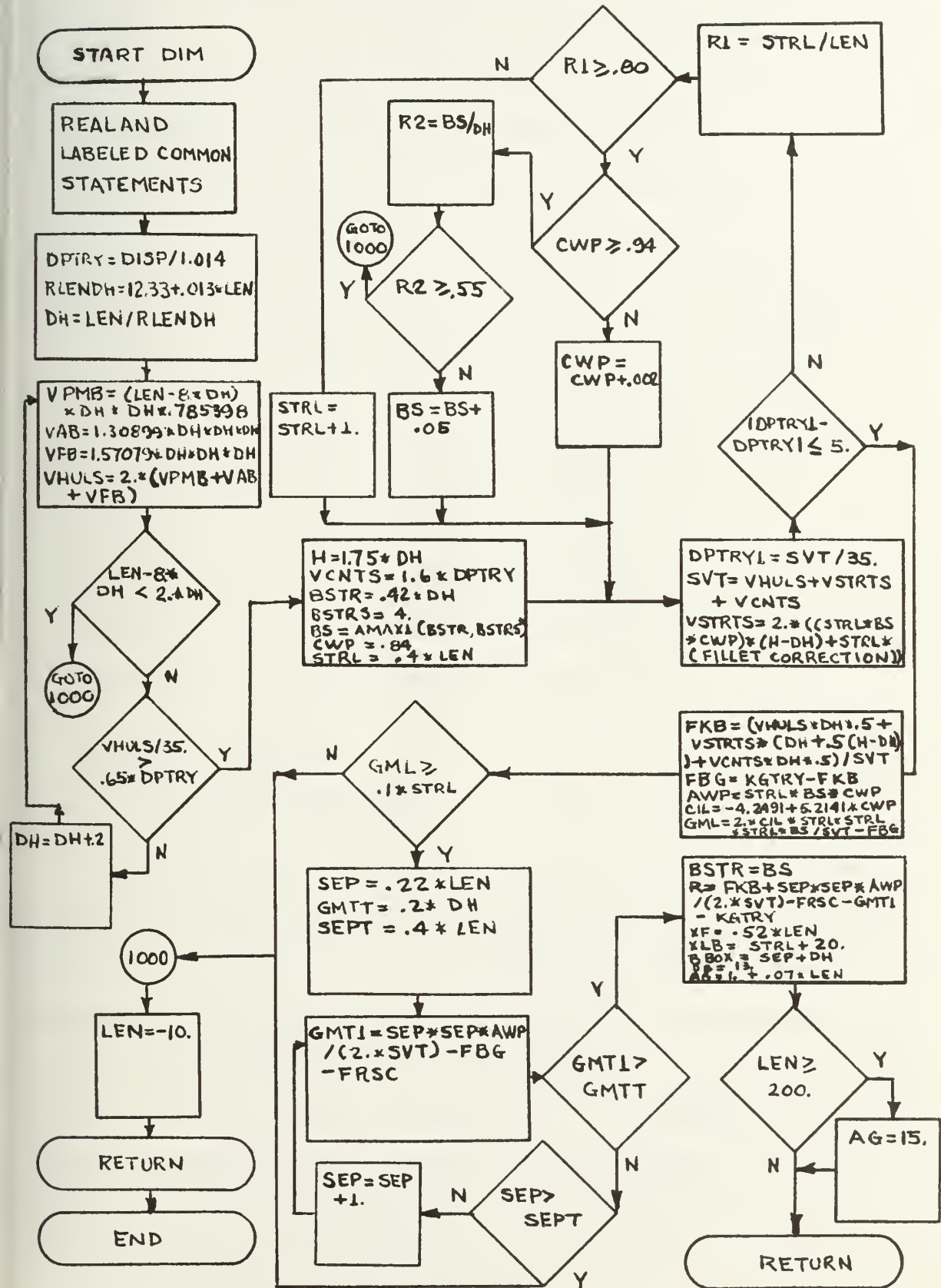
AG	LC(JJ)	H	LC(JJ)
BBOX	LC(GG)	R	SDCA
BS	LC(GG)	SEP	LC(JJ)
CWP	LC(GG)	XF	LC(JJ)
DB	LC(JJ)	XLB	LC(JJ)
DH	LC(GG)	XLS	LC(GG)

6.4.6 Nomenclature List

All variables used in this routine are the same as those defined for the MAIN program with the following exceptions:

AWP	area of the waterplane of one strut, sq ft
BSTR	beam of strut, ft-same as BS in MAIN
BSTRS	minimum beam of strut, ft
CIL	inertia coefficient of waterplane
DISP	displacement, tons - same as DPTRY in MAIN
DPTRY	displacement of moulded form, tons
FBG	distance from center of buoyancy to center of gravity, ft
FKB	distance from baseline to center of buoyancy, ft
GML	longitudinal metacentric height, ft
GMTT	test value for transverse metacentric height, ft

FIGURE 9: DIM SUBROUTINE FLOW CHART



Nomenclature List (Continued)

GMT1	transverse metacentric height, ft
R	excess KG, ft
RENDH	Length-Diameter ratio
R1	strut length/hull length ratio
R2	strut base/hull diameter ratio
SEPT	test value for hull centerline separation, ft
STRL	strut length, ft-same as XLS in MAIN
SVT	total submerged volume, cu ft
VAB	volume of hull tail, cu ft
VCNTS	volume of control surface, cu ft
VFB	volume of hull nose, cu ft
VHULS	total volume of hulls, cu ft
VPMB	volume of parallel section of hull, cu ft
VSTRTS	volume of struts, cu ft

6.5 Subroutine HPCALC

6.5.1 Purpose and Approach

Subroutine HPCALC calculates points on a speed-power curve for the SWATH geometry input and it stores the values of speed and horsepower in two arrays which can be recalled and used to determine the horsepower requirements or speed attained for a given horsepower by an interpolation procedure in Subroutine XECUTE. This routine is based entirely on the work of Richard Chapman^(12,22). Chapman's SWATH resistance program, DRAG, is general in its application. It accepts varied geometries, speed increments, options on control surfaces,

hydrodynamic assumptions and includes several types of plotting routines. Chapman uses a combination of empirical drag coefficient formulations, standard frictional drag formulations, interference and eddy-making drag correction factors and a linearized potential flow solution for wave making drag. In this synthesis model, certain simplifications of this program were desirable to reduce the overall size of the program and expense of generating feasible solutions.

The simplifications of the DRAG program which were made for this subroutine restrict its use to the SWATH forms which are generated by this model. Two hull SWATH configurations with one strut per hull are assumed. The hulls are assumed to have elliptical noses of length 3 times the hull diameter and parabolic tails of length 5 times the hull diameter. The struts are assumed to have parabolic noses and tails of length 3 times the strut beam and 5 times the strut beam, respectively and a parallel section between the nose and tail. No appendages are assumed in the calculation although a 6 percent appendage resistance is added at the end of the calculation. The routine assumes a 10 percent eddy-making drag correction. A speed range of 6 to 33 knots with a 3 knot increment is assumed fixed in this routine. The interested reader is referred to reference (12) for a discussion of the theory of the DRAG program.

6.5.2 Input List for Subroutine HPCALC

The basic dimensional data computed in Subroutine DIM is required as input for HPCALC and it is available in common storage.

BS	LC(GG)	PC	LC(CC)
DH	LC(GG)	SEP	LC(JJ)
H	LC(JJ)	XF	LC(JJ)
LEN	LC(BB)	XLS	LC(GG)

6.5.3 Program Development

A detailed description of the complete DRAG program is to be found in reference (22). To provide insight into what the routine does, the steps of the calculation will be summarized here. First the dimension data are transferred from storage and other dimensions required in the routine are computed. Then the volume and surface area of each of the submerged components of the ship is calculated. It is assumed that the displacement generated in this calculation is more accurate than that approximated in the dimension routine and this value of displacement replaces the test value in storage. Wind drag of the box structure is computed next. Then an eddy making drag term is computed for the struts. A velocity loop is started which will calculate the drag values at speeds from 6 to 33 knots in 3 knot increments. Wave-making resistance is estimated using a 400 term expansion. Then frictional resistance coefficients for the hull parts are estimated. Schoenherr friction and a ΔCF value of .0005 are used. A 10 percent addition to hull friction drag is applied to account for eddy-making. The final resistance component estimated in this routine is spray drag from the struts. Then the drag components are summed, a 6 percent allowance added for appendages and a horsepower value is computed as a function of the input propulsive coefficient for each speed generated in the loop. The looping on speed continues until the DO parameter is satisfied and

the POW and VKNTS arrays are filled with values of shaft horsepower and speed, respectively. A user of this routine is cautioned that any change in the speed values desired as output necessitates a change in the speed DO loop and the dimensions of the arrays for storing the horsepower and speed data as well as the dimension of the coefficient arrays for storing the horsepower and speed data as well as the dimension of the coefficient array for the spline cubic curve fitting routine, UGLYDK, used in subroutine XECUTE. It is felt that the range of speed values calculated by the existing program is sufficient for the required operating speeds for Coast Guard SWATH applications.

6.5.4 Flow Chart

A simplified flow chart of the HPCALC subroutine showing the order and type of calculations performed is shown in Figure 10.

6.5.5 Output List for Subroutine HPCALC

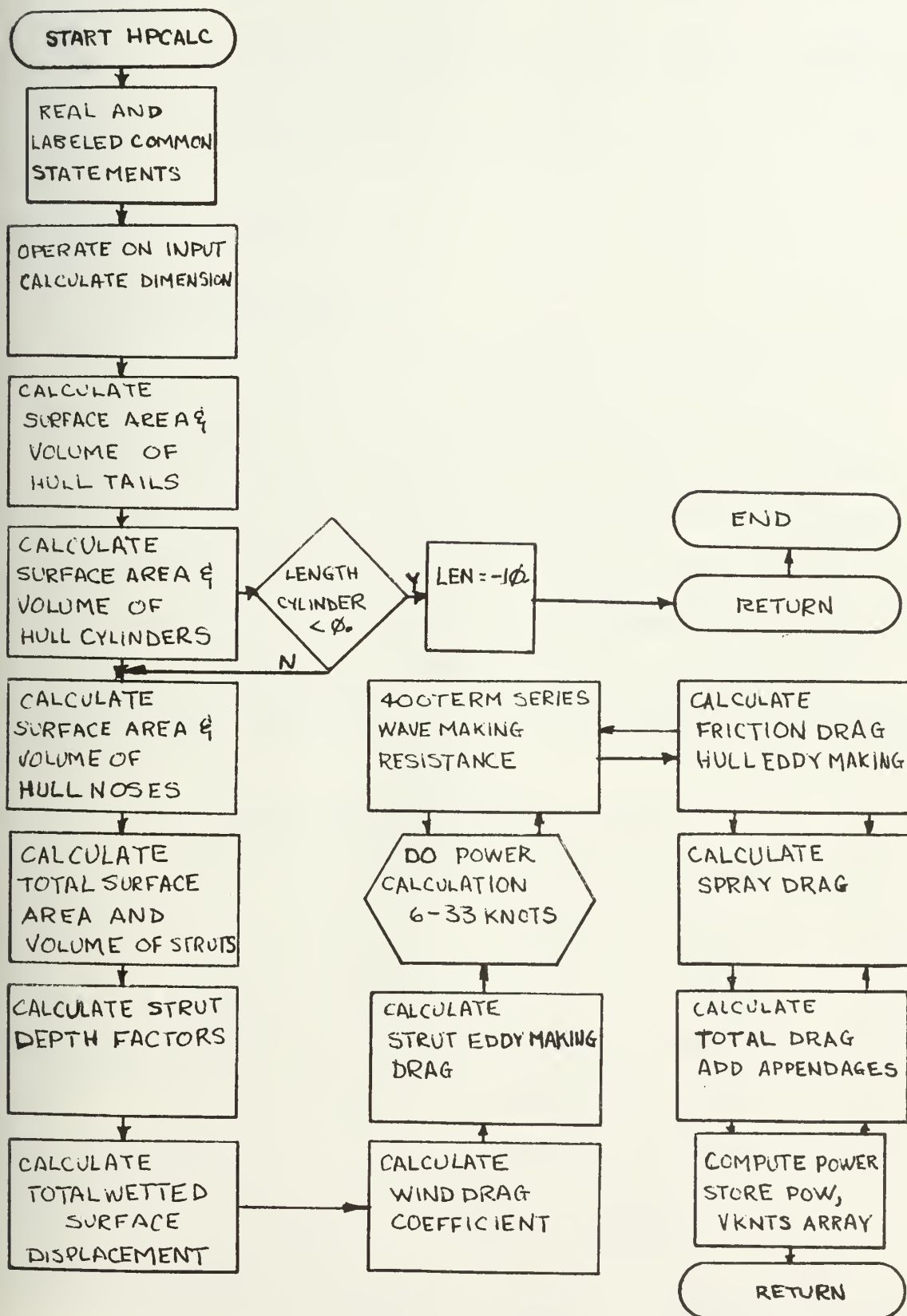
TONS..... LC(GG)
POW(12)..... LC(SS)
VKNTS(12) LC(SS)

6.5.6 Nomenclature List

There are a large number of variables defined within this subroutine. With the exception of those listed below, each of these variables is defined by a comment card in the program listing, is not used elsewhere in the model, and therefore will not be listed in this section.

CA	length of the strut-in feet - XLS in MAIN
EFGH	depth of box for wind drag calculation, feet - DB in MAIN

FIGURE 10: HPCALC SUBROUTINE FLOW CHART



TA	strut beam in feet - BS in MAIN
TONS	displacement, tons - DPTRY in MAIN
W	width of channel used in wave-making resistance estimate, ft
XA	distance from tail to center of strut, feet - XF in MAIN

6.6 Subroutine EPLANT

6.6.1 Purpose and Approach

This subroutine performs two functions. It estimates the average electrical plant load for use in estimating the fuel requirements for providing electrical energy to the ship and it calculates the size of generator needed for installation on the ship based on the expected loads with appropriate margins. Both of these outputs are useful in the preliminary design phase. The EPLANT routine follows Goodwin's routine with modification to provide for SWATH options. Goodwin's data for conventional ships and data for one SWATH design are shown in Table III.

TABLE III
ELECTRICAL LOAD DATA IN KW

Ship	150 WPB	210 WMEC	378 WHEC	240 AGOR
Electronics	4.8	21.99	117.84	72.00
Armament	42.7	0.0	46.64	0.0
Propulsion Auxiliaries	1.02	.71	71.03	15.00
Air Conditioning and Ventilation	21.1	49.13	308.34	190.00
Hotel	20.9	35.4	171.51	88.00
Other Auxiliaries	19.8	46.76	113.08	204.00
Steering Gear	.54	4.48	37.38	
Auxiliary Machinery	18.26	40.08	70.72	110.
Shops	1.0	2.2	4.98	
Mission Related				94.
	<hr/> 110.32	<hr/> 153.99	<hr/> 827.44	<hr/> 569.00

6.6.2 Input List for Subroutine EPLANT

Electronics and armament electrical loads, whether the machinery plant auxiliary load is specified and what that load is, the type of machinery plant and the crew size are inputs through the MAIN program. Cubic number is estimated in the MAIN program and used in EPLANT. The following is the input list:

BLOAD. LC(DD)	NCPO. LC(AA)
CN. LC(BB)	NENL. LC(AA)
ELOAD. LC(DD)	NOFF. LC(AA)
JOPT. LC(CC)	PALOAD. LC(AA)
MTYPE LC(CC)	

6.6.3 Program Development

In using Goodwin's electric plant sizing relationships as a starting point for a SWATH model it is assumed that the requirements of Coast Guard operated SWATHs will be similar to that of conventional ships and that the parameters used by Goodwin apply to SWATHs. This routine assumes that the electronics and armament loads are input. Then the propulsion auxiliary load is estimated. For diesel propulsion a value of 1 KW is assumed for equipment directly related to the operation of the main propulsion machinery. For diesel electric propulsion a value for propulsion auxiliaries of 15 KW is used based on data from the AGOR SWATH estimates. For gas turbine plants and gas turbine electric plants a value of 71 KW is used. If the JOPT option is used with propulsion data as input, the input value of propulsion auxiliary load is used.

Air conditioning loads are estimated as a function of cubic number times the number of accommodations. This relation is shown in Figure 11. Note that the one SWATH point falls well off the estimating curve. This ship has the volume sufficient for a crew of approximately 100 if military standards are used, yet its crew is 49 and the arrangements are more nearly commercial practice. If the crew size were doubled on this ship, its data point would fall very nearly on the estimator.

Hotel loads, which consist of galley and lighting loads, are estimated as a function of the number of accommodations. This relation is shown in Figure 12. Again note that the one SWATH point is well off the estimator but if the crew size is brought more in line with military practice, the point will fall nearly on the line.

Other auxiliary loads are estimated as a function of cubic number. This relation is shown in Figure 13. Note that the SWATH point falls near the line if a large portion of the mission related loads, which are considerable on this ship, are removed from the relation.

The total electrical load computed is the sum of the electronics, armament, propulsion auxiliaries, air conditioning and ventilation, hotel and other auxiliaries loads with a two percent growth margin on all equipment and a 100 percent margin on electronics. The average load for determining fuel requirements is the total load without margins minus armament. An additional factor of 25 percent is included to allow for starting loads and deterioration.

Three diesel generators, each of which is capable of carrying the entire ship load, are assumed in this model. The smallest generator

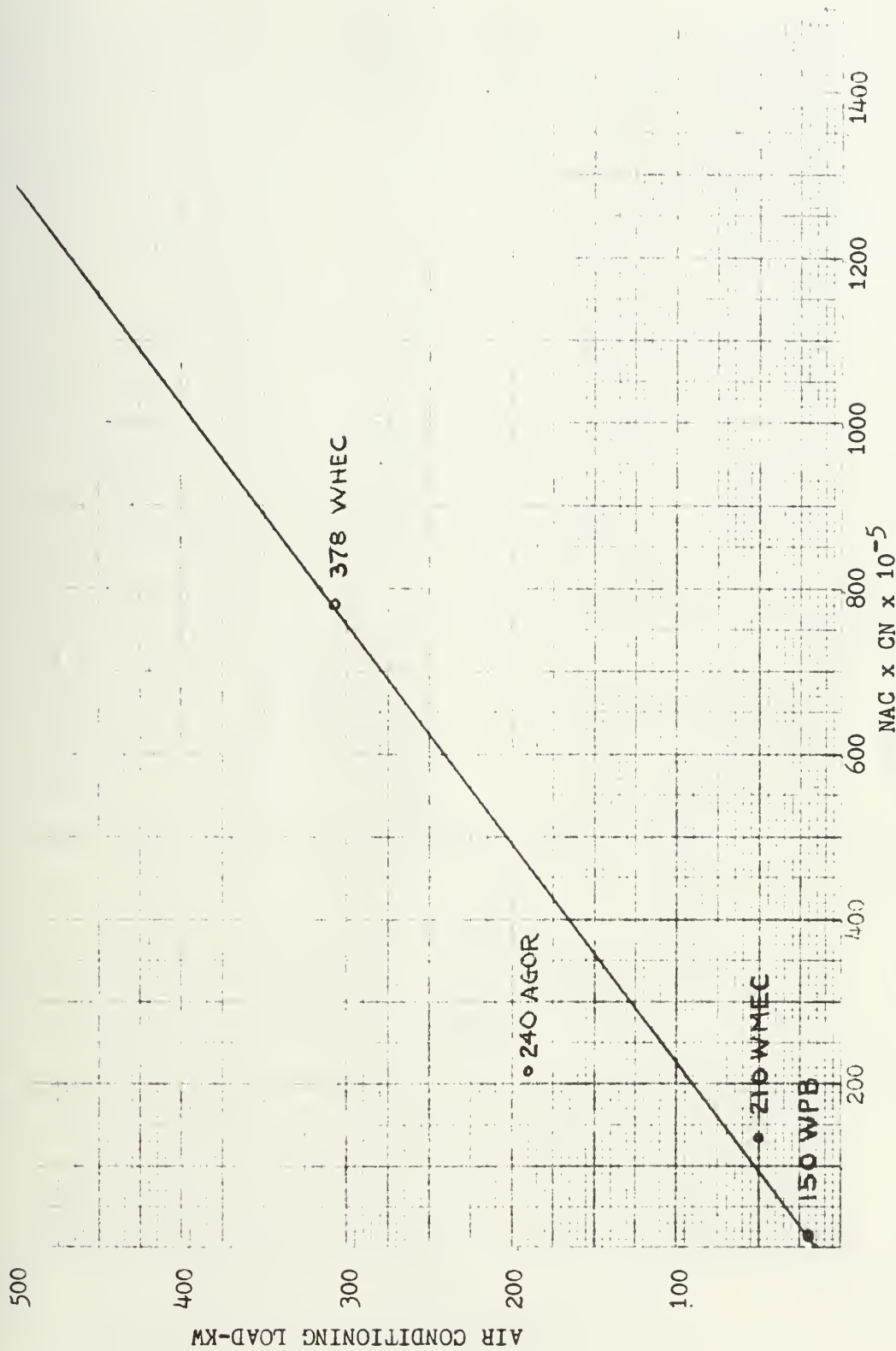


FIGURE 11: AIR CONDITIONING LOAD VERSUS $NAC \times CN \times 10^{-5}$

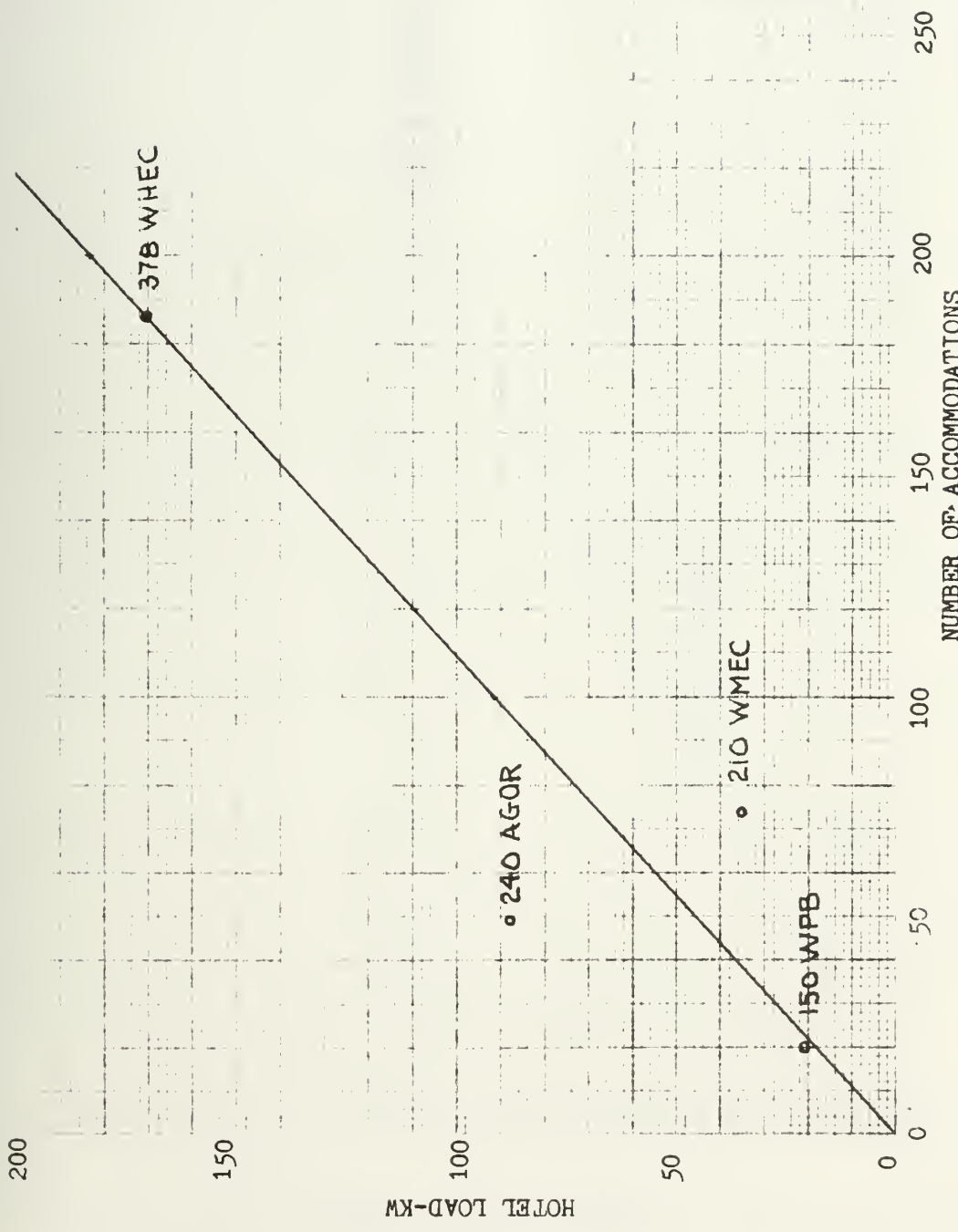


FIGURE 12: HOTEL LOAD VERSUS NUMBER OF ACCOMMODATIONS

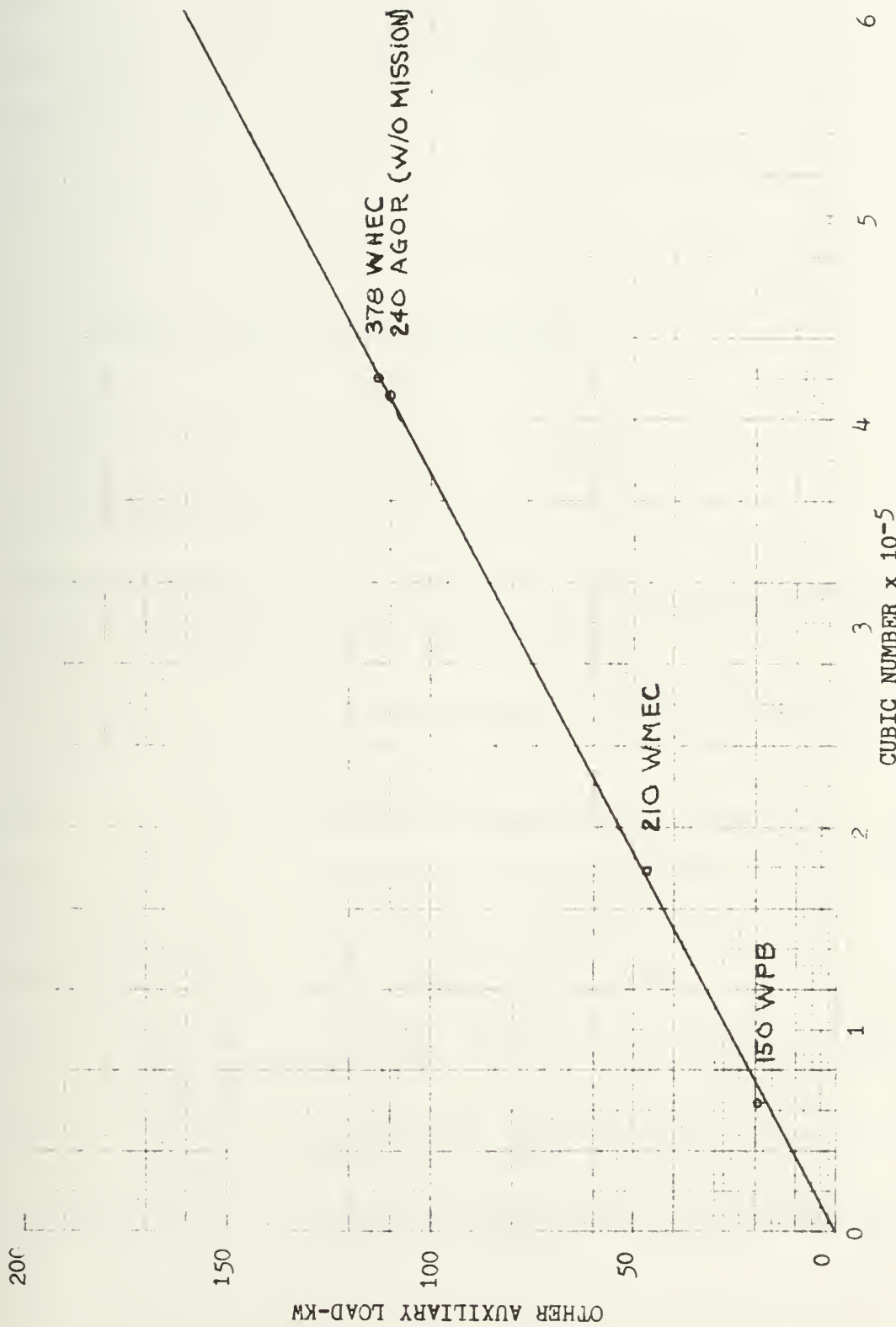


FIGURE 13: OTHER AUXILIARY LOAD VERSUS CUBIC NUMBER x 10⁻⁵

size to be installed is assumed to be 100 KW. Other possible plant sizes are between 100 and 250 KW in 50 KW increments, between 250 and 1000 KW in 250 KW increments and above 1000 KW in 500 KW increments. The final section of the subroutine chooses the smallest generator capable of supplying the load.

6.6.4 Flow Chart

A flow chart of this routine is shown in Figure 14.

6.6.5 Output List for Subroutine EPLANT

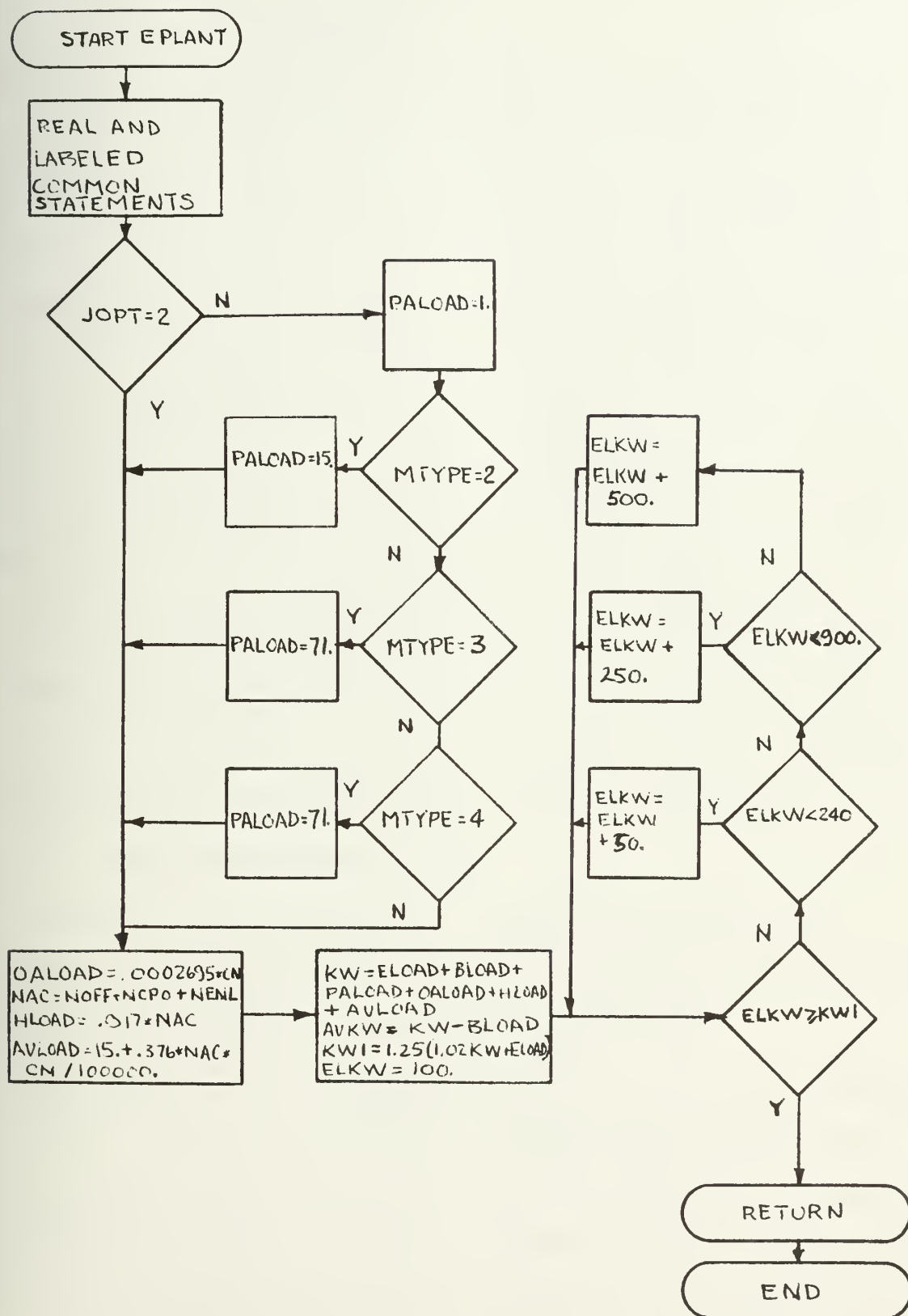
AVKW LC(DD)
ELKW LC(DD)

6.6.6 Nomenclature List

All variables have the same definition as given in the MAIN program nomenclature with the exception of the following:

AVLOAD	air conditioning and ventilation load, KW
HLOAD	hotel load, KW
KW	total load without margins, KW
KW1	total load with margins, KW
NAC	number of accommodations
OALOAD	other auxiliaries load, KW
RE	endurance range, nautical miles - RGEND in MAIN
SFCH	specific fuel consumption at half power - SFCHHP in MAIN
SFCM	specific fuel consumption at maximum power - SFCMHP in MAIN
VE	endurance speed, knots - VEND in MAIN

FIGURE 14: EPLANT SUBROUTINE FLOW CHART



6.7 Subroutine LIQ

6.7.1 Purpose and Approach

The shaft horsepower and size of the electrical plant have been determined for the ship. With this information the weight of required fuel, lubricating oil and potable water can be calculated. Subroutine LIQ estimates the endurance power specific fuel consumption, SFC, in pounds per shaft horsepower - hour, calculates, the required fuel weight to meet endurance requirements, calculates lubricating oil weight as a function of machinery type and horsepower and calculates potable water weight as a function of crew size. If a specific machinery plant is input, the input description includes the specific fuel consumption at half and full power. These data are used to estimate the endurance fuel requirements.

Data on specific fuel consumption as functions of horsepower and machinery type are compiled and linear approximations of variation of specific fuel rate between half and full power were computed. This data and the associated equations are shown in the following sections.

6.7.2 Input List for Subroutine LIQ

Crew size, electrical load data, endurance range and speed, horsepower required for speeds and machinery type are required inputs. If JOPT equals 2 the specific fuel consumptions are input.

AVKW	LC(DD)	RE	LC(CC)
JOPT	LC(CC)	SFCH (JOPT=2 only) . .	LC(CC)
MTYPE	LC(CC)	SFCM (JOPT=2 only) . .	LC(CC)
NCPO	LC(AA)	SHPE	LC(CC)
NENL	LC(AA)	SHPM	LC(CC)
NOFF	LC(AA)	VE	LC(CC)

6.7.3 Program Development

Gas Turbine specific fuel consumption data were gathered and analyzed. The gas turbine horsepower range was divided into three categories and specific fuel consumption relationships were computed for each horsepower range based on the data. The three horsepower ranges are representative of small, medium and large marine gas turbines and include both first and second generation turbine data. For diesel propulsion it is assumed that the SFC at full power is 0.42 pounds per shaft horsepower-hour and at half power, 0.46 pounds per shaft horsepower-hour. For the electric power options an efficiency of 0.97 is assumed for the motors and generators, respectively and 0.98 for the connections; this results in an overall loss of 8.5 percent. Experimental values from existing installations indicate that the electrical losses are approximately six and fifteen percent for alternating and direct current systems, respectively. In this model linear relationships between the full and half power point specific fuel consumptions are assumed. No allowance for the possibility of cruising on one shaft at endurance speed is made for the gas turbine or gas turbine-electric configurations, but a fuel saving for reducing the number of connected diesel engines is assumed. Table IV summarizes the assumed values of specific fuel consumption for machinery types and horsepower. These specific fuel consumption estimates lead to the following equations for estimating the endurance fuel consumption. For Diesel propulsion systems:

$$\text{SFC} = 0.5 - 0.08 * \text{SHPE} / \text{SHPM}$$

TABLE IV
FUEL RATE ASSUMPTIONS

MACHINERY TYPE	NOMINAL HORSEPOWER	SFCM	SFCH
GAS TURBINE	More Than 30000	.40	.49
FT 9	35000	.391	.491
FT 4 A-2	25500	.475	-
LM 2500	24050	.393	.474
GAS TURBINE	8000 - 30000	.56	.64
LM 1500	14300	.56	.64
GAS TURBINE	Less Than 8000	.57	.71
GTP 990	5000	.473	-
TYNE	4000	.50	-
PROTEUS	3000	.66	-
TF 35	2750	.571	.71
LM 100PJ102	1150	.629	.809
GAS TURBINE-ELECTRIC	More Than 30000	.43	.53
GAS TURBINE-ELECTRIC	8000 - 30000	.61	.69
GAS TURBINE-ELECTRIC	Less Than 8000	.62	.77
DIESEL	3500	.42	.46
DIESEL-ELECTRIC	3500	.46	.50

For Diesel propulsion systems where the maximum horsepower exceeds 7000 and the endurance horsepower is less than half the maximum horsepower:

$$\text{SFC} = 0.5 - 0.16 * \text{SHPE} / \text{SHPM}$$

For Diesel-electric propulsion:

$$\text{SFC} = 0.54 - 0.08 * \text{SHPE} / \text{SHPM}$$

For Diesel-electric propulsion with low endurance horsepower requirement:

$$\text{SFC} = 0.54 - 0.16 * \text{SHPE} / \text{SHPM}$$

For gas turbine propulsion with maximum horsepower required less than 8000:

$$\text{SFC} = 0.85 - 0.28 * \text{SHPE} / \text{SHPM}$$

For gas turbine propulsion in the 8000 to 30000 horsepower range:

$$\text{SFC} = 0.64 - 0.16 * \text{SHPE} / \text{SHPM}$$

For gas turbine propulsion above 30000 horsepower:

$$\text{SFC} = 0.49 - 0.18 * \text{SHPE} / \text{SHPM}$$

For gas turbine-electric propulsion of less than 8000 horsepower:

$$\text{SFC} = 0.92 - 0.30 * \text{SHPE} / \text{SHPM}$$

For gas turbine-electric propulsion in the 8000 to 30000 horsepower range:

$$SFC = 0.77 - 0.16 * SHPE / SHPM$$

For gas turbine-electric propulsion above 30000 horsepower:

$$SFC = 0.63 - 0.20 * SHPE / SHPM$$

If the maximum horsepower and half power specific fuel consumption values are input the following relation is used to determine the fuel consumption at endurance speed:

$$SFC = SFCM + (1. - SHPE / SHPM) * 2. (SFCH - SFCM)$$

The specific fuel consumption of the main propulsion machinery is added to the specific fuel consumption for ship service generators and the fuel consumption for hotel services to determine the total fuel rate. The specific fuel consumption for the ship service generators is assumed to be about 0.48 pounds per shaft horsepower-hour or 0.65 pounds per kilowatt hour. Fuel consumption for the generators is calculated using the average electrical load. Fuel consumption for hotel services is taken as 0.32 pounds per man-hour and assumes some waste heat recovery. The total weight of fuel is calculated as the total fuel rate time the endurance is nautical miles times a fouling allowance times a degradation allowance times a torsion meter correction times a tail pipe allowance divided by the endurance speed in knots and 2240 to convert to tons. Thus,

$$WTFUEL = FR * RE(1.1)(1.05)(1.03)(1/.95) / (2240. * VE) = FR * RE / (1788. * VE)$$

Lubricating oil requirements are assumed to be five tons plus one ton per thousand horsepower for any Diesel plant or three and one half tons plus one ton per ten thousand horsepower for all gas turbine plants. Potable water requirements are taken as fifty gallons per man or 0.186 tons per man.

6.7.4 Flow Chart

A flow chart of this routine is shown in Figure 15.

6.7.5 Output List for Subroutine LIQ

WTFUEL LC(LL)

WTLO LC(LL)

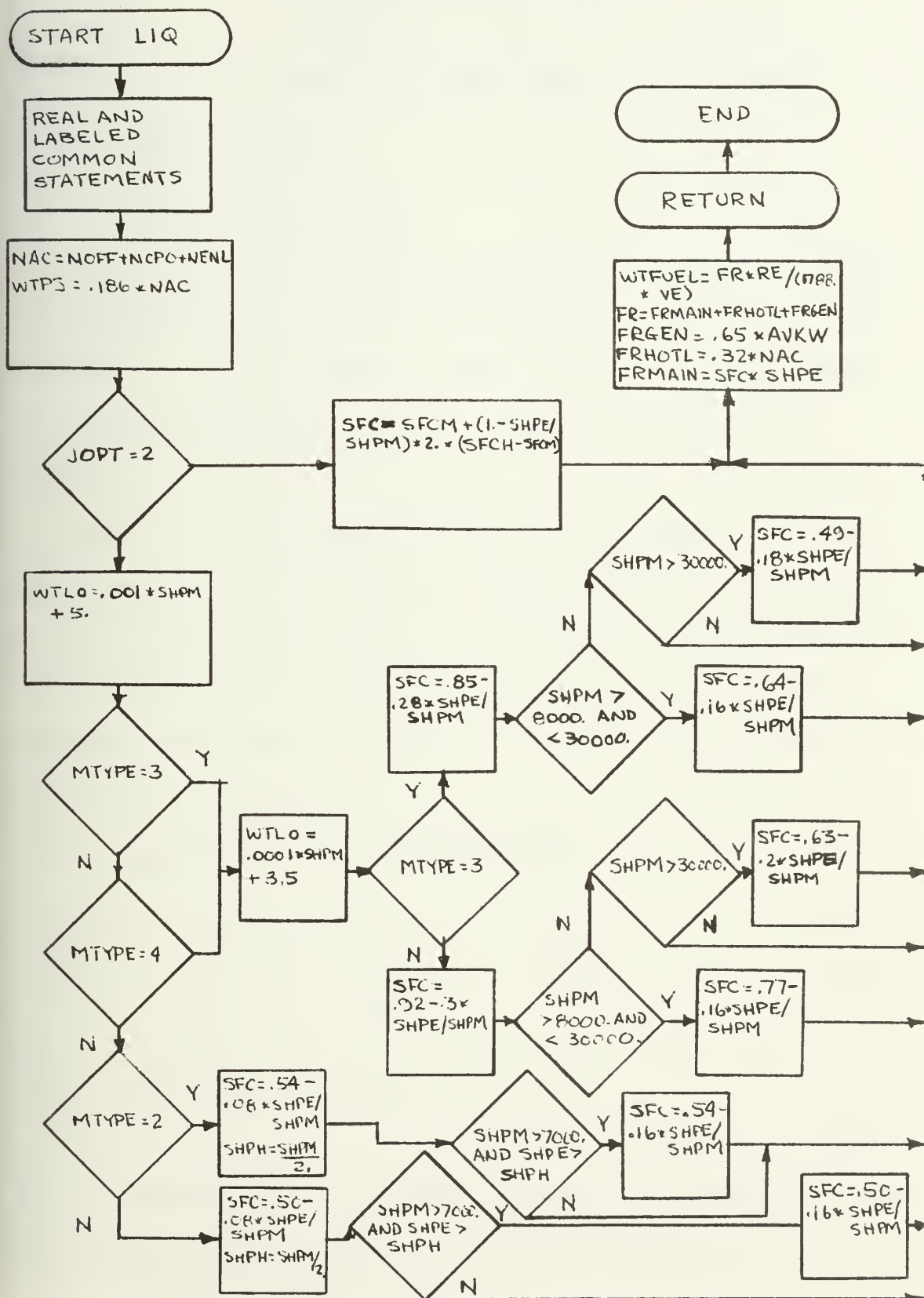
WTPS LC(LL)

6.7.6 Nomenclature List

All variables have the same definitions as given in the MAIN program nomenclature with the exception of the following:

FR	total fuel rate in pounds per hour
FRGEN	generator fuel rate in pounds per hour
FRHOTL	hotel fuel rate in pounds per hour
FRMAIN	main engine fuel rate in pounds per hour
NAC	number of accommodations
RE	endurance range, nautical miles - RGEND in MAIN
SFC	specific fuel consumption at endurance power, lbs/SHP-hr
SFCH	specific fuel consumption at half power - SFCHHP in MAIN

FIGURE 15: LIQ SUBROUTINE FLOW CHART



SHCM	specific fuel consumption at maximum power - SFCMHP in MAIN
SHPH	one half of maximum shaft horsepower
VE	endurance speed, knots - VEND in MAIN

6.8 Subroutine MACHBX

6.8.1 Purpose and Approach

Based on the machinery type selected, the shaft horsepower and the ship dimensions, the location and dimensions of the prime mover and power transmission machinery spaces are estimated and assigned. If the machinery space dimensions are input, this routine is not executed.

There is very little data available on SWATH machinery spaces. Table V summarizes available data. Because of the lack of data, the approach to this routine has been a best reasonable estimate taking into account obvious volume requirements of the machinery but doing few calculations. The results are therefore only estimates to be used in the remainder of the program.

6.8.2 Input List for Subroutine MACHBX

BS LC(GG)	MTYPE LC(CC)
DB LC(JJ)	SHPM LC(CC)
DH LC(GG)	

6.8.3 Program Development

Subroutine MACHBX proceeds from several important assumptions. First the feasible range of ship dimensions and required horsepower given in the limits of Subroutine XECUTE eliminates combinations of

TABLE V
MACHINERY SPACE DATA

MACHINERY PARAMETER	SHIP			
	3	6	18	24
Machinery Type	3	3	3	3
Location Prime Mover	Hull	Hull	Box	Hull
Location Aux. Space	Hull	Hull	Hull	2nd Dk Bx
	Hull	Hull	Hull	2nd Dk Bx
	Box	Box	Box	
Dimensions Prime Mover (L x W x D) FT	56x19.2x19.2	56x19x19	40x51x9	35x15x15
Dimensions Aux. Space	32x19.2x19.2	40x19x19	80x13x13	43x20x9
	32x19.2x19.2	40x19x19	80x13x13	43x20x9
	96x54x9	96x60x9	40x46x9	
Volume Machinery Spaces	103621	110814	74850	27850
Volume Aux. Spaces (cu. ft.)	66561	74522	37664	15480

Volume Machinery Spaces = Total Machinery and Auxiliary Machinery Spaces, Both Hulls Plus Box.

design variables which are not feasible and prevents further execution of the program. If a feasible set of ship dimensions has been generated and the machinery space dimensions are not inputs, MACHBX is executed. Machinery may be located in the hulls, the struts or in the box of a SWATH. A code is used to determine where parts of the propulsion system are located. MBLOC1 is the code for the transmission and propulsor device, that is, the gears shafting and propeller or the electric motor, shafting

and the propeller. MBLOC2 is the code for the prime mover. A value of 1 for these codes implies that the machinery system part is in the hull; a value of 2 for these codes implies that the machinery system part is in the box. Thus, MBLOC2=1 implies that the prime mover is in the hull. The only valid value of MBLOC1 in this model is MBLOC1=1; the propeller, shaft and gears must be in the hull. When electric propulsion is specified, the model assumes that the prime movers are in the box and the motors in the hulls. For Diesel propulsion the model assumes that the prime movers will be in the box if the required horsepower exceeds 7000 and that a gear and shaft system will transfer the power to the hulls. This model assumes that there will always be a large auxiliary machinery space located in the box which will be used for generators and auxiliary machinery. The data in Table V indicate the size of previous SWATH auxiliary spaces. The requirements for auxiliary spaces are satisfied in Subroutine VOLUME.

Specific assumptions made in the routine for expressing the machinery space dimensions are functions of horsepower, machinery type and geometry too. The minimum power transmission space length is taken as 25 feet and the height and width of that space are the diameter of the hull. The minimum length for a Diesel engine space is assumed to be 28 feet. For electric propulsion requiring more than 30000 horsepower, it is assumed that two motor armatures will be mounted on a common shaft and the length of the power transmission space is doubled. To determine the required length of gas turbine engine spaces, a curve was constructed expressing the length of gas turbine engines as a function of horsepower and adding 10 feet to account for ducting. The equation for the length of gas turbine is:

$$\text{LENGTH} = 10. + .00048 * \text{SHP}$$

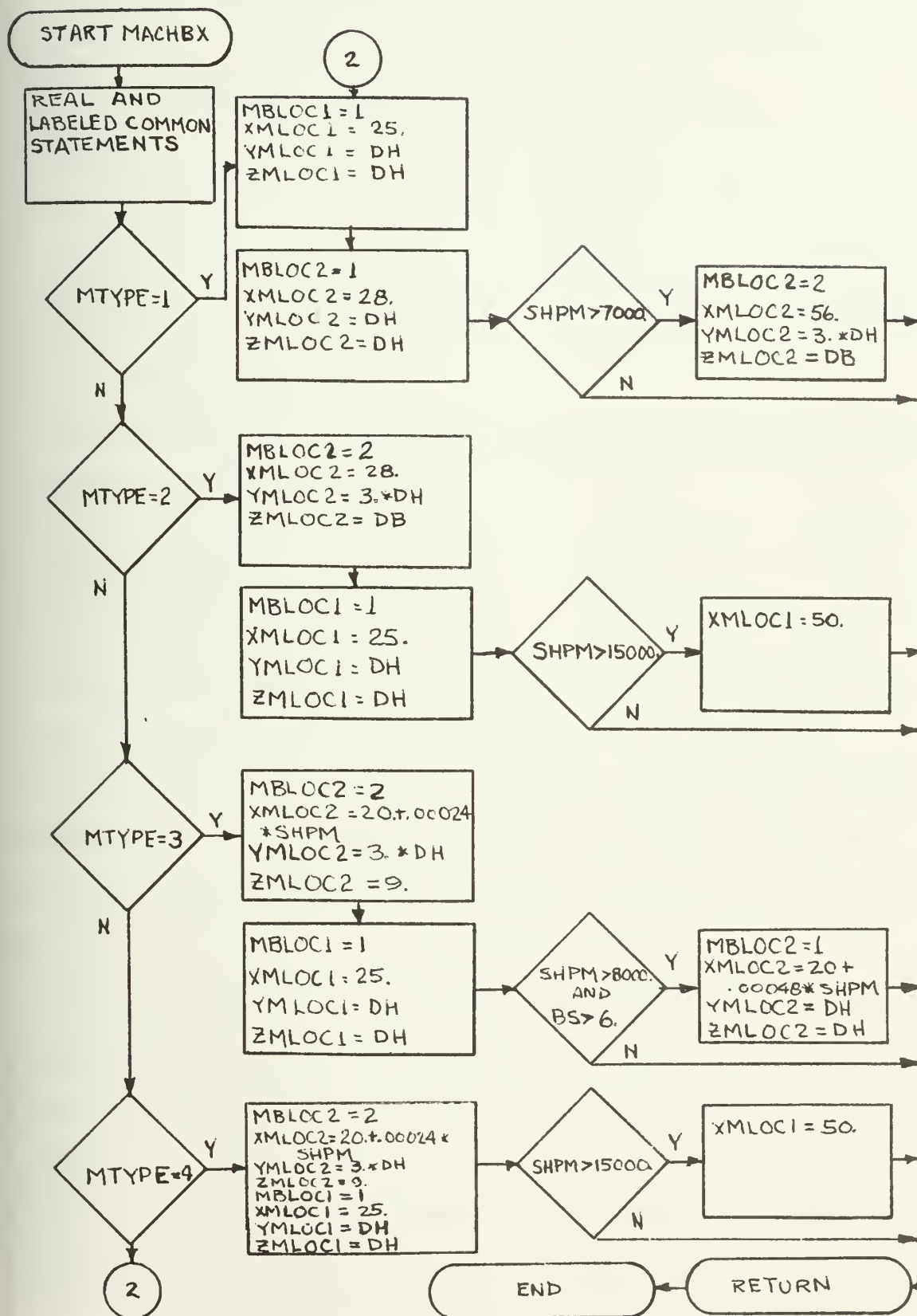
When corrected for the total shaft horsepower and for ducting the form of the equation used in the model is:

$$\text{XMLOC2} = 20. + .00024 * \text{SHPM}$$

Additional allowances are made for large gas turbine engines in the hulls. The program also assumes that small gas turbines are located in the box and drive the propulsor through a gear or chain drive. If the gas turbine total horsepower exceeds 8000 and the width of the strut is sufficient to provide for access and removal, 6 feet, then the gas turbine is placed in the hull. An analysis of rough arrangements of three Navy designs indicated that the dimensions of machinery spaces in the box could be approximated by setting the machinery space length equal to the Diesel engine minimum for Diesel propulsion or to the gas turbine length estimated above, the machinery space width could be approximated by three times the hull diameter and the height could be set equal to 9 feet for gas turbines and the box depth for Diesels.

The subroutine first tests to determine the type of machinery which has been specified and directs execution of a series of statements which estimate the dimensions. Within each set of dimension-estimating statements, tests are carried out on the geometry and horsepower to determine whether the estimates should be modified before completion of the routine. The length, width and height dimensions for the two machinery spaces are calculated and stored in a common storage location.

FIGURE 16: MACHBX SUBROUTINE FLOW CHART



6.8.4 Flow Chart

A flow chart for the MACHBX routine is shown in Figure 16.

6.8.5 Output List for Subroutine MACHBX

MBLOC1.	LC(JJ)	YMLOC1.	LC(QQ)
MBLOC2.	LC(JJ)	YMLOC2.	LC(QQ)
XMLOC1.	LC(QQ)	ZMLOC1.	LC(QQ)
XMLOC2.	LC(QQ)	ZMLOC2.	LC(QQ)

6.8.6 Nomenclature List

All variables used in this routine have the same definitions listed in the MAIN program.

6.9 Subroutine VOLUME

6.9.1 Purpose and Approach

Many modern ships are volume limited rather than weight limited. However, the SWATH ship is more likely to be weight limited than volume limited due to the large box-like cross structure of the box and the lack of waterplane area for controlling sinkage and trim. This subroutine balances the volume required and the volume available for the SWATH ship.

The basic dimensions of the entire ship have already been determined in Subroutine DIM. Subroutine VOLUME checks for the arrangement of various volume groups and increments the number of decks in the box or adjusts the deckhouse volume to attain a volume check. The volume groups are divided among the components of the ship. Hull volume, strut volume, box volume, deckhouse volume and total volume are computed

separately and then summed. It is assumed that the hulls may be used for machinery spaces, liquid tanks, steering gear and control fin actuator spaces only. The struts are assumed to have one useable platform over 75 percent of the length, access spaces, uptakes and fuel overflow tanks. The remainder of the volume in the struts is assumed to be inaccessible voids. The box volume is assumed to be used for arrangements and for machinery spaces. The box is provided with a double bottom which is not available for arrangements. The deckhouse is assumed to contain the pilothouse, Combat Information Center, Captain's Quarters and all areas specified in the input of payload, armament and electronics equipment which were to be in the deckhouse. No sheer is assumed. No raised decks may be added over a fraction of the length of the box; a complete deck must be added for structural reasons. The assumed deck height is 9 feet. The requirement for addition of a complete deck if a space balance cannot be achieved by varying the deckhouse size alone means that there is a step function of volume and that it is likely that excess volumes will be produced by this model.

6.9.2 Input List of Subroutine VOLUME

AG	LC(JJ)	DH	LC(GG)
AREADH	LC(BB)	H	LC(GG)
AREAHL	LC(BB)	JOPT.....	LC(CC)
BBOX	LC(GG)	LEN	LC(BB)
BS	LC(GG)	MBLOC1	LC(JJ)
CWP	LC(GG)	MBLOC2	LC(JJ)
D	LC(AA)	NCPO	LC(AA)

NENL.	LC(AA)	XLS.	LC(GG)
NOFF.	LC(AA)	XMLOC1	LC(QQ)
WACFUL	LC(LL)	XMLOC2	LC(QQ)
WTFUEL	LC(LL)	YMLOC2	LC(QQ)
WTLO	LC(LL)	ZMLOC2	LC(QQ)
XLB	LC(JJ)		

6.9.3 Program Development

The SWATH ship dimensions determined by Subroutine DIM and input to this subroutine are average SWATH dimensions based on previous design studies. These dimensions and the assumptions made completely determine the enclosed volume except for the deckhouse volume variable and the number of decks variable. The deckhouse volume is computed early in the routine and adjusted to attain a volume check. To do this, the maximum value of deckhouse volume based on previous SWATH designs is used as an upper limit. Deckhouse volume is constrained by stability requirements and secondarily by required deck area on a conventional ship. In a SWATH configuration the stability requirement and the deck space requirements are not as controlling because of the wide spacing of hulls and wide rectangular decks. Deckhouse volume limitations have been included in this model and are shown in Figure 17. The program starts by assuming the maximum deckhouse volume in the range: $DHV = .007 * LEN^3$ and if the volume available which is computed at the end of the program is excessive, the deckhouse volume is reduced as necessary down to the minimum value of $DHV = .000223 * LEN^3$. The minimum line used by Goodwin, $DHV = .000151 * LEN^3$, is also shown on Figure 17. If the required volume is not sufficient with the maximum

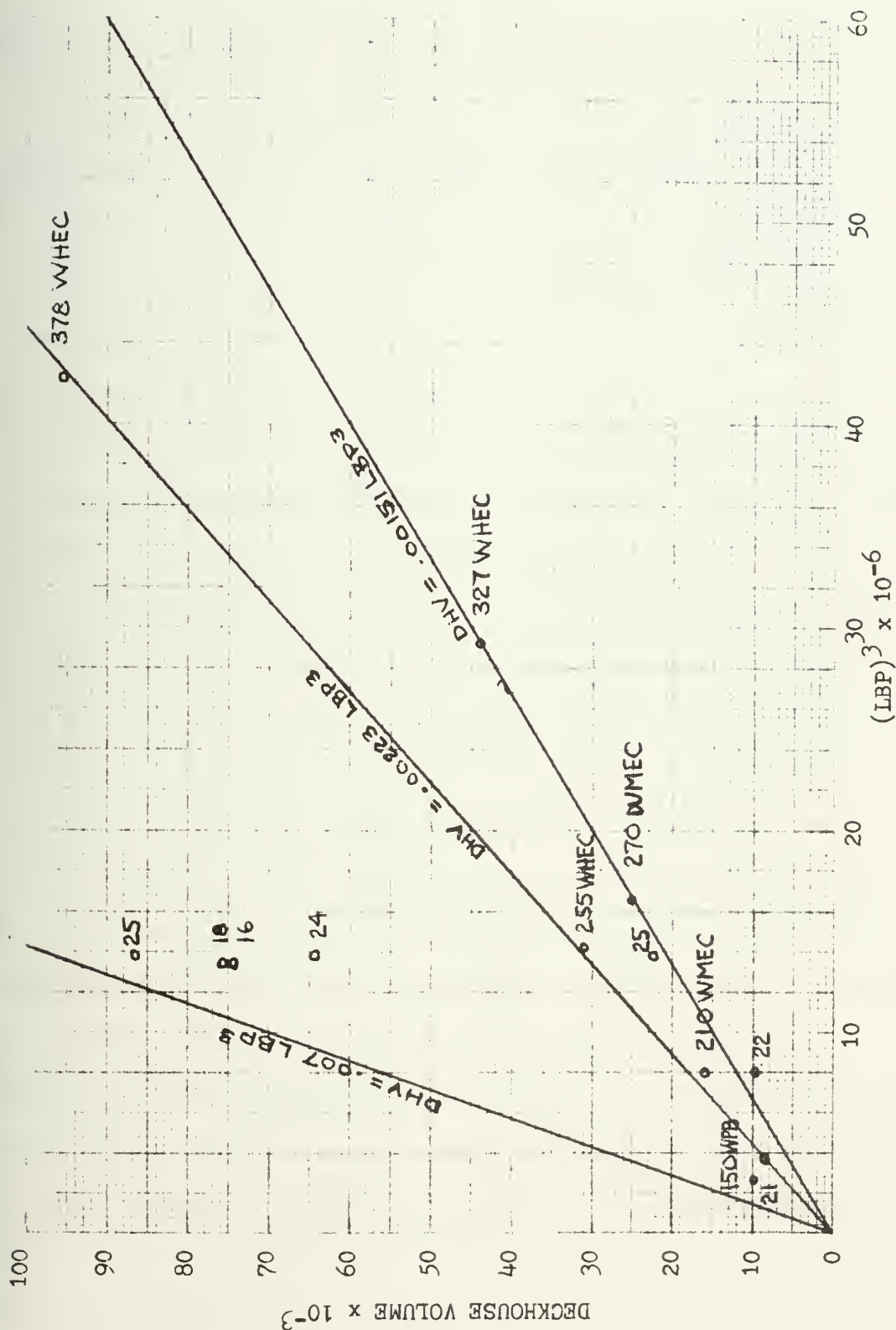


FIGURE 17: DECKHOUSE VOLUME VERSUS (LBP)³

deckhouse size, the program will increment the number of decks and recompute the areas. A maximum limit of two decks in the box is allowed.

The program proceeds through the calculation of volume in the following manner. First the hull volume is recomputed. Then the liquid volumes are computed and multiplied by a factor of 1.2 to account for structure, expansion and overflow. The volume of machinery spaces is next computed. The total volume of the ship is computed and the deckhouse volume is subtracted from this number to determine the cubic number which is used as a variable in sizing the steering machinery and fin control actuator spaces. Based on limited SWATH data and recalling that the SWATH requires a rudder for each hull and a number of control surfaces for motions control, the deck area for steering gear is taken as three times that used in the cutter model and the volume of steering gear is taken as the deck area times deck height. The required volume of the hulls is the sum of tankage volume, steering gear volume and any machinery space volume to be placed in the hull. If the hull volume is insufficient, liquid overflow tanks are allowed to fill up to 30 percent of the strut volume. It is not expected that this liquid overflow tank alternative will be used but it is provided as a safety feature in the program. After the hull volumes are checked, the required deckhouse area is computed and checked with the available area. If the requirements are larger than the available area the program returns an error message. Otherwise the program computes the arrangements area of the struts and the box and adds this arrangement area to the area in the deckhouse to determine the total available arrangements area.

The next section of the routine lists the estimating relationships used for computing the required areas for each of many ship functional areas. In general the relationships developed by Goodwin from Coast Guard Cutter data have been retained in this model, however several adjustments have been made to reflect SWATH differences or more modern data. The first exception to the Goodwin relationships comes in computing the area required for other stores, OSDA. Recent data and an apparent trend towards shorter endurance periods and more land-based support indicates that Goodwin's values are excessive and 75 percent of these values are used in this model. A study of the machinery space requirements of a SWATH indicates that the size of auxiliary machinery spaces is larger than for a conventional ship. A correction for this was considered in the MACHBX subroutine preparation and the expression $AUXVOL = 13178 + .4755 * SHPM$ was derived. Further study showed that auxiliary spaces are strongly dependent on ship volume and a relationship similar to Goodwin's but increased by a factor of approximately two was found to fit the data well. Therefore the expression

$$AMDA = .0097 * CN$$

was used in this model. SWATHs appear to require more deck area in passages than conventional ships; a passageway factor of 10 percent is used in this model. Repair lockers are fixed at 145 square feet of deck area in this model. Uptakes and access to the hulls are sized if the machinery specifications are not input. If the prime movers are in the hulls, 700 square feet is allotted to uptakes; if the prime movers are in the box, 200 square feet are allotted to uptakes. If the prime movers

are in the box, space is reserved for machinery in the box arrangement by the expression

$$VMXA = VMX/9.$$

SWATHs require additional space for mooring stations near the sides of the ship at the dock level; in general lines cannot be handled exclusively from the main deck. The model allows for additional mooring station space as

$$WSDA = 5.*LEN-475.$$

After all requirements have been computed the total required area is calculated and compared against the available area. If the area available is too small, the deck increment is added and the routine recycles; if the available area is too large, the deckhouse volume is reduced until a balance is reached or the minimum deckhouse size is reached. At this point the volume balance is completed and control is returned to XECUTE.

Data for space allocation which forms the basis for the estimating relationships used in subroutine VOLUME is shown in Table VI. This data includes some data used by Goodwin and new data from SWATH design and Coast Guard conventional design. Figures 18 through 22 show the linear relations developed for estimating areas.

6.9.4 Flow Chart

A flow chart of the VOLUME routine is shown in Figure 23.

TABLE VI
ARRANGEMENT AREA DATA

CATEGORY	378 WHEC	327 WHEC	270 WMEC	210 WMEC	240 AGOR SWATH
Office Spaces	493	465	432	130	266
Messing Facilities	2713	2348	1771	1452	1491
Crew Special	725	609	482	324	599
Officer Staterooms	1157	1338	983	567	1956
Officer Sanitary	243	133	181	193	345
CPO Staterooms	1040	364	418	283	270
CPO Sanitary	250	100	168	75	66
Crew Berthing	3641	2655	1097	1658	2300
Crew Sanitary	716	444	530	384	530
CO Stateroom & Cabin	697	511	204	406	336
CO Pantry	58	128	-	-	-
Commissary Stores	600	724	160	480	501
Other Stores	3015	2354	1780	1294	1681
Workshops	1161	818	954	544	176
Passages	2567	2588	2251	739	2481
Repair Lockers	148	18	183	110	180
Steering Gear & Windlass	736	548	739	270	2872
Chain Locker	47	30	33	42	56
A/C & Fan Spaces	369	324	239	165	462
I.C. & Gyro Room	312	143	-	180	442
Aux. Machinery Spaces	1860	1874	1532	820	4714
Uptakes (Hull)	462	1216	536	-	-
Pilothouse, Chartroom & C.I.C.	1125	856	730	422	1055
SUB TOTAL	24135	20588	15403	10538	22752
<u>EXTRAS</u>					
Crew Recreation Rooms	1445	-	1390	-	236
Cargo & Flume Tanks	1219	249	-	-	-
Electronics & Stores	1618	775	1384	319	-
Armament & Stores	844	822	451	280	-
Balloon Shelters	512	156	1074	-	-
Mission Offices & Labs	746	336	-	-	2418
Mission Workshops	-	-	-	105	1134
Bow Thruster	344	-	-	-	-
TOTAL	30863	22926	19704	11242	26540

Messing Facilities = Wardroom, Pantry, CPO Mess, Crew Mess, Galley, Scullery.

Crew Special = Sick Bay, Barbershop, Movie Locker, Laundry, Ship Store.

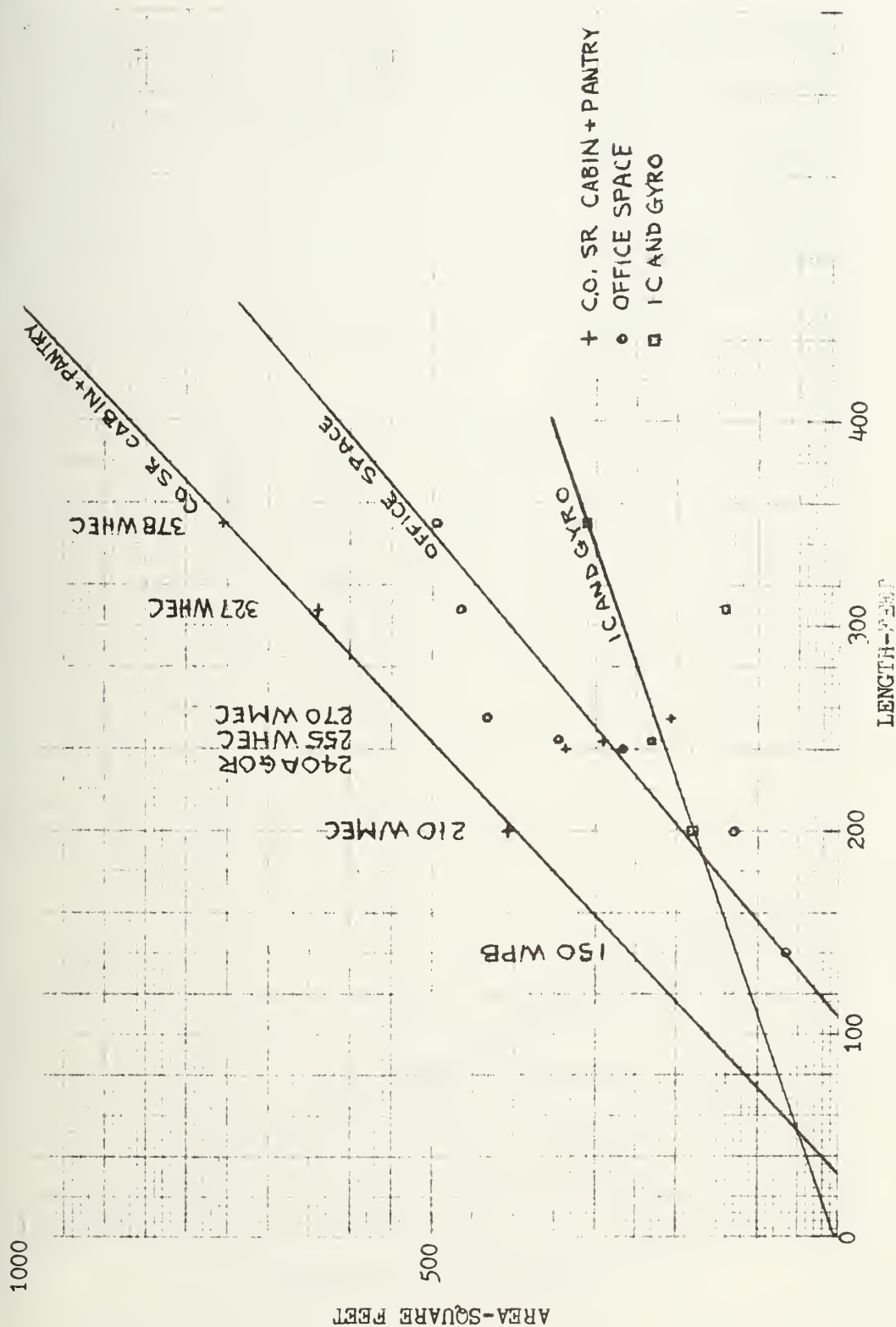
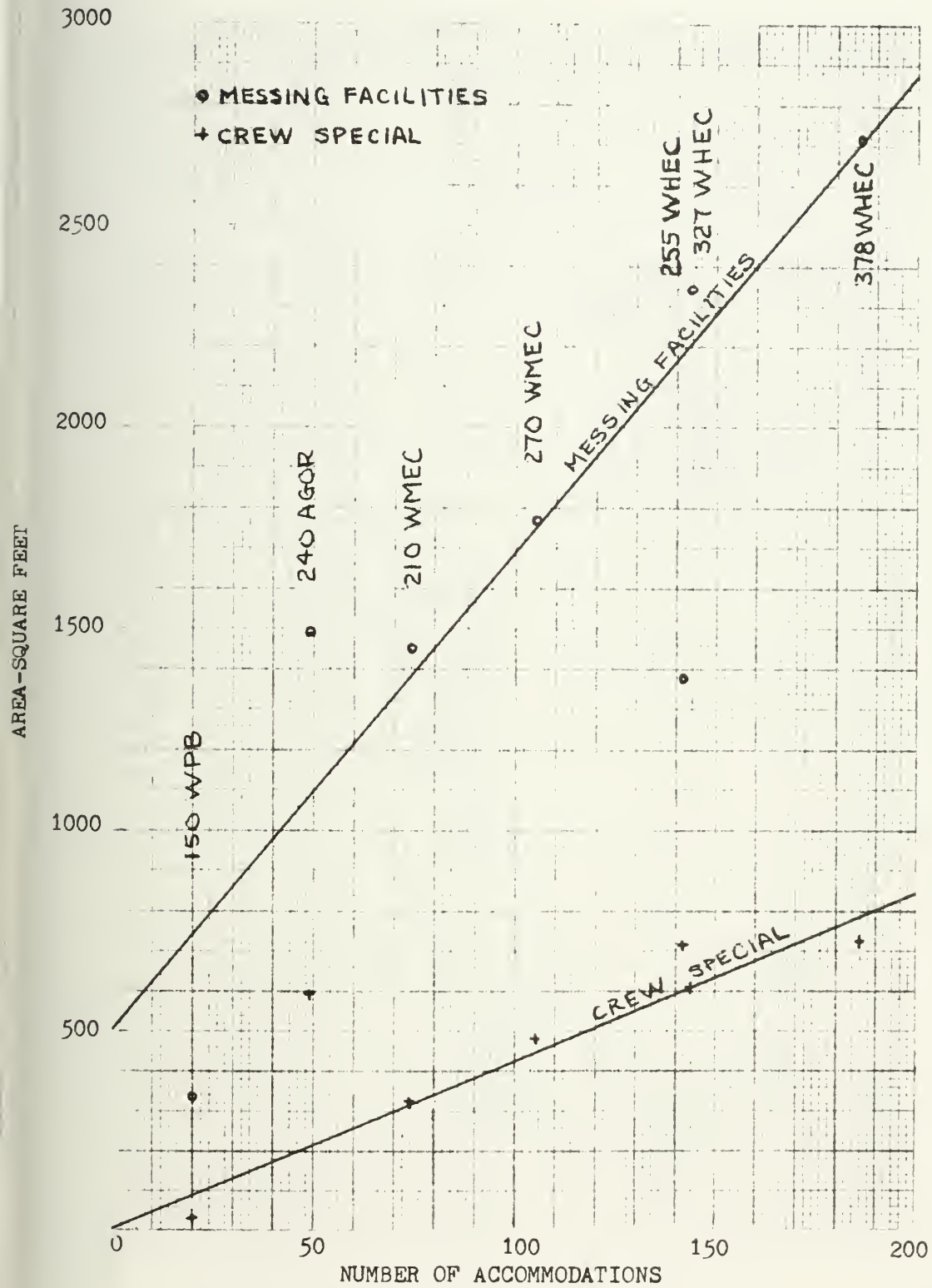


FIGURE 18: ARRANGEMENT AREAS

FIGURE 19: ARRANGEMENT AREAS



1000

AREA-SQUARE FEET

500

5

10

15

20

NUMBER OF ACCOMMODATIONS x ENDURANCE DAYS x 10⁻³

327 WHEC

378 WHEC

255 WHEC

240 AGOR

210 WMEC

270 WMEC

150 WPB

COMMISSARY STORES

SHIP	NAC	D
378 WHEC	186	90
327 WHEC	144	120
270 WMEC	105	30
255 WHEC	142	90
240 AGOR	49	60
210 WMEC	75	90
150 WPB	20	30

FIGURE 20: ARRANGEMENT AREAS

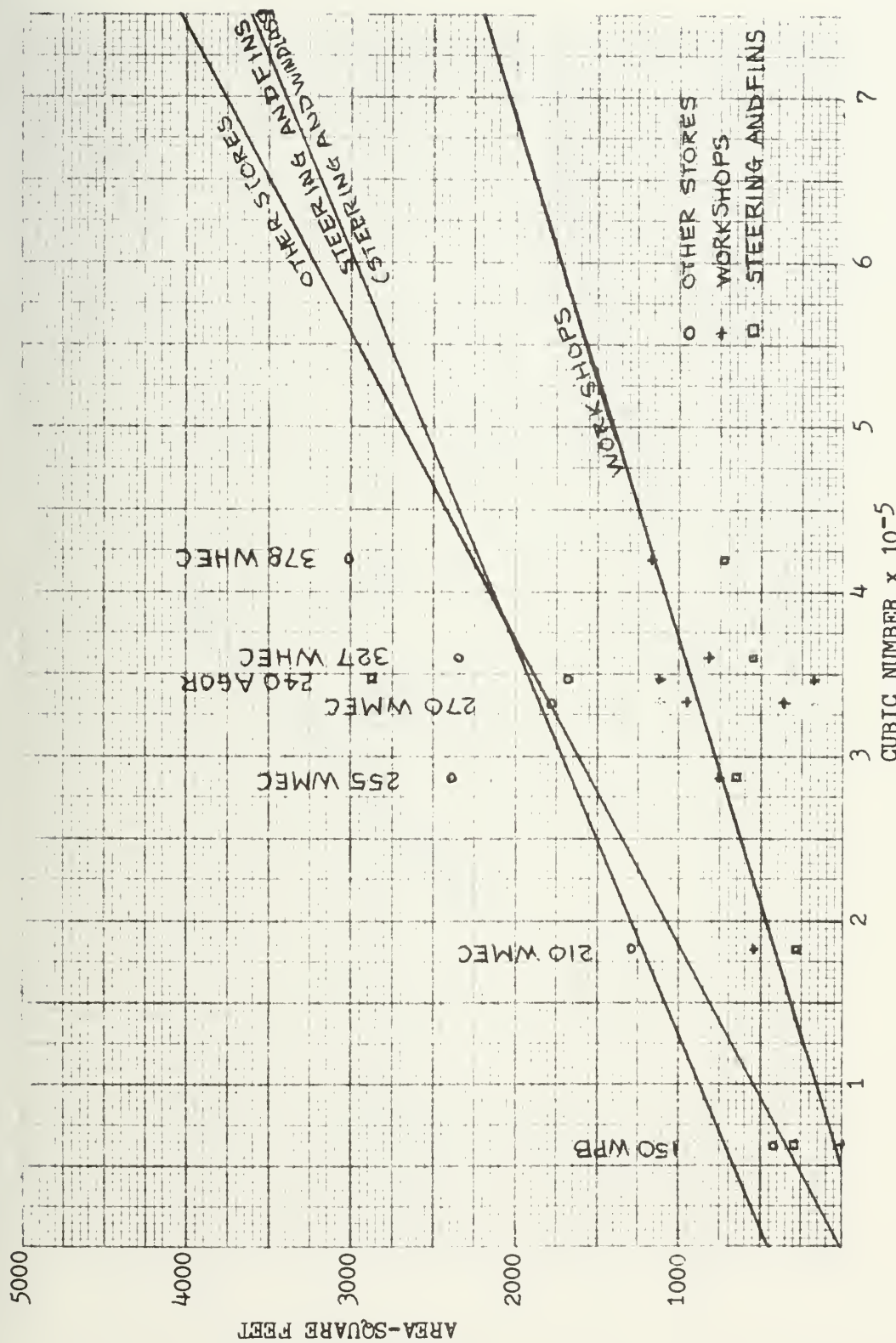


FIGURE 21: ARRANGEMENT AREAS

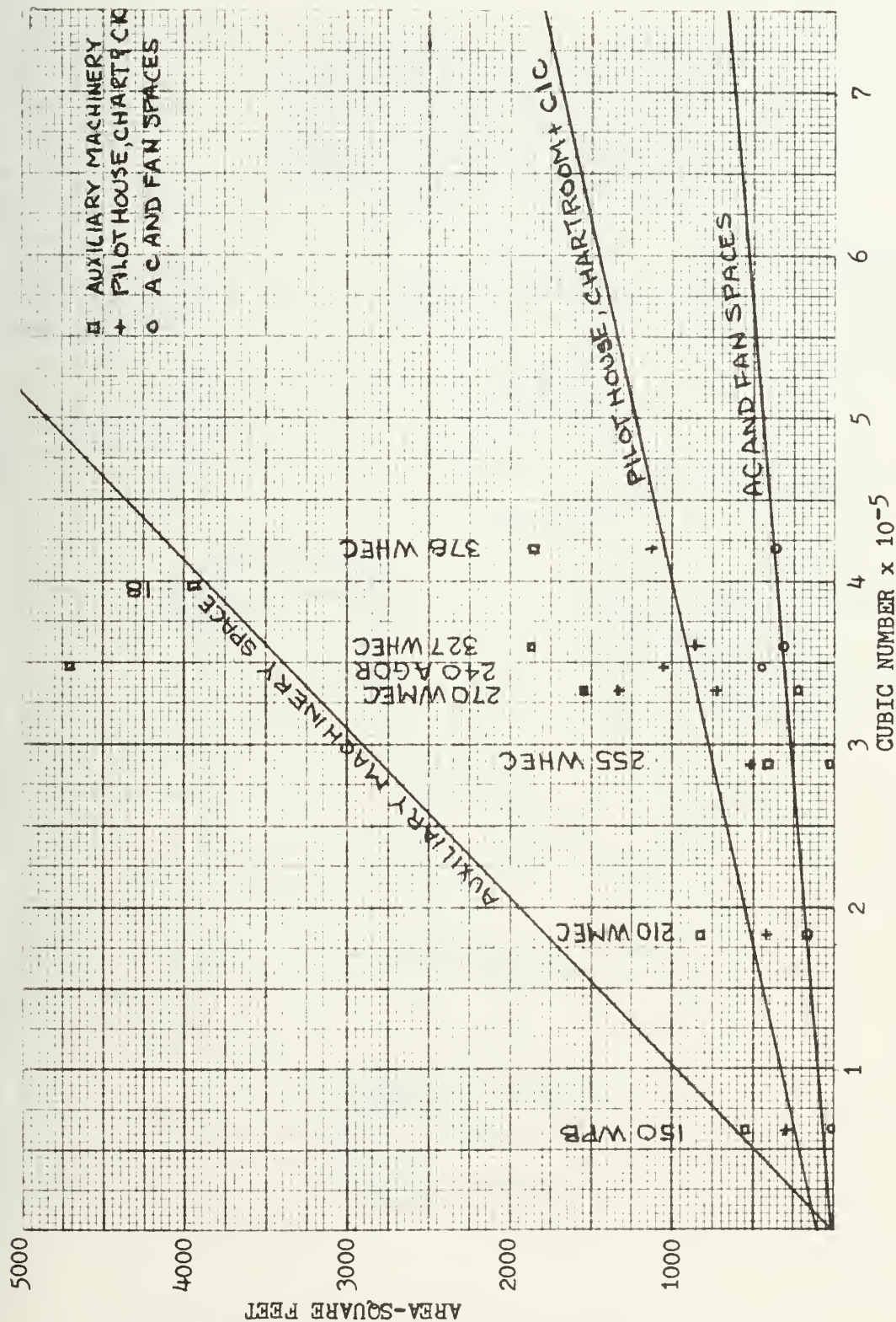


FIGURE 22: ARRANGEMENT AREAS

FIGURE 23a: VOLUME SUBROUTINE FLOW CHART

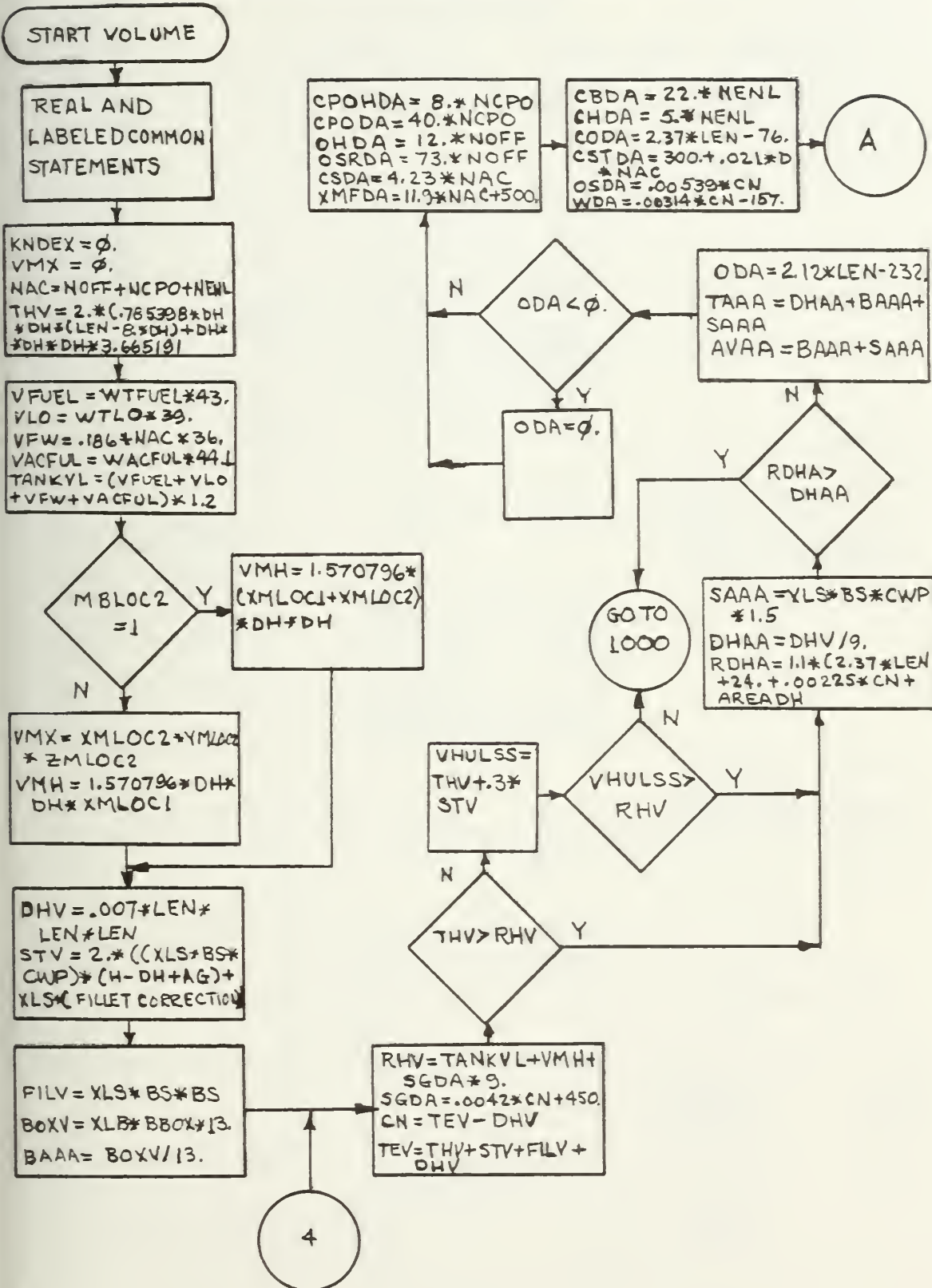
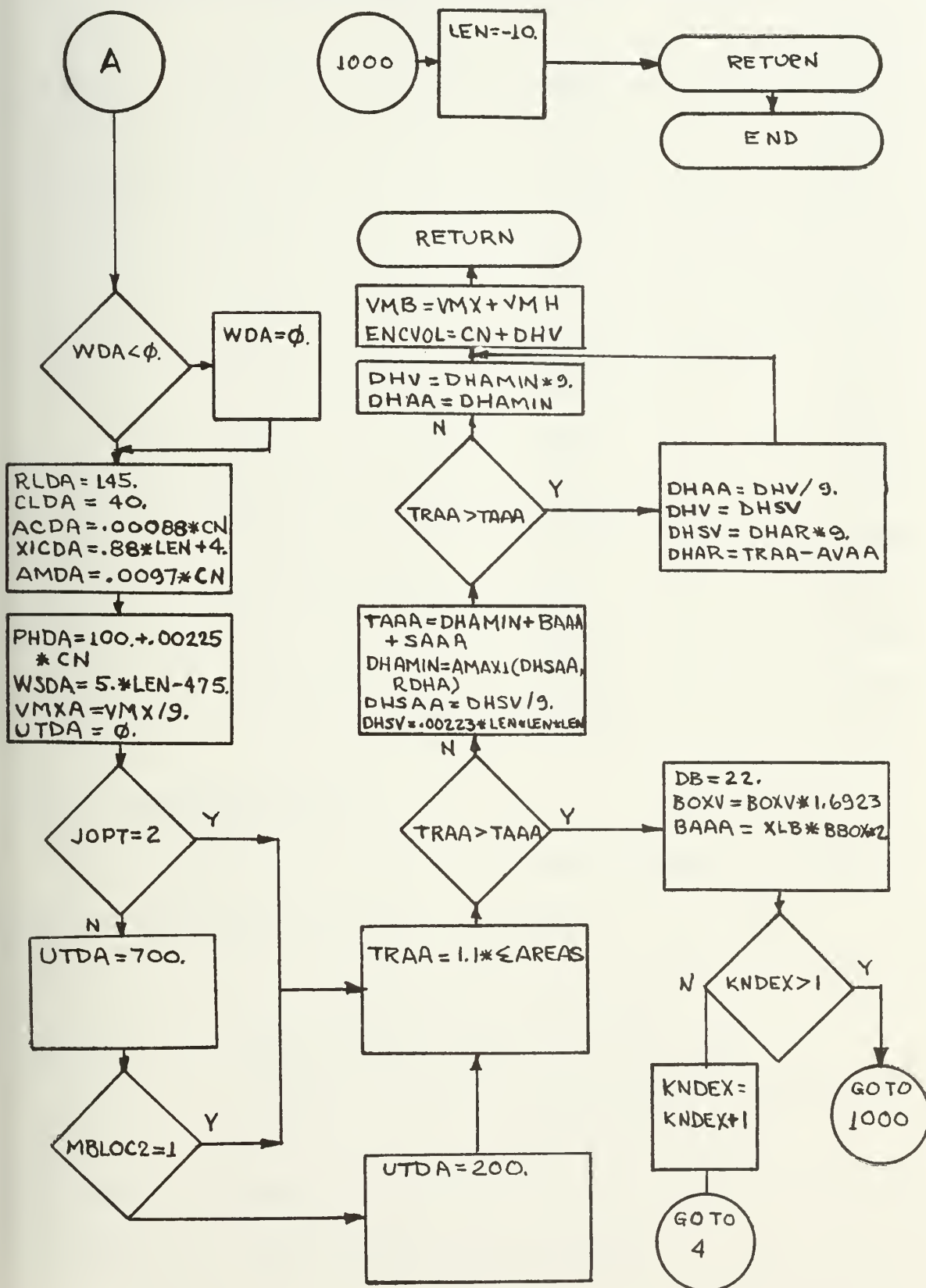


FIGURE 23b: VOLUME SUBROUTINE FLOW CHART-continued



6.9.5 Output List for Subroutine VOLUME

ACDA	LC(PP)	ODA	LC(PP)
AMDA	LC(PP)	OHDA	LC(PP)
AVAA	LC(PP)	OSDA	LC(PP)
CBDA	LC(PP)	OSRDA	LC(PP)
CHDA	LC(PP)	PHDA	LC(PP)
CLDA	LC(PP)	RLDA	LC(PP)
CN	LC(BB)	SGDA	LC(PP)
CODA	LC(PP)	TANKVL	LC(PP)
CPODA	LC(PP)	UTDA	LC(PP)
CPOHDA	LC(PP)	VMB	LC(PP)
CSDA	LC(PP)	VMXA	LC(PP)
CSTDA	LC(PP)	WDA	LC(PP)
DHAA	LC(PP)	WSDA	LC(PP)
DHV	LC(BB)	XICDA	LC(PP)
ENCVOL	LC(BB)	XMFDA	LC(PP)

6.9.6 Nomenclature List

The definition of all variables is the same as given in the MAIN program nomenclature except for the following:

ACDA	A/C & ventilation deck area, sq ft
AMDA	aux. machinery spaces deck area, sq ft
AVAA	available arrangements area in box and struts, sq ft
BAAA	available arrangements area in box, sq ft
BOXV	volume of box, cu ft
CBDA	crews berthing deck area, sq ft

CHDA	crew heads deck area, sq ft
CLDA	chain locker deck area, sq ft
GODA	C.O. S.R., Cabin & pantry deck area, sq ft
CPODA	CPO S.R. deck area, sq ft
CPOHDA	CPO heads deck area, sq ft
CSDA	crew special deck area, sq ft
CSTDA	commissary stores deck area, sq ft
D	stores endurance, days - ENDDAY in MAIN
DHAA	deckhouse arrangements area, sq ft
DHAMIN	minimum deckhouse area, sq ft
DHAR	deckhouse area required, sq ft
DHSAA	smallest deckhouse arrangements area, sq ft
DHSV	smallest deckhouse volume, cu ft
FILV	volume of strut - box fillets, cu ft
KNDEX	counter
NAC	number of accommodations
ODA	office deck area, sq ft
OHDA	officer heads deck area, sq ft
OSDA	other stores deck area, sq ft
OSRDA	officer staterooms deck area, sq ft
PHDA	pilothouse, chartroom & CIC deck area, sq ft
RDHA	area required to be in deckhouse, sq ft
RLDA	repair locker deck area, sq ft
RHV	required volume in hulls, cu ft
SAAA	available arrangements area in struts, sq ft
SGDA	steering gear & fins deck area, sq ft

STV	strut volume, cu ft
TAAA	total available arrangements area, sq ft
TANKVL	tankage volume, cu ft
TEV	total enclosed volume, cu ft
THV	total hull volume, cu ft
TRAA	total required arrangements area, sq ft
UTDA	uptake deck area in hull, sq ft
VACFUL	volume of aircraft fuel, cu ft
VFUEL	volume of ships fuel, cu ft
VFW	volume potable water, cu ft
VHULSS	volume of hulls and fraction of struts used for excess liquids, cu ft
VLO	volume of lub oil, cu ft
VMB	volume of machinery box, cu ft
VMH	volume of machinery in hulls, cu ft
VMX	volume of machinery in box, du ft
VMXA	deck area of machinery spaces located in box, sq ft
WDA	workshops deck area, sq ft
WSDA	mooring station deck area, sq ft
XICDA	I. C. & gyro room deck area, sq ft
XMFDA	messing facilities deck area, sq ft

6.10 Subroutine WEIGHT

6.10.1 Purpose and Approach

This subroutine estimates the weight of the ship to the one digit level or better based on the available data and provides weight estimates for a balance between full load weight and displacement.

The weight groups estimated by this routine are broken down according to the NAVSHIPS Hull Group Weight Classification of 1965 shown in Appendix D. This classification is used by the Coast Guard. Several of the weight groups are not estimated by this routine. Groups 4 and 7, communication and control and armament, respectively are given as inputs to the model. Group 2 will not be estimated by the routine if the machinery weight is an input. The liquid load weights have been previously calculated in subroutine LIQ. The remaining groups, 1, 2, 3, 5, 6 and loads are estimated in this routine.

Group 1 weights for the SWATH configuration are significantly different from the conventional ship. SWATH group 1 weight data was compiled and parametric studies used to determine the best combination of parameters to use to estimate weight conveniently. Data from SWATH machinery weight estimates, empirical weight estimation equations for group 2, data from other ship types and rough estimates of group 2 weights were combined to generate simple relations for group 2 weights. SWATH data and data from Coast Guard Cutters given by Goodwin were used to form relationships for groups 3, 5 and 6. The load assumptions used are the same as those used by Goodwin.

6.10.2 Input List for Subroutine WEIGHT

CN	LC(BB)	ELKW	LC(DD)
D	LC(AA)	ENCVOL	LC(BB)
DB	LC(JJ)	JOPT	LC(CC)
DBMAR	LC(WW)	LEN	LC(BB)
DHV	LC(BB)	MOPT	LC(CC)

MTYPE	LC(CC)	WCARGO	LC(LL)
MBLOC2	LC(JJ)	WTAC	LC(LL)
NCPO	LC(AA)	WTAMMO	LC(LL)
NENL	LC(AA)	WTFUEL	LC(LL)
NOFF	LC(AA)	WTG2 (JOPT=2 only).	LC(WW)
SHPE	LC(CC)	WTG4	LC(WW)
SHPM	LC(CC)	WTG7	LC(WW)
WACFUL	LC(LL)	WTLO	LC(LL)

6.10.3 Program Development

The basic approach of a weight estimating routine is to estimate the weight of each weight group in turn as a function of the variables which affect that weight group, to estimate the loads based on the crew size and operational requirements and to sum the group weights multiplied by a margin with the load weights to determine the full load weight. This is exactly what is done in this routine. Determining the proper variables and functional relationships to use in making the estimator may be difficult. Group 1 is estimated here as a function of the number of decks in the box, the material and ship dimensions. Group 2 estimating relationships are based on the location and type of machinery and the horsepower. Group 3 estimates are based on the installed generator size and the volume of the ship. Group 5 and 6 estimates are based on the enclosed volume of the ship. The following paragraphs indicate the methods of development of these estimating relationships.

Group 1 weight estimation for a SWATH is somewhat more complex than for a conventional ship due to the structural problem of connecting the two hulls through struts and a cross structure. Complex structural

analysis would be necessary to find the exact requirements for scantlings and weight. A structural analysis for each feasibility study is too complex and time consuming to be an acceptable solution. Therefore a method for estimating weights based on existing SWATH studies, some of which have had structural analysis or detailed structural weight estimates, was desired. The dimensions of the ship, the enclosed volume, the displacement, the number of decks and struts and the material used are all variables affecting the weight. Plots of group 1 weights versus length or cubic number as functions of number of decks and material are not suitable estimators. However, group 1 weights is strongly affected by the total area of structure in the ship as indicated by Arrone⁽²⁰⁾.

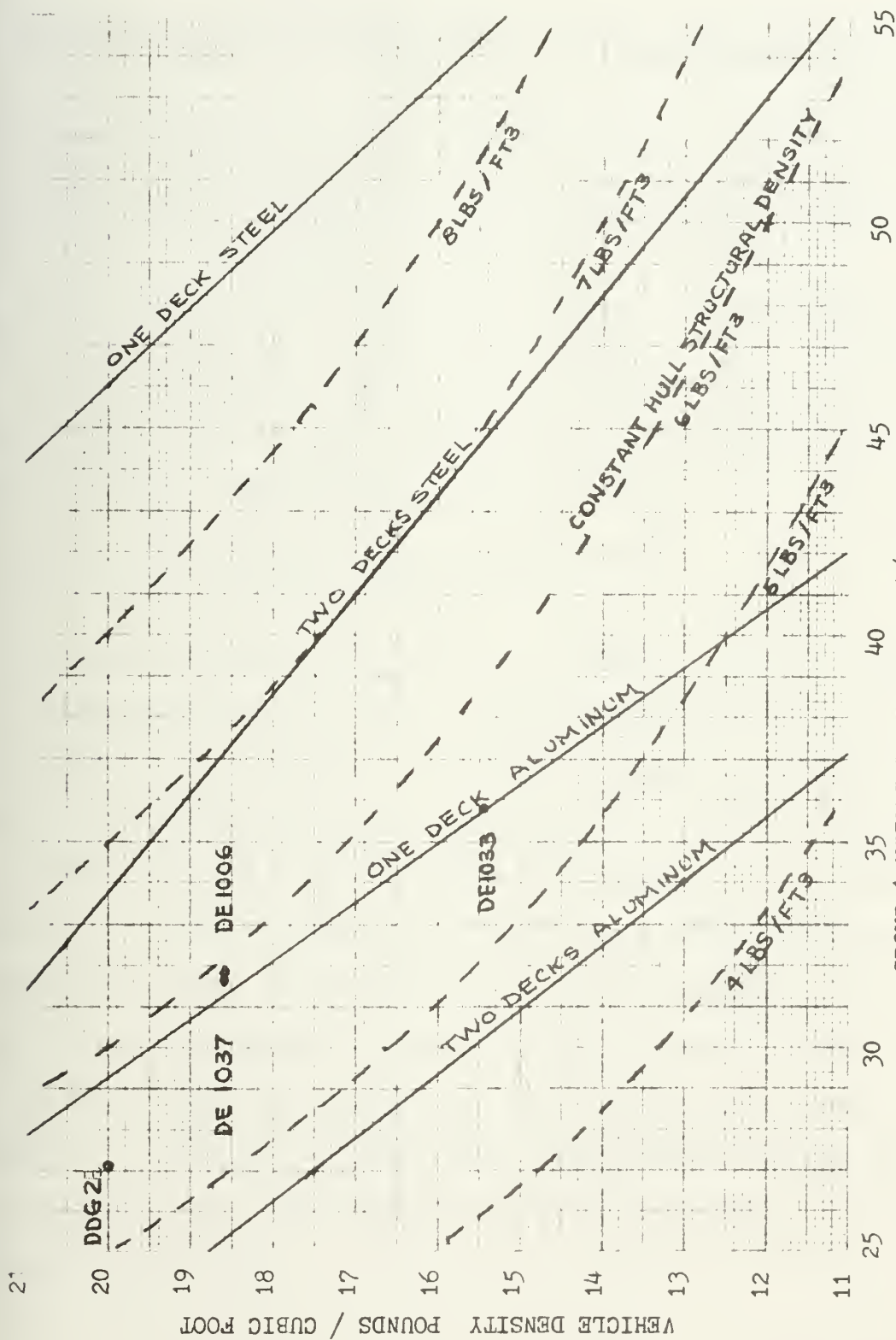
Approximate values of the surface of structure enclosing the ship were computed. The structural density of the ships were computed. A vehicle density versus group 1 weight fraction curve was plotted with cross curves of material and number of decks alternatives (Steel-one deck, Aluminum-two decks, etc.) and of structural surface area. Linear trend lines were plotted for four alternatives: two deck-steel, two deck-aluminum, one deck-steel and one deck-aluminum. Figure 24 shows these curves. These expressions are of the form:

$$\text{Weight 1/Displacement} = A(\text{Displacement/Enclosed Volume}) + B$$

To confirm this type of formulation equations for the displacement, volume and surface area for a hypothetical SWATH based on average dimensions were developed. For a two deck box these equations are:

$$\text{Displacement} = .00015707 * \text{Length}^3 \text{ Tons}$$

$$\text{Structural Surface Area} = 920 + 1.18777 * \text{Length}^2 + 121.01786 * \text{Length}$$



GROUP 1 WEIGHT FRACTION WTG1/DISPLACEMENT-PERCENT

FIGURE 24: VEHICLE DENSITY VERSUS WEIGHT GROUP 1 WEIGHT FRACTION

$$\text{Enclosed Volume} = 165.048 * \text{Length} + 6.196155 * \text{Length}^2 + .0054973 * \text{Length}^3$$

For a one deck box the surface area and volume equations are as follows:

$$\text{Structural Surface Area} = 560 + 102.01346 * \text{Length} + 1.18777 * \text{Length}^2$$

$$\text{Enclosed Volume} = 100.464 * \text{Length} + 3.935715 * \text{Length}^2 + .0054973 * \text{Length}^3$$

Based on scantling data from early Navy structural studies⁽⁸⁾, equations were derived for the average value of plate weight for the structure as a function of the number of decks, length and beam of the vessel and the material selection. These equations are of the form:

$$\text{Average Plate Weight} = c_1 * \text{Length} * \text{Beam} + c_2$$

The applicability of these equations must be limited to a range of values of the length times beam to remain consistent with the input data. By combining the equations for the average plate weight and for structural surface area, the weights of structure for hypothetical SWATH ships can be estimated. These data are then plotted on a vehicle density versus weight group 1 weight fraction curve and the results compared with the vehicle density curves previously prepared. The hypothetical values check well with the input data. This is not unexpected as the same data base was used for both calculation approaches, but it shows internal consistency. The linear estimating relationships derived estimate well in the mid-range of the length values accepted by the program, but over-estimate for small ships.

Two suggestions for estimating group 1 weights indicated in reference (3) were also evaluated. The first of these methods was a plot of weight fraction versus length. This estimator was discarded because it did not treat a sufficient number of assumed primary variables such as materials, decks and geometry. The second method evaluated was a plot of weight fraction versus displacement as functions of the material selection. Mean lines drawn through this type of data for high tensile steel SWATHs results in the following equation:

$$WT1/Displacement \approx 40 - .002 * Displacement, \text{ percent}$$

For aluminum construction with no allowances for structural fire protection the corresponding equation is:

$$WT1/Displacement = 27.29 - .001225 * Displacement, \text{ percent}$$

This approach leads to an error of more than twenty percent in estimating ships in the data base. Because of this error and its lack of attention to the primary dimension variables, this method of estimating group 1 weight was also discarded. The linear equations developed using the comparison of the data base and the hypothetical ship were used in estimating group 1 weights in this model. These relationships are shown in Figure 24. The equations developed from this figure and used in the model's calculation are:

$$WT1 = .82285 * DPTRY - 54.40049 * DPTRY * DPTRY / CN \text{ for two deck steel SWATHS}$$

$$WT1 = .542222 * DPTRY - 34.84444 * DPTRY * DPTRY / CN \text{ for two deck aluminum SWATHS}$$

$WT1 = .83335*DPTRY - 41.8151*DPTRY*DPTRY/CN$ for one deck
steel SWATHS

$WT1 = .577857*DPTRY - 32.000039*DPTRY*DPTRY/CN$ for one deck
aluminum SWATHS

where DPTRY is the displacement in tons and CN is the enclosed volume of the ship up to the main deck. These relationships include a 15 percent margin. Figure 24 also shows conventional destroyer data and lines of constant structural density for comparison.

Weight group 111 is estimated as a function of the enclosed volume of the deckhouse. The destroyer model DD07 uses the relationship $WT111 = .00085*DHV$. SWATH deckhouses are more box-like than those of destroyers and can make more efficient use of structure because of this shape. SWATH deckhouse weights are better estimated by:

$WT111 = .000353*DHV$

Estimates of machinery weight, Group 2, are made based on estimates of existing plants and previous ship synthesis model results. The entire weight group is estimated by one equation because the data inputs are not detailed enough to permit further breakdown. Conventional Diesel plants are estimated using data presented by Goodwin⁽¹¹⁾. Gas turbine plants are estimated from SWATH studies (8) and confirmed using a method developed by Reed⁽²³⁾ and suitably modified for SWATHs. Electric propulsion component weights are estimated from data in Harrington⁽²⁴⁾ and limited SWATH data is used for comparison. Only one data point is available for gas turbine electric plants. The estimating relationship is derived by estimating the component total weights over a range of horsepower and translating the resulting mean line until it passes

through the data point. Although the trends resulting from these estimators appear to be correct, the data base is limited. The estimating relationships are shown in Figure 25.

$WTG2 = .03754 * SHPM^{.925}$ for Diesel propulsion

$WTG2 = .1109828 * SHPM^{.86}$ for Diesel-electric propulsion

$WTG2 = .339053 * SHPM^{.634}$ for gas turbine propulsion

$WTG2 = .4777 * SHPM^{.692}$ for gas turbine-electric propulsion

There are two cases where the prime mover is located in the hull and power must be transmitted to the propulsor through a gear system in the struts. For these cases the group 2 weight is incremented to account for this extra transmission weight.

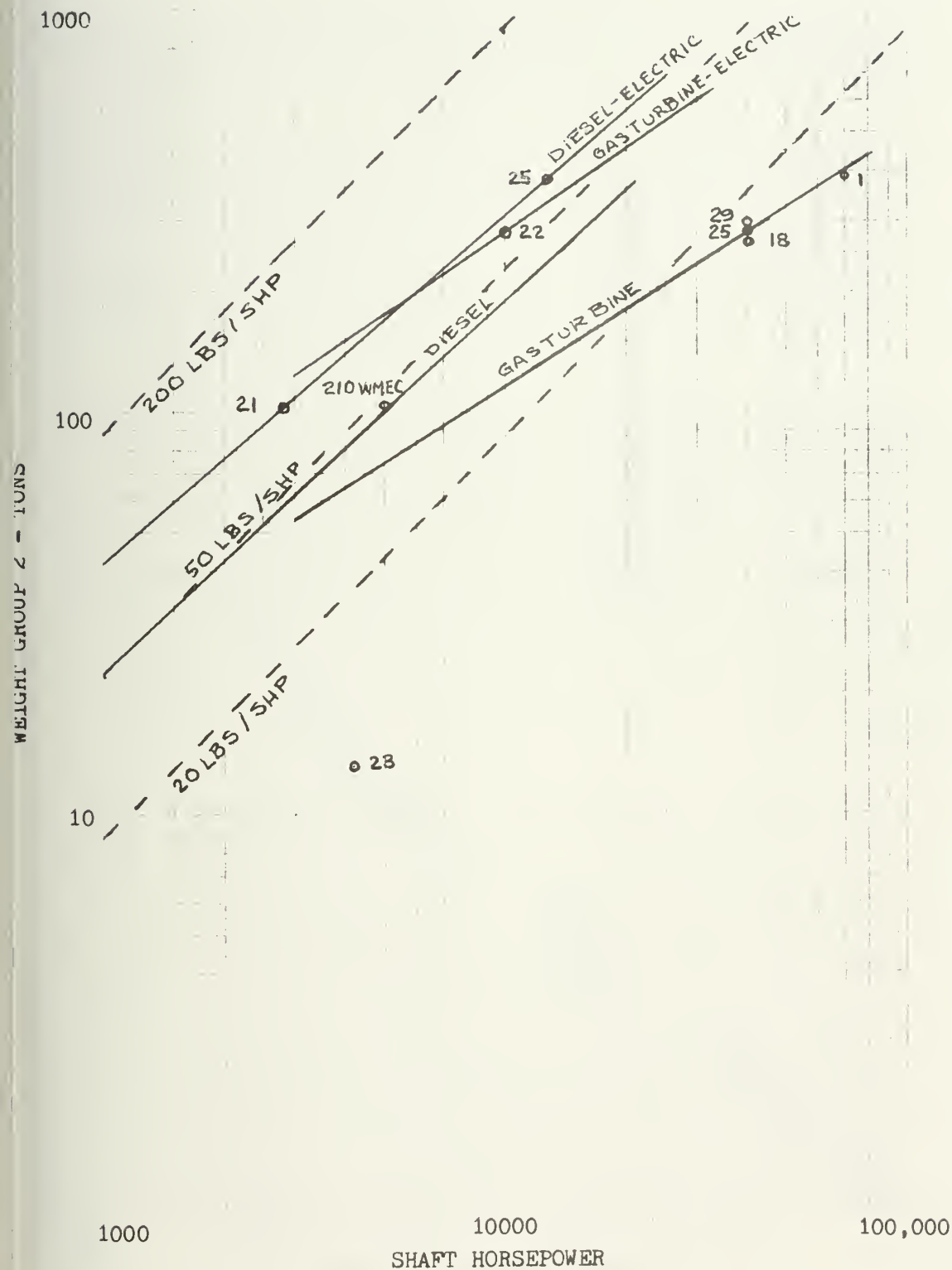
$$WTG2 = WTG2 + .001 * SHPM - 2.033, \text{ tons}$$

Goodwin's estimating relationships were used in this model for the electric power generation and power distribution switchboards classifications. Figure 26 shows the estimating relationship for power generation. The remainder of group 3 weight was estimated as a function of the enclosed volume. The total weight of this group is small and any inaccuracies in the estimates will have a small impact on the overall design.

$$WT3R = .0001534 * ENCVOL$$

Group 5 weight is estimated as a function of the enclosed volume. SWATH data indicate that the group 5 weight is of approximately the same functional relationship as the data compiled for conventional ships and

FIGURE 25: WEIGHT GROUP 2 VERSUS SHAFT HORSEPOWER



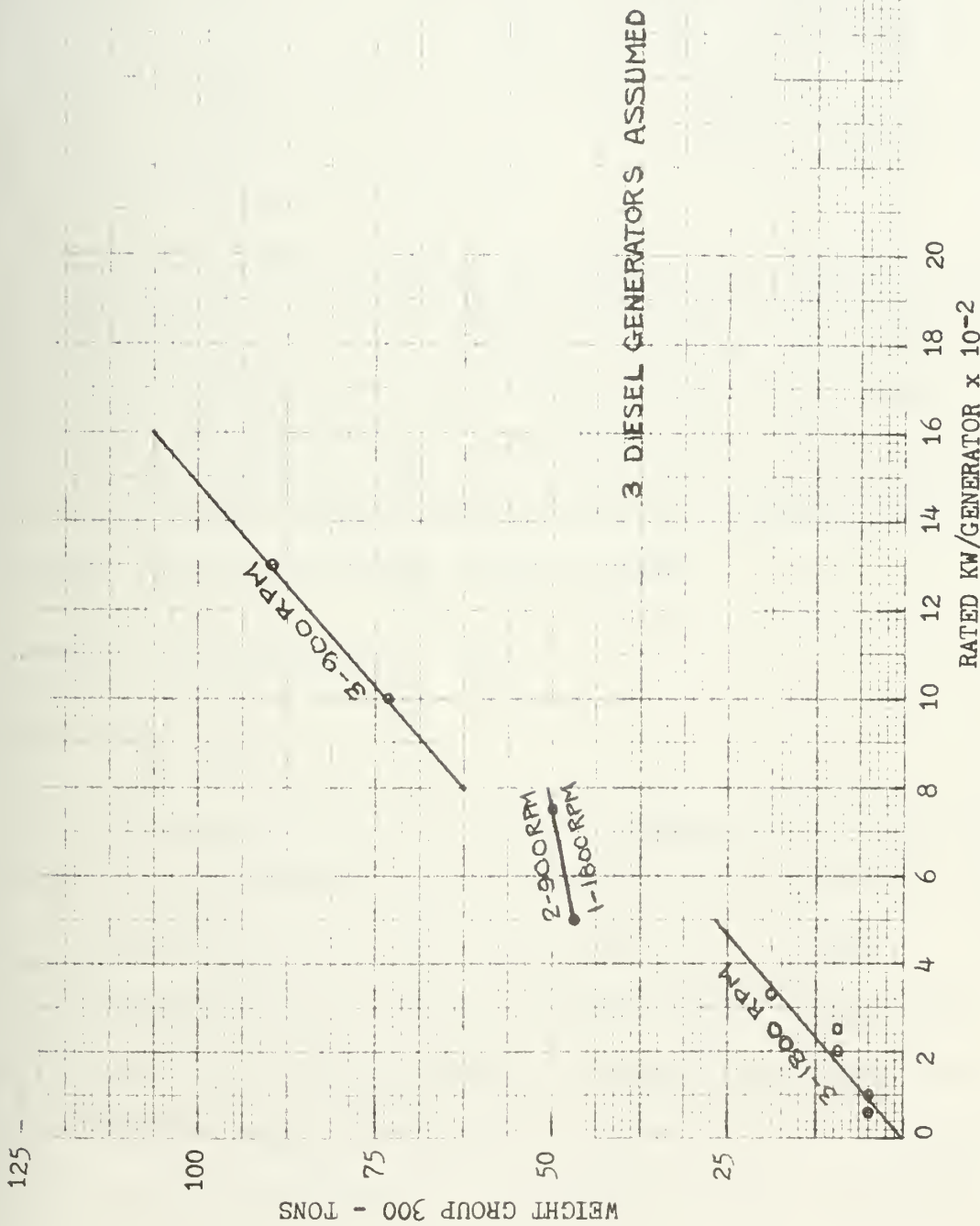


FIGURE 26: WEIGHT GROUP 300 VERSUS RATED KW/GENERATOR

given in DD07 and Goodwin but with a substantial weight reduction. Volume should be the most important variable for auxiliary weight but it is felt that the increase in weight should decrease with increasing volume and boxiness. The following equation for estimating group 5 weight is of the same form as that used previously for conventional ships but the coefficients have been reduced to agree with SWATH data.

$$WTG5 = .000023072*ENCVOL*ENCVOL + .00065456*ENCVOL$$

This relationship is shown in Figure 27.

Group 6 weight is also estimated as a function of enclosed volume based on SWATH data. No accounting has been made for fire insulation of aluminum hulls nor has an allowance been added for excess boats. One surfboat can be assumed for crews up to 25 and two such boats for larger crews. If more small boats are to be carried, they should be added as cargo items. The relationship for group 6 weight,

$$WTG6 = .05318*ENCVOL** .6266$$

is shown in Figure 28.

The light ship weight is determined by adding the five weight groups which have been calculated and the two, groups 4 and 7, which have been input and multiplying the sum by the design and builders margin.

The full load displacement is calculated by adding the light ship weight and the loads. The loads consist of the liquid loads calculated by Subroutine LIQ, the cargo, ammunition, aircraft and aircraft fuel inputs, crew, personal effects and stores. The crew is assumed to weigh 165

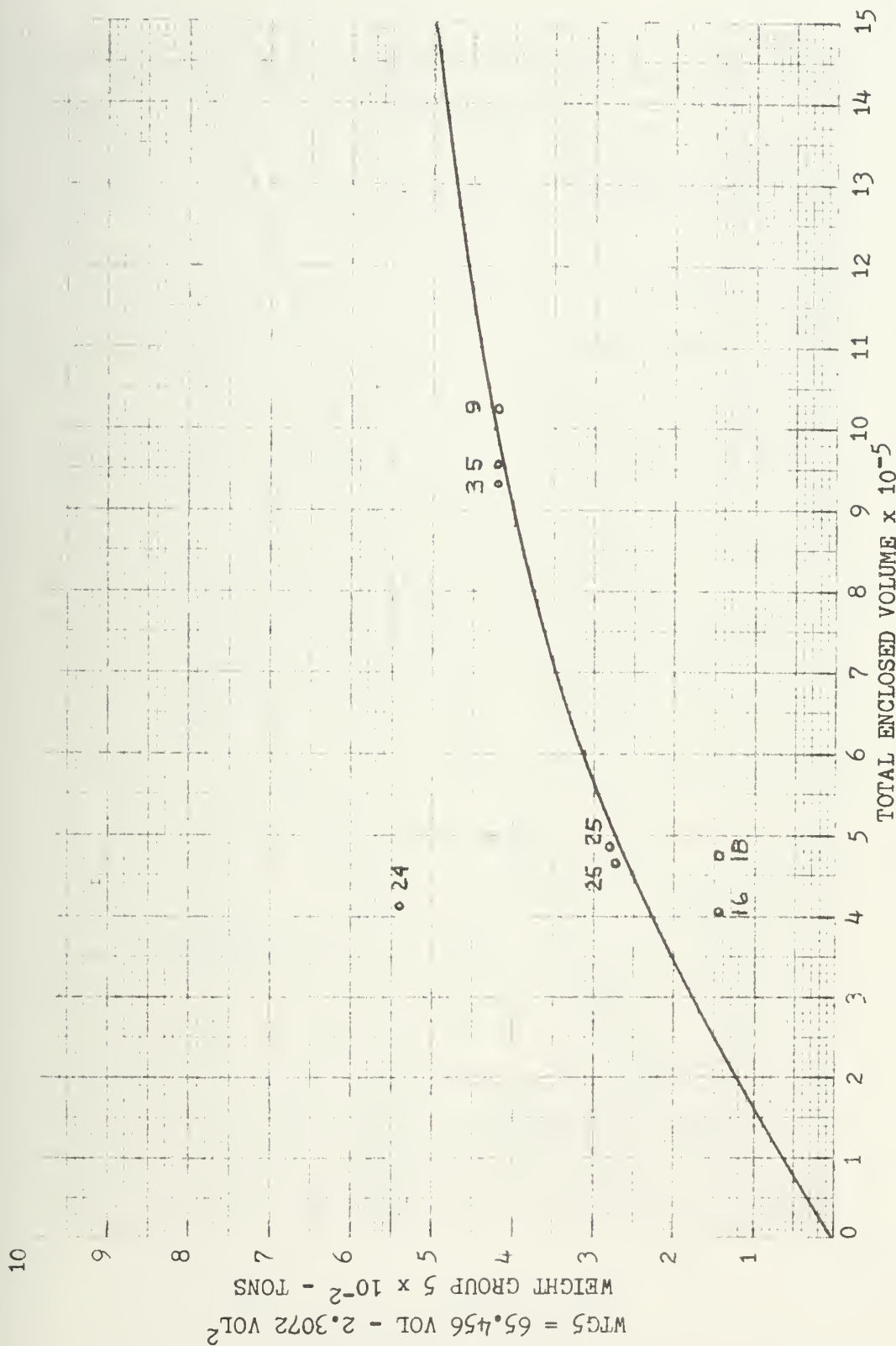


FIGURE 27: WEIGHT GROUP 5 VERSUS ENCLOSED VOLUME

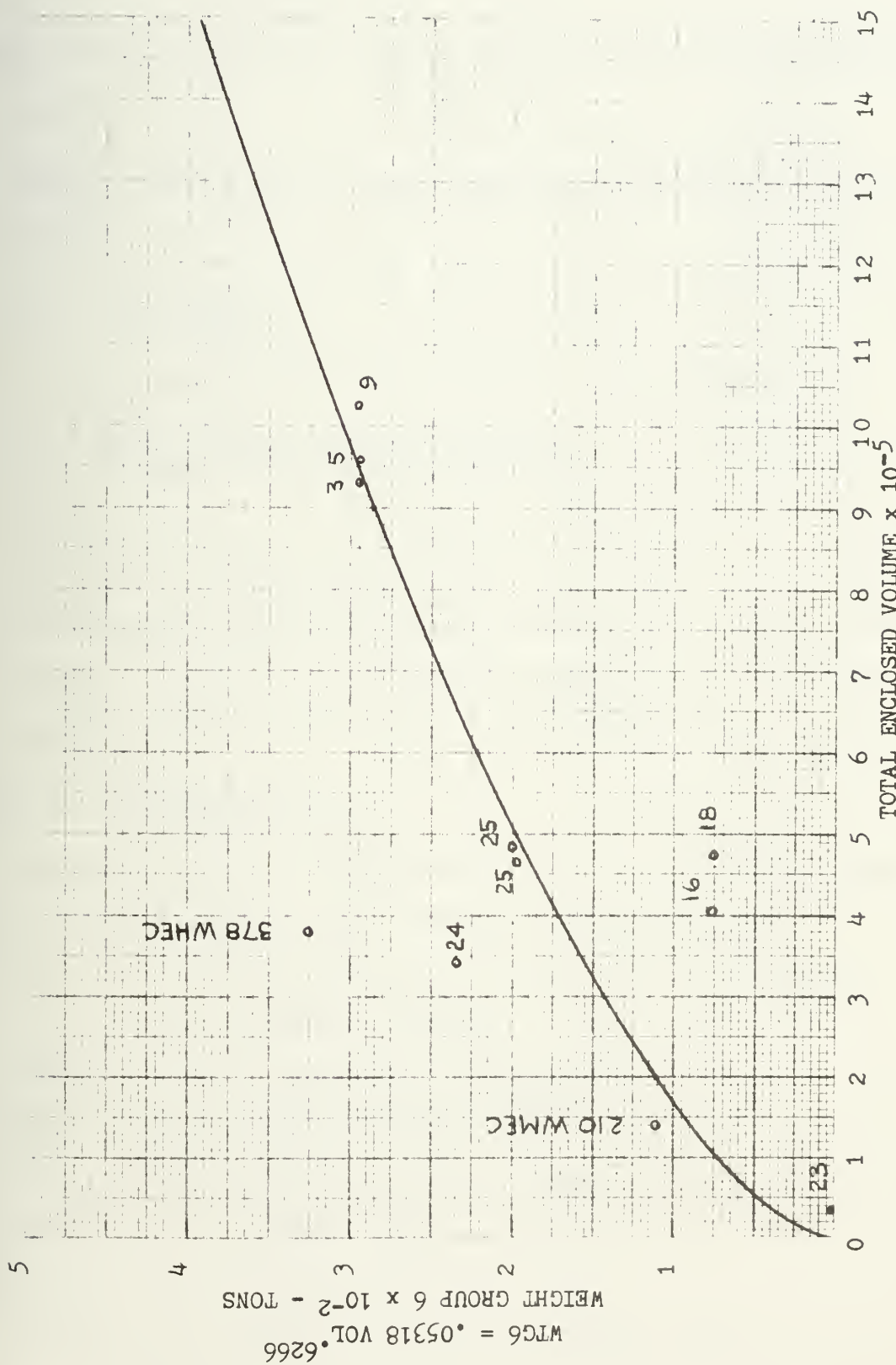


FIGURE 28: WEIGHT GROUP 6 VERSUS ENCLOSED VOLUME

pounds per man and personal effects, 235 pounds per officer, 165 pounds per chief petty officer and 65 pounds per enlisted man. The weight of stores is a function of the crew size and the required endurance.

$$\text{Weight of Stores} = (.0222 + .00202 * D) * \text{NAC} + .00135 * D * \text{NAC}$$

The weight of potable water is again calculated as 50 gallons per man or $0.186 * \text{NAC}$, tons.

6.10.4 Flow Chart

A flow chart for Subroutine WEIGHT is shown in Figure 29.

6.10.5 Output List for Subroutine WEIGHT

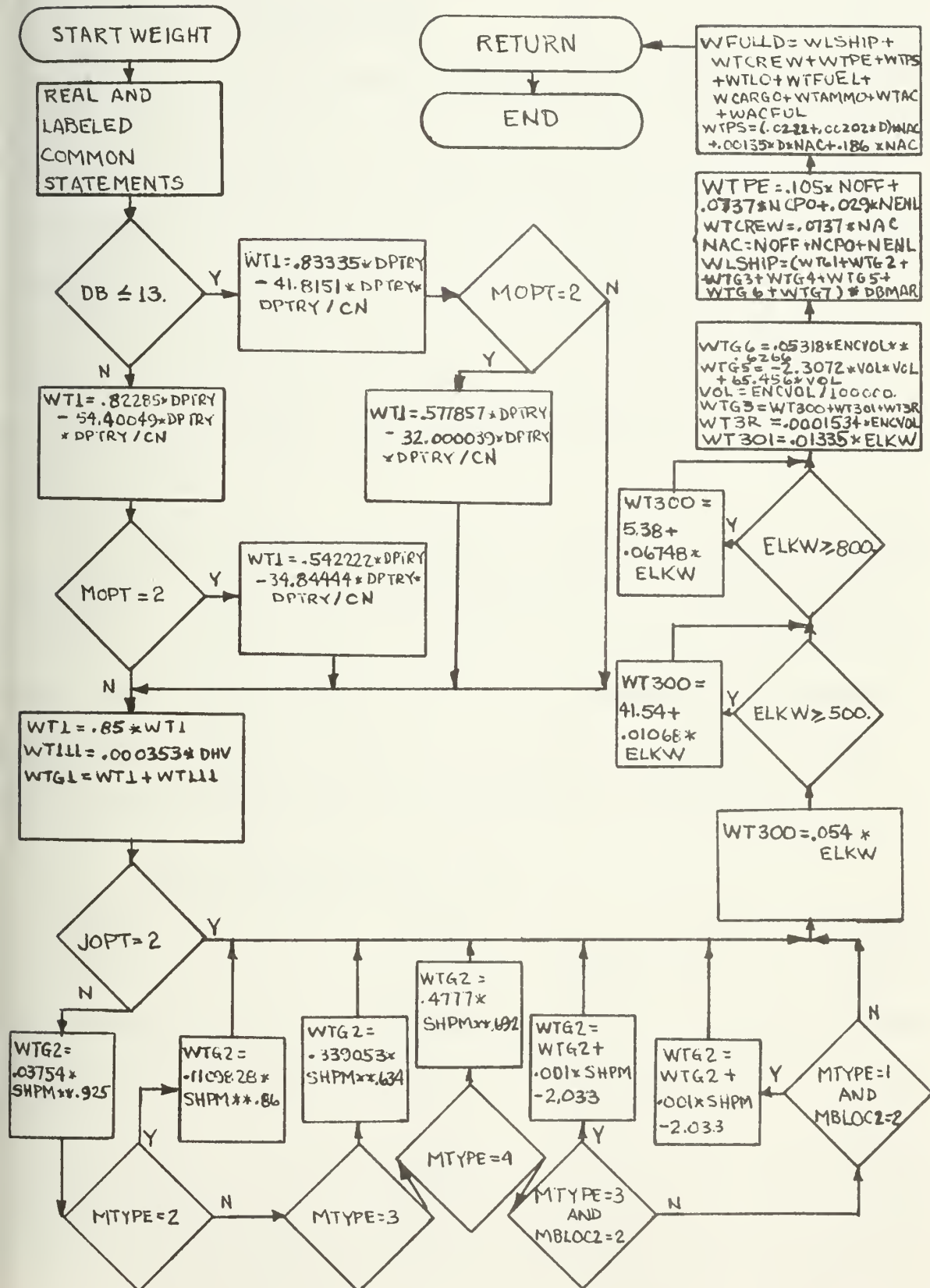
WFULLD	LC(WW)	WTG3	LC(WW)
WLSHIP	LC(WW)	WTG5	LC(WW)
WTCREW	LC(LL)	WTG6	LC(WW)
WTG1	LC(WW)	WTPE	LC(LL)
WTG2 (JOPT=1 only) . .	LC(WW)	WTPS	LC(LL)

6.10.6 Nomenclature List

The definitions of all variables used in this routine are the same as those used in the MAIN program with the following exceptions:

D	endurance days for dry provisions - same as ENDDAY in MAIN
NAC	number of accommodations
VOL	enclosed volume x 10^{-5}
WT111	weight of group 111, tons
WT300	weight of group 300, tons
WT301	weight of group 301, tons
WT3R	weight of remainder of group 3, tons

FIGURE 29: WEIGHT SUBROUTINE FLOW CHART



6.11 Subroutine VCG

6.11.1 Purpose and Approach

Subroutine VCG estimates the location of the vertical center of gravity of the ship in the full load condition. Data from weight estimates of previous SWATH designs are used to determine feasible locations of the vertical centers of gravity of the various weight groups and load items. These data are tabulated as the ratio of the vertical center of gravity location to the depth to the top of the box for each SWATH ship. The routine selects the appropriate value of VCG/DT for use in computing the total vertical moment of the ship and the resultant vertical center of gravity location.

The values assigned to the VCG/DT ratio by the routine are feasible values only. The free surface correction term may be used to effect a variation of the center of gravity location as it is subtracted from the KG value. Additional variation in KG values are possible with the SWATH configuration because the transverse stability is controlled to a large extent by the hull separation rather than the exact value of KG.

6.11.2 Input List for Subroutine VCG

ACCG LC(EF)	D LC(AA)
ACWT LC(EF)	DBMAR LC(WW)
AMOCG LC(EF)	DH LC(GG)
AMOWT LC(EF)	GR4CG LC(EF)
CACFUL LC(HH)	GR4WT LC(EF)
CARGOC LC(EF)	GR7CG LC(EF)
CARGOW LC(EF)	GR7WT LC(EF)

MBLOC2	LC(JJ)	WTG1	LC(WW)
MTYPE	LC(CC)	WTG2	LC(WW)
NOARM	LC(FF)	WTG3	LC(WW)
NOELT	LC(FF)	WTG4	LC(WW)
WCARGO	LC(LL)	WTG5	LC(WW)
WFULLD	LC(WW)	WTG6	LC(WW)
WLSHIP	LC(WW)	WTG7	LC(WW)
WTAMMO	LC(LL)	WTLO	LC(LL)
WTCREW	LC(LL)	WTPE	LC(LL)
WTFUEL	LC(LL)	WTPS	LC(LL)
		WACFUL	LC(LL)

6.11.3 Program Development

Data on the vertical center of gravity location for various weight groups and load items are tabulated in Table VII. The machinery type, machinery location, number of decks and the material selected influence the values of VCG/DT selected. The ASSUMED column of the table indicates the condition codes for the various assumptions made and the assumed values of VCG/DT used in the model. This routine calculates the depth to the main deck of the SWATH using the geometry previously determined and an assumed deck height of 9 feet. The center of gravity value for group 1 is determined as a function of the material option, number of decks and the depth. The center of gravity value for group 2 is determined as a function of the machinery type, the location of the prime mover, the shaft horsepower and the total depth. Groups 3, 5 and 6 centers of gravity locations are estimated as a function of the number of decks. Groups 4 and 7 centers are input values as are centers for aircraft fuel, cargo, aircraft and ammunition. The values of VCG/D

or groups 4 and 7 and payloads given in the table may be used for initial estimates of input values. The vertical moments for these items are calculated in two DO loops in the routine and the vertical centers are determined. The light ship vertical center is calculated by summing the weights times the appropriate center of gravity times the margin divided by the light ship weight. Next the centers of gravity of load items are estimated. Liquids are generally assumed to be centered at the centers of the hulls. Crew and effects and stores are assumed to be in the box. The total vertical moment due to loads is computed. The sum of the light ship moment and the loads moment divided by the full load displacement results in the vertical center of gravity location which is returned to the EXECUTE subroutine.

6.11.4 Flow Chart

The flow chart for the VCG subroutine is shown in Figure 30.

6.11.5 Output List for Subroutine VCG

CCARGO LC(OO)	CGG3 LC(OO)
CFULD SCDA	CGG4 LC(OO)
CFULLD LC(OO)	CGG5 LC(OO)
CGAC LC(HH)	CGG6 LC(OO)
CGAMMO LC(HH)	CGG7 LC(OO)
CGCREW LC(HH)	CGLO LC(HH)
CGFUEL LC(HH)	CGPE LC(HH)
CGG1 LC(OO)	CGPS LC(HH)
CGG2 LC(OO)	CLSHIP LC(OO)

VERTICAL CENTER OF GRAVITY DATA

SHIP	23	24	24 MOD	25	25	ASSUMED		VCG/ DT
						MTYPE/ MBLOC2	DECKS	MOPT
MTYPE/MBLOC2	3/2	3/1	3/1	3/1	2/2			
DECKS	1	1	1	2	2			
MOPT	1	1	1	1	1			
WEIGHTS:								
GROUP 1	.563	.604	.582	.605	.606		1	1
							1	2
							2	-
							-	-
GROUP 111	.978	1.220		1.125	1.124	1/-		.58
GROUP 2	.403	.227	.223	.234	.388	2/2		.57
						3/2		.605
						3/1		-
						4/2		.15
GROUP 3	.859	.916	.832	.781	.783			.39
GROUP 4		1.00		1.00				.40
GROUP 5	.319	.669	.669	.781	.783		1	.22
GROUP 6	.248	.879	.879	.771	.773		2	.43
GROUP 7		1.051					1	.869
CREW		.89					2	.782
PROVISIONS		.89						.67
GENERAL STORES		.89					1	.78
AMMUNITION		.89					1	.88
FUEL	.117	.127					2	.77
AIRCRAFT								
AIRCRAFT FUEL				.109	1.062			.89
MARGIN	.502	.848		.859	.860			.85
FULL LOAD	.500	.588	.615	.624	.624			.83

FIGURE 30a: VCG SUBROUTINE FLOW CHART

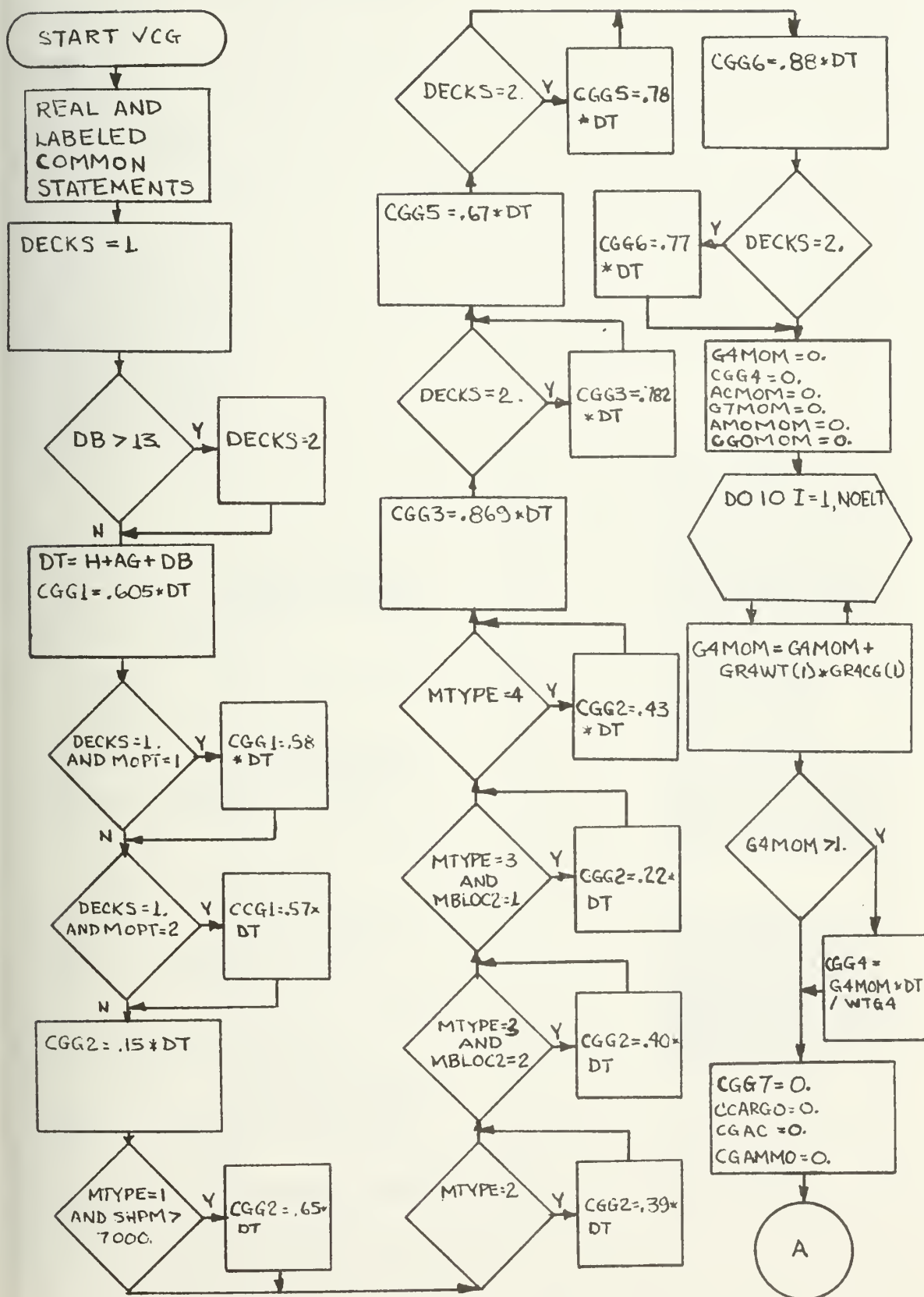
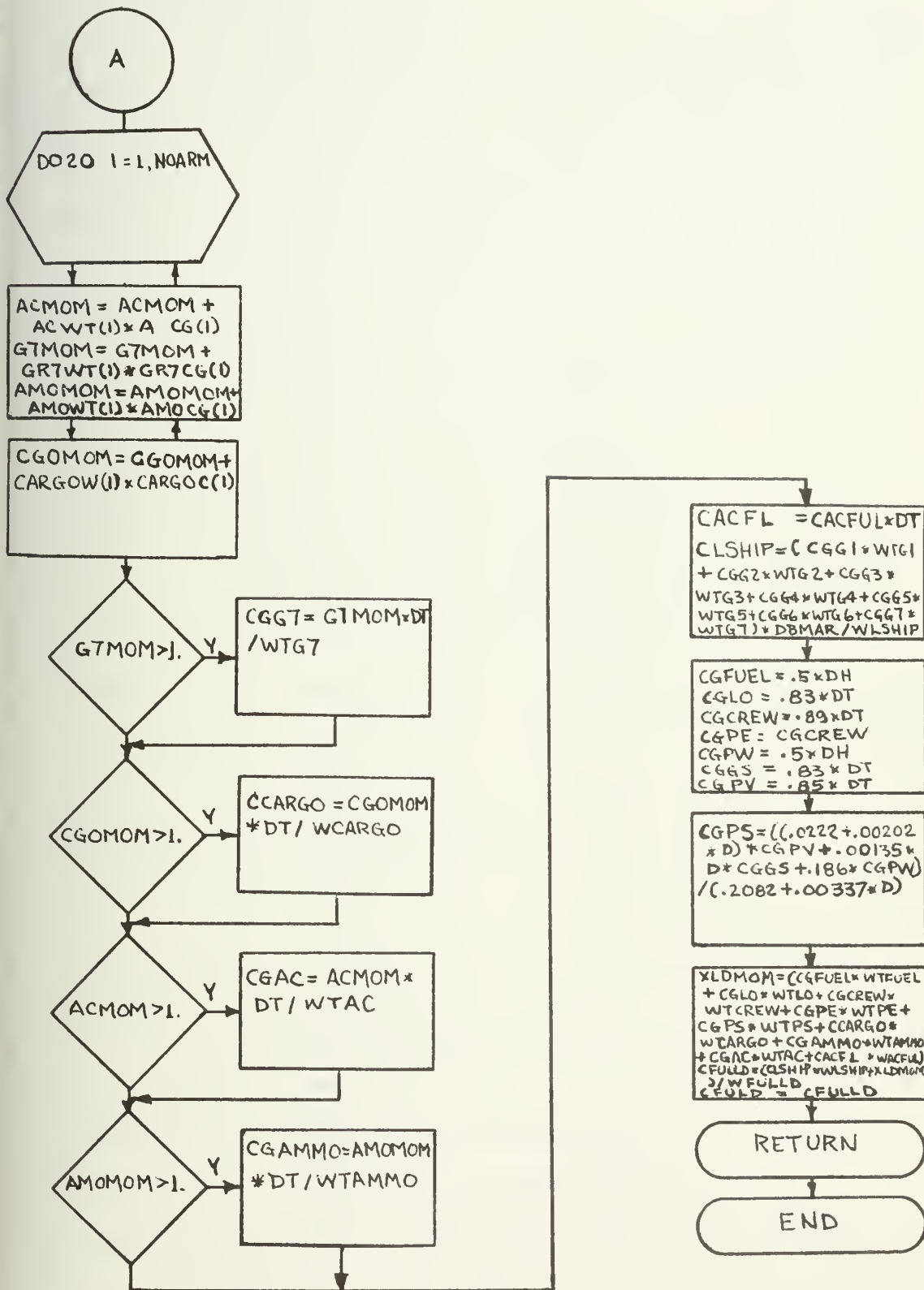


FIGURE 30b: VCG SUBROUTINE FLOW CHART-continued



6.11.6 Nomenclature List

The definitions of all variables used in this routine are the same as those used in the MAIN program with the following exceptions:

ACMOM	total vertical aircraft moment, tons
AMOMOM	total vertical ammunition moment, tons
CACFL	vertical center aircraft fuel, ft
CFULD	same as CFULLD
CFULLD	vertical center of ship at full load, ft
CGG1	vertical center of group 1, ft
CGG2	vertical center of group 2, ft
CGG3	vertical center of group 3, ft
CGG4	vertical center of group 4, ft
CGG5	vertical center of group 5, ft
CGG6	vertical center of group 6, ft
CGG7	vertical center of group 7, ft
CGGS	vertical center of general stores, ft
CGOMOM	vertical moment of cargo, tons
CGPV	vertical center of provisions, ft
CGPW	vertical center of potable water, ft
CLSHIP	vertical center of light ship, ft
D	endurance days for dry provisions - ENDDAY in MAIN
G4MOM	total group 4 moment, tons
G7MOM	total group 7 moment, tons
XLDMOM	total load moment, ton-ft

6.12 Subroutine COST

6.12.1 Purpose and Approach

This subroutine calculates the lead ship acquisition cost based on the seven light ship weight groups. The method was developed by Coast Guard Naval Engineering personnel (Flanagan's Method), used in graphical format and later in a computer routine for estimating ship acquisition costs and programmed by Goodwin in the cutter model. This routine makes minor modifications to Goodwin's COST to make it applicable to the SWATH and provides several new estimating relationships which will be described below.

The routine uses materials cost equations developed from 1959 price data and thus require a correction factor to correct the prices in which the ship will be built. These cost indices are shown in Figure 31 and are based on Bureau of Labor Statistics data for a product representative of a weight group.

The labor rate for all weight groups is assumed to be the same and is input as an average labor rate in dollars per hour in the year in which the ship will be built. Bureau of Labor Statistics data for wage rates of shipyard workers is supplied as Figure 32. As there is wide regional variation of wage rates, the values extrapolated from the figure can only be considered averages.

Using the weight, cost index and labor rate data the routine calculates the materials, labor and miscellaneous costs of the ship and returns a cost breakdown and total cost figures to storage for printing as output.

FIGURE 31: COST INDICES VERSUS TIME

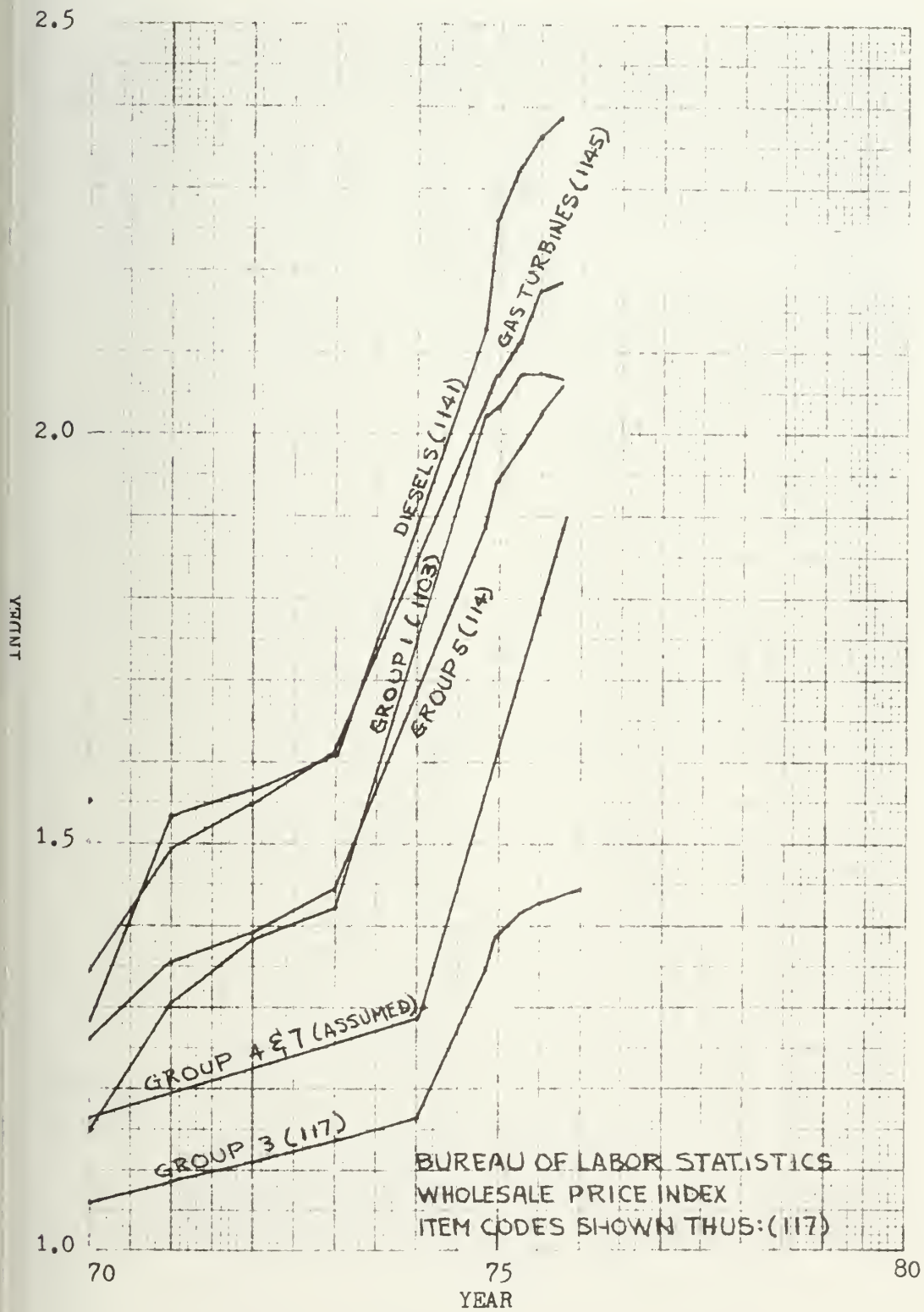
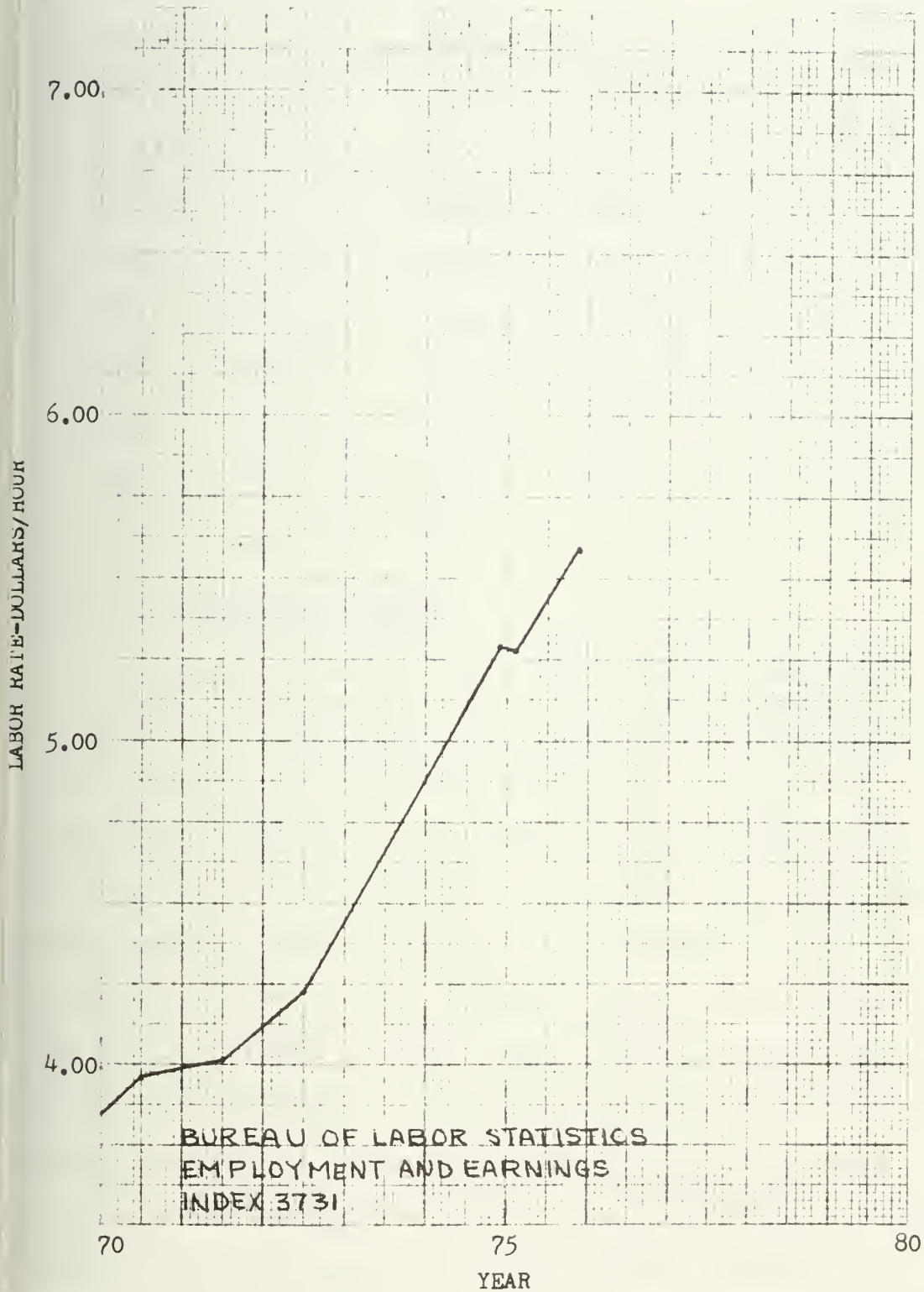


FIGURE 32: LABOR RATES VERSUS TIME



6.12.2 Input List for Subroutine COST

CSTG2 (JOPT=2 only) . LC(MM)	MOPT LC(CC)
CSTG4 LC(MM)	MTYPE LC(CC)
CSTG7 LC(MM)	WTG1. LC(WW)
DBMAR LC(WW)	WTG2 LC(WW)
DOLHR LC(NN)	G6IND LC(NN)
G1IND LC(NN)	WTG3 LC(WW)
G2IND LC(NN)	WTG4 LC(WW)
G3IND LC(NN)	WTG5 LC(WW)
G5IND LC(NN)	WTG6 LC(WW)
JOPT. LC(CC)	WTG7 LC(WW)
LEN SDCA	

6.12.3 Program Development

The assumptions made in this routine are many. Materials costs are based on representative items in the Wholesale Price Index. Group 1 data are based on cold rolled steel plate, group 2 and 5 data are based on pumps and compressors, group 3 data are based on small electric machinery, group 6 data are based on steel furniture and groups 4 and 7 must be assumed at the prices in the construction year. Figure 31 shows an assumed curve for groups 4 and 7 which may be used to estimate prices if an old estimate is known. Eighty percent overhead and ten percent profit are assumed. Miscellaneous cost items are assumed as follows: initial output, 2 percent of total cost; spares, 9 percent of group 2 materials cost plus 8 percent of group 3 materials cost plus 25 percent of group 4 materials cost plus 10 percent of group 5 materials cost; retrofit, 4 percent of total cost; and 3.5 percent for administrative costs.

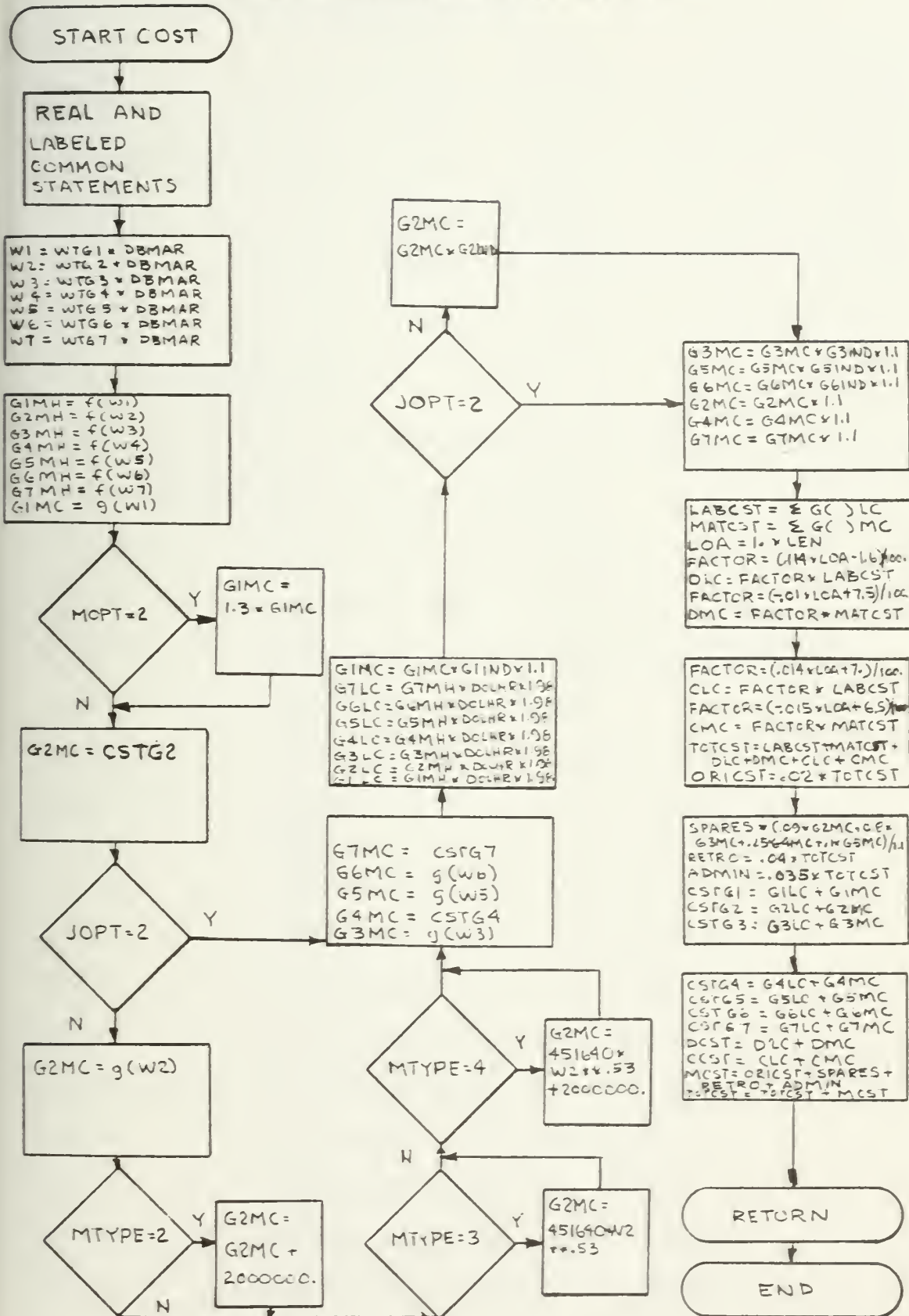
Several changes in the relationships presented previously are necessary to include four machinery options and two materials options and account for the difference in SWATH geometry. For Diesel propulsion the routine is unchanged; for Diesel-electric an additional \$2,000,000 is added. For gas turbine propulsion a new relationship was determined from 1971 data. Thus any cost index applied should be related to the 1971 value rather than that which is shown in Figure 31 directly. There is a good possibility of error in this calculation. For gas turbine-electric propulsion, \$2,000,000 is added to the value for gas turbine propulsion. If aluminum structure is specified, the materials cost for group one is increased 30 percent. For calculating the design and construction services costs, the Coast Guard procedure uses the length overall rather than the length between perpendiculars. For SWATHS it is assumed that the proper length for computing the FACTOR in making these calculations is the hull length.

A word of caution should be added here regarding the possibility of cost estimation errors. In this program group 2, 4 and 7 costs may be inputs into the calculation and may form a large part of the total ship cost. Input values are not corrected for inflation by the program. Any input value must be corrected for inflation before input or the result may be unreasonable.

6.12.4 Flow Chart

A flow chart of this routine is shown in Figure 33.

FIGURE 33: COST SUBROUTINE FLOW CHART



6.12.5 Output List for Subroutine COST

CCST	LC(MM)	CSTG6	LC(MM)
CSTG1	LC(MM)	CSTG7	LC(MM)
CSTG2 (JOPT=1 only) .	LC(MM)	DCST	LC(MM)
CSTG3	LC(MM)	MCST	LC(MM)
CSTG4	LC(MM)	TOTCST	LC(NN)
CSTG5	LC(MM)		

6.12.6 Nomenclature List

The definition of all variables is the same as that given in the MAIN program nomenclature except for the following:

ADMIN	administrative costs, dollars
CLC	construction services labor cost, dollars
CMC	construction services material cost, dollars
DLC	design labor cost, dollars
DMC	design materials cost, dollars
FACTOR	multiplier for design and construction services costs
G1LC	weight group 1 labor cost, dollars
G2LC	weight group 2 labor cost, dollars
G3LC	weight group 3 labor cost, dollars
G4LC	weight group 4 labor cost, dollars
G5LC	weight group 5 labor cost, dollars
G6LC	weight group 6 labor cost, dollars
G7LC	weight group 7 labor cost, dollars
G1MC	weight group 1 material cost, dollars
G2MC	weight group 2 material cost, dollars

G3MC	weight group 3 material cost, dollars
G4MC	weight group 4 material cost, dollars
G5MC	weight group 5 material cost, dollars
G6MC	weight group 6 material cost, collars
G7MC	weight group 7 material cost, dollars
G1MH	weight group 1 man-hours
G2MH	weight group 2 man-hours
G3MH	weight group 3 man-hours
G4MH	weight group 4 man-hours
G5MH	weight group 5 man-hours
G6MH	weight group 6 man-hours
G7MH	weight group 7 man-hours
LABCST	total construction labor cost, dollars
LOA	length overall, feet
MATCST	total construction material cost, dollars
ORICST	initial output cost, dollars
RE	endurance nautical miles - RGEND in MAIN
RETRO	retrofit cost, dollars
SFCH	specific fuel consumption at half power - SFCHHP in MAIN
SFCM	specific fuel consumption at full power - SFCMHP in MAIN
SPARES	spare parts cost, dollars
VE	endurance speed, knots - VEND in MAIN
W1	weight group 1 with margin, tons
W2	weight group 2 with margin, tons
W3	weight group 3 with margin, tons
W4	weight group 4 with margin, tons
W5	weight group 5 with margin, tons

W6	weight group 6 with margin, tons
W7	weight group 7 with margin, tons

6.13 Subroutine OUTPUT

6.13.1 Purpose and Approach

This subroutine prints all the program output except the error messages printed in the XECUTE subroutine. The subroutine is divided into two major sections, the input data printing section and an output data printing section. The input data section lists all the input data supplied to the program including the payload listings, manning, cost indices, mission and performance inputs, options and the input length. If an error message is generated no further printing will occur for the given input case. If there is more data, the program will cycle and operate on the new data set.

If the program completes the calculation successfully, the output data will also be printed. The output data consists of dimensional data, weight, center of gravity and cost data, area data and a series of ratios and coefficients which may be useful for comparison of design alternatives.

6.13.2 Inputs Required

All of the inputs required for printing the outputs to the program have previously been stored in Labeled Common Blocks as a result of inputting a value or calculating the value in another subroutine. The data stored in these common storage areas are all required inputs to this subroutine. No additional listing of the common storage will be made here.

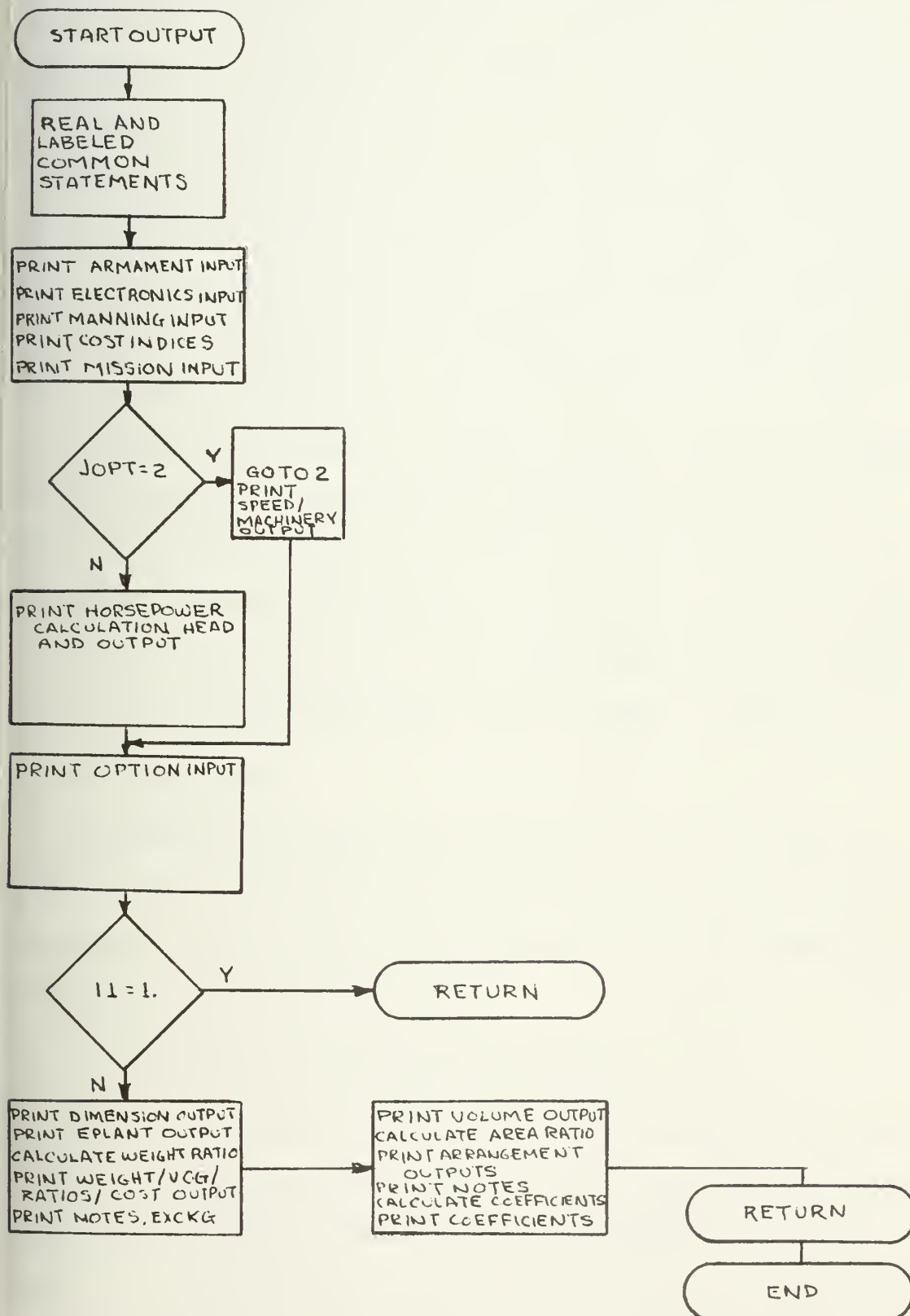
6.13.3 Program Development

The format of the output documents of this program has been modeled after that of Goodwin to provide for easy comparison of SWATH and conventional displacement ships. Certain modifications are made to accept the geometry of the SWATH.

The subroutine consists primarily of FORMAT and WRITE statements. These statements will not be described in detail, but the order and purpose of each will be noted. First the heading statement is printed; this provides the basic identification of the run. The input payload data is then printed. Armament, aircraft, cargo and electronics input data will appear in the same form as the input data cards. Next the manning inputs are listed. Manning inputs are followed by cost indices, military mission input parameters and the vehicle performance inputs. If the machinery plant is specified, the specifications of the machinery plant which were input will be listed as output. If the machinery is not specified and the maximum speed, endurance speed, endurance range and propulsive coefficient are input, these values are listed as output. Next the options inputs--machinery type, material type, free surface correction, margins and length are listed. This completes the listing of input data. The program then tests for the existence of any error messages. If there are errors in the program execution, the print stops and control is returned to EXECUTE.

The output data fields begin with a summary of the ship dimensions as calculated. The hull volume and generator size are then output. Weight fractions of full load and light ship displacements with margins

FIGURE 34: OUTPUT SUBROUTINE FLOW CHART



re computed for each of the weight groups. The weight, center of gravity, weight fractions and cost data are then printed out for each weight group and for the light ship. Payload fractions are then computed and a listing of the payload weights, centers of gravity and weight fractions are printed out for the full load ship. After printing some explanatory notes and miscellaneous cost figures the program computes volume percentages for machinery, tankage and arrangements area; these data are also printed. The next section of the program computes area ratios for each type of space in the design model and prints out the area value computed and the area ratio for each type of space. Finally the program computes a number of coefficients-the habitability volume per man, weight of machinery per shaft, horsepower, volume of machinery spaces per shaft horsepower, vehicle density, weight group one density, payload cost fractions and VCG/D value. After completing printing, control is returned to the XECUTE subroutine and more input is sought.

6.13.4 Flow Chart

A simplified flow chart of the OUTPUT subroutine is shown in Figure 34. Note that this flow chart shows the two decision nodes in the subroutine and indicates what type of operations are being performed without listing all the statements.

6.13.5 Output List for Subroutine OUTPUT

No values are generated in this subroutine which are to be used elsewhere. All the values generated and stored in previous subroutines and the values calculated in this subroutine are output in the output listing.

6.13.6 Nomenclature List

All the variables used in this subroutine with the exception of several dummy variables used to make calculations within the routine have been defined previously.

AAVOM	available arrangements volume, cubic feet
AR	total arrangements area, sq ft
ARE	sum of the input required areas, sq ft
COEFm	dummy variable used for comparison coefficients
EXAR	excess area, sq ft
HABSPC	habitability space, sq ft
Rn	dummy variable used for volume and area ratios

CHAPTER VII

EVALUATION

The SWATH synthesis model developed in this thesis may be used to test the feasibility of a set of input design parameters for a SWATH ship. The parameters of the feasible design which are produced as outputs may be used as inputs for the preliminary design validation phase. These output parameters compare favorably with those generated by the Navy for a Coast Guard-operated SWATH and fall within the limits of the existing data base. The program has shortcomings and is expensive to run. This chapter reviews the problem areas in the program and examines the reliability of outputs by comparing the outputs of this program with Navy-generated designs.

Four areas of difficulty can be identified in the program; the arbitrariness of several of the estimating relationships, the oversizing of the electrical plant, the overestimation of structural weight and the determination of shaft horsepower. To improve on the estimating relations, there is no alternative to generating a larger data base. As there is but one operating SWATH in existence and only on the order of hundreds of design studies, the best way to validate estimating relations appears to be construction of a prototype or series of prototype ships of this design type. An effort has been made to incorporate data into the data base for estimates as it became available, but this effort must continue to insure the best design data.

Goodwin noted in evaluating his program that the electric generator capacity calculated reflected the policy of the Coast Guard for new designs

and is not an error in the program even though it tends to overestimate the required capacity considerably. Since this program uses the same method as Goodwin to estimate generator requirements, the results appear to be high. For instance, for a 240 foot SWATH design, this model indicates that either three 750 KW generators, three 1000 KW generators or three 1500 KW generators will be required. The total ship's load ranges from 650 to 1030 KW. With a load including growth, deterioration and starting loads of 1030 KW, a set of 1000 KW generators probably are sufficient, not the 1500 KW generators calculated. This type of trade-off is required at a later stage of the design than is considered in this model, however.

A third area of difficulty in the program output is in the estimation of a group 1 weight. In this program no structural analysis is attempted; data from previous designs has merely been used as a starting point. The program also assumes that the box is longer than the struts. This may appear to be a logical and reasonable assumption but its consequences may not be clear. The box length has an impact on the number of decks in the box and the structural weights. The extra box length requires cantilever structures forward and aft. If the box length is reduced, the enclosed volume may not be sufficient for arrangements on one level and another deck will be added to the box. This leads to an improvement in the use of structural material due to the deeper, more rigid box structure, but it leads to excess volume. The vehicle density of the two deck ship can be reduced and still meet the structural criteria. This can be seen by referring to Figure 24. The relationships tend to estimate from three percent low to ten percent high when compared to Navy design

studies of similar sized SWATHs. On the Navy AGOR SWATH design a detailed structural weight estimate agreed better with the design model output value with all the margin than without margin. This indicates that the structural design problem for SWATHs is far from solved and that some conservatism is desirable. This model provides for this conservatism in group 1 weight estimation, but this tends to make the ship larger and of deeper draft.

The last problem area in the program is horsepower calculation. This program uses a considerable simplification of the DRAG problem of Chapman⁽²²⁾. This simplification requires that the geometric relationships be fixed in the DIM subroutine and transferred into the horsepower routine. No resistance optimizing procedure is used; DIM merely generates a "good" form for a SWATH. Since the hull form is not optimized from a resistance point of view and since the speed-power curve has some rather pronounced humps and hollows for SWATH forms, the horsepower required at endurance speed may be higher than that of an optimized SWATH form. The resistance of a SWATH form generated by this model 3335 tons displacement is approximately 30 percent higher than that of a conventional destroyer form at maximum speed and at the endurance speed of a destroyer, around 18 knots, the SWATH is starting up a pronounced hump in the speed-power curve.

Not only is the method used for calculating the horsepower requirements in this program an unoptimized solution, but it is an expensive way to find the required powering. In each iteration through the program, the horsepower calculation is made. This requires approximately 5 seconds on the IBM 370 computer; five iterations cost about \$8.00. To limit

the time and money used in determining the horsepower, the program was monitored as it executed the dimension changes and horsepower calculations. It was found that after approximately five iterations the dimensions had stabilized such that further horsepower calculations do not result in significant changes. Table VIII gives an indication of this stabilization of dimensions. A control has been placed in the XECUTE routine which allows only five iterations before the HPCALC routine is bypassed. If an unrestricted run is desired this control loop may be removed. However, unrestricted running of the program may result in up to 40 iteration loops and a cost exceeding \$40 for one ship run. The use of this horsepower calculation may not be economically feasible. It is also possible to remove the horsepower calculation from the program and substitute dummy values of the horsepower returned. This approach is reasonable if the user has a good estimate of the horsepower from another source.

The final section of this chapter compares the results of this model with previous studies conducted by the Navy. Several design outputs from the model are included in Appendix C. Table IXa shows a comparison of the 240 foot Navy SWATH AGOR, Ship 24, and the 240 foot Navy-designed SWATH CUTTER, Ship 25 in the data base, with the model output for a series of 240 foot ships with diesel-electric propulsion, gas turbine propulsion and with the machinery parameters specified and the speed of the ship calculated, the JOPT=2 option. Table IXb shows a comparison of the 155 foot Navy PMR patrol vessel, Ship 21, with the model outputs for the gas turbine propulsion/ aluminum construction option and the diesel-electric/steel option. For further comparison the results of the Goodwin Cutter model synthesis of the 210 foot WMEC, 270 foot WMEC and 378 foot WHEC are also shown in this table. The notation "DUMMY" describing a ship indicates that the program has

TABLE VIII

STABILIZATION OF VARIABLES

Variable	Run Loop	SHIP 1 DUMMY			SHIP 2		SHIP 3 DUMMY		
		4	5	29	1	4	1	5	13
Length		240	240	240	240	240	155	155	155
Diameter		17.93	17.93	17.53	15.53	16.93	11.55	13.56	13.56
Draft		31.38	31.38	30.68	27.18	29.63	20.22	23.72	23.72
Strut Length		193	193	193	193	193	125	122	125
Strut Beam		7.58	7.58	7.41	6.52	7.26	4.85	5.60	5.60
CWP		.942	.942	.942	.84	.941	.858	.84	.856
Box Beam		89.73	86.73	83.33	89.33	87.73	61.66	67.65	67.66
Trail Displ.		3641	3641	3504	2755	3324	95342	1214.77	1233.66
Molded Displ.		3590	3590	3456	2717	3279	940.26	1198.00	1216.63
GMT		4.1	4.21	4.07	3.79	3.89	2.69	3.12	3.00
GML		551.32	553.75	564.38	103.08	579.30	113.28	47.81	94.79
Tons					2831	3319	3331		
SHP Max.		32000	32000	32000	14835	17374	2800	2800	2800
Sust. Speed		24.250	24.250	24.250	20.00	20.00	15	15	15
SHP End.		3025	3025	3025	4691.8	5380	1200	1200	1200
End. Speed		12.000	12.00	12.000	13.00	13.00	10	10	10
Job Option		2	2	2	1	1	1	1	1
Average KW		485	487	470	645	602	156	150	152
KW1		668	671	649	1086	1032	224	217	219
Propulsion KW		70	70	70	71	71	15	15	15
Lub Oil		5.25	5.25	5.25	4.98	5.23	7.80	7.80	7.80
SFC		.705	.705	.705	.589	.590	.506	.506	.506
WT Fuel		346.8	346.9	345.4	830.57	930	80.16	80.16	80.31
Enc. Vol.		460687	452380	436525	430472	462320	175678	197515	201477
Mach'y Vol.		31323	31323	29941	19755	24026	17861	22018	22018
WTG1		1756	1730	1665	984	1076	483	583	504
WTG2		283	283	283	150	165	102	102	102
WTG3		130	129	127	193	198	44	47	47
WTG4		90	90	90	90	90	4	4	4

TABLE VIII (Continued)

Variable	Run Loop	SHIP 1 DUMMY 4	SHIP 1 DUMMY 5	SHIP 1 DUMMY 29	SHIP 2 1	SHIP 2 4	SHIP 2 5	SHIP 3 DUMMY 1	SHIP 3 DUMMY 5	SHIP 3 DUMMY 13
WTG5		253	249	242	239	253	253	108	120	123
WTG6		188	186	182	180	189	189	102	111	112
WTG7		17	17	17	17	17	17	6	6	6
WFULLD		3637	3599	3508	3076	3331	3336	1083	1221	1237
Total Depth		59.38		58.68			57.63			28.69
VCG		32.52		31.99			28.19			19.40
Cost \$M				40.127						

TABLE IX a
COMPARISON OF DESIGN OUTPUTS

SHIP	AGOR 24	CUTTER 25	CUTTER 25	CUTTER MODEL	CUTTER MODEL	CUTTER MODEL
Material	Steel	Steel	Steel	Steel	Steel	Steel
Machinery	Diesel	D-E	G-T	D-E	G-T	G-T
Job Option	-	-	-	1	1	2
Length	240.	240.	240.	240.	240.	240.
Diameter	15.	15.72	15.43	16.78	15.53	16.03
Draft	16.25	27.51	27.00	29.37	27.18	28.06
Strut Length	200.	184.02	180.09	193.	193.	193.
Strut Beam	7.5	7.5	7.5	7.2	6.72	6.88
CWP	.89	.845	.842	.942	.942	.942
Box Beam	82.	85.02	82.82	81.58	77.33	77.83
Box Depth	13.	22.	22.	13.	13	13.
Box Length	171.	184.02	180.09	213.	213.	213.
Total Depth	59.25	64.51	64.00	57.42	55.16	56.09
Displacement	3019.12	3058.08	2947.63	3267.55	2853.38	3013.13
SHP MAX.	4842.	12880.	40000	15278	38611	32000
Sust. Speed	13.17	19.36	24.26	19.7	24.	22.67
SHP END.	3834.7	2609	2537	2974	2848	2305
END. Speed	13.	12.	12.	12.	12.	12.
Endurance	6000.	3000.	3000.	3000	3000	3000
Generators	4 x 350	4 x 500	4 x 500	3 x 750	3 x 750	3 x 750
WTG1	1130	1315	1267	1361	1232	1273
WTG2	213	380	283	440	274	283
WTG3	74	105	105	128	121	123
WTG4	19	90	90	90	90	90
WTG5	417	283	273	245	226	230
WTG6	235	201	198	184	173	175
WTG7	1	17	17	17	17	17
WLSHIP	2401	2749	2569	2834	2454	2519
WLSHIP/ WFULLD	.795	.899	.871	.867	.859	.835
WTFUEL	472	155	224	253	235	332
WFULLD	3032	3059	2948	3269	2857	3018
KG	34.84	40.23	38.40	32.44	30.67	30.40
VCG/DT	.588	.624	.602	.565	.556	.542
ENCVOL	341352	486256	465398	443809	402486	410984
MACH'Y VOL	-	-	-	40453	24082	25038
TANK VOL	-	-	-	19660	18109	23011

TABLE IXa (Continued)

SHIP	AGOR 24	CUTTER 25	CUTTER 25	CUTTER MODEL	CUTTER MODEL	CUTTER MODEL
Total Arrgt.	20733	33533	32069	25286	23025	23195
Hull Arrgt.	14022	31293	29829	19341	18306	18456
DKHSE. Arrgt.	6711	2240	2240	5945	4719	4739
HAB VOL/ MAN	-	-	-	559.2	559.2	559.2
WTG1/ ENCVOL	.0038	.00270	.00272	.00307	.00306	.00310
WTG2/ HP	.0505	.0424	.00708	.0288	.0071	.0088
MACH VOL/ HP	-	-	-	2.6477	.6237	.7824
WFULLD/ ENCVOL	.00899	.00629	.00633	.00737	.00710	.00734
WLSHIP/ ENCVOL	.00703	.00565	.00552	.00639	.00610	.00613
COST \$M	-	26.36	29.96	40.99	54.19	38.18

Notes for Table IXa, b:

- 1) Dimensions in feet. Weights in tons. Speed in knots.
Endurance in nautical miles.
- 2) Nomenclature
 - WTG = weight group
 - WLSHIP = light ship weight
 - WFULLD = full load weight
 - WTFUEL = weight of fuel
 - KG = vertical center of gravity location
 - VCG/DT = vertical center of gravity/total depth ratio
 - ENCVOL = total enclosed volume
 - HABVOL = habitability volume

TABLE IXb
COMPARISON OF DESIGN OUTPUTS

SHIP	PMR 21	PATROL MODEL	PATROL DUMMY	CUTTER MODEL 378 WHEC	270 WMEC	210 WMEC
Material	Steel	Alum.	Steel	Steel	Steel	Steel
Machinery	D-E	G-T	D-E	CODOG	Diesel	Diesel
Job Option	-	1	1	2	1	1
Length	155.	155.	155.	350	270 ¹	210
Diameter	9.5	10.81	13.56			
Draft	16.70	18.91	23.72	14.60	13.42	9.12
Trut Length	112.	125.	125.			
Trut Beam	5.5	4.54	5.89			
WP		.928	.856			
Box Beam	54.	58.91	67.66	43.32	40.92	33.96
Box Depth		13	13			
Box Length		145	145			
Total Depth	39.70	43.78	48.55			
Displacement	786	871.33	1233.66	3062	1984	944
HP MAX	2800.	2605	2800D	36000	9139	4412
ust. Speed	15.	15	15	2644	19.7	17.29
HP END.		1124	1200D	2647	2838	1554
ND. Speed	5	10	10	14.	15	14
ndurance	2000	2000	2000	10500	6500	4000
Generators		3 x 500	3 x 250	3 x 1500	3 x 750	3 x 500
WTG1	354	300	594	963	661	335
WTG2	100	50	102	384	203	99
WTG3	11	79	48	165	89	75
WTG4	3	4	4	80	50	26
WTG5	80	103	123	262	190	104
WTG6	27	100	112	322	200	106
WTG7	0	6	6	39	30	9
WLSHIP	661	718	1107	2215	1465	753
WLSHIP/						
WFULLD	.841	.824	.895	.723	.738	.796
WTFUEL	47	107	80	653	386	141
WFULLD	786	872	1237	3061	1986	946
WG		25.92	28.69	17.20	16.47	15.12
WCG/DT		.592	.591	.58	.559	.621
WNCVOL		166958	201479	368439	254816	133709
WACH'Y VOL		10602	22018	57390	44238	18178
WANK VOL.		6815	5608	36987	24526	16651

Shortest ship feasible in Goodwin Model.

TABLE IXb (Continued)

SHIP	PMR 21	PATROL MODEL	PATROL DUMMY	CUTTER MODEL		
				378 WHEC	270 WMEC	210 WMEC
Total Arrgt.		10479	11955	29664	20344	10661
Hull Arrgt.		9331	10724	18522	15180	8562
DKHSE Arrgt.		1148	1232	11142	5164	2099
HAB VOL/ MAN		650.4	650.4	491.2	512.9	549
WTG1/ ENCVOL		.00180	.00295	.00261	.00259	.0025
WTG2/HP		.0193	.0365	.0107	.0222	.0224
MACHY VOL/ HP		4.0701	7.8635	1.5942	4.8408	4.1175
WFULLD/ ENCVOL		.00522	.00614	.00831	.00779	.00707
WLSHIP/ ENCVOL		.00430	.00549	.00601	.00575	.00563
COST \$M		22.23	19.40	29.37	30.136	8.521

truncated the horsepower calculation or dummy inputs have been made to cause the computer to loop across the HPCALC subroutine section.

The tables show that the values of the various parameters returned by the model are in the range of values given by the Navy studies. This model produces ships which tend to be somewhat larger, have more displacement and have larger draft. The displacements returned by the model for the 240 foot ship range from two percent more to three percent less than the Navy results. It is more difficult to compare the 155 foot ship because the input payloads are different, but the best agreement of displacement at this size is 11 percent. Conservative estimates of structural weights, an apparent overestimate of the generator size and conservative fuel rate estimates combine to increase displacement. These effects are more severe for the smaller ship. In general the model calculates a vertical center of gravity location somewhat lower than the Navy studies. This may be due to the larger fuel weight located in the hulls. The cost estimates show that the SWATH ship is likely to be more expensive to acquire than the conventional ship. In conclusion, the outputs of the model for the various options specified show considerable bracketing of the outputs of Navy design studies.

CHAPTER VIII

CONCLUSIONS AND RECOMMENDATIONS

This thesis has investigated the use of the SWATH ship for Coast Guard applications and developed a set of estimating relationships in a computer ship synthesis model which can be used as a design tool for feasibility and preliminary design studies.

The SWATH Model is a reasonable basis for design studies for this particular type of hull form. The model is not applicable to any other geometry, but can be used in conjunction with the Cutter Model to generate information from which decisions may be made on design approaches.

The SWATH Model is limited by a small data base and must be used with caution until additional checking of the results has verified the method. Additions to the data base may help to confirm or invalidate certain estimating relationships. Although the outputs are reasonably close to the data base, the large number of variables and assumptions required in the model make correspondence of output unlikely.

Two estimating relationships used in the model noticeably overestimate. The structural weight and the electrical plant size both are estimated using the best information available or the present design policy, yet both lead to excessive values. The conservatism in the structural weight determination can probably be investigated by a manual study following application of the model. The generator oversizing must also be evaluated on a ship-by-ship basis. Applying a service factor to the requirements and thus reducing the required generator size is one approach which has been considered but not used because load analyses to determine the value of the service factor have not been calculated.

The method of horsepower calculation used by the SWATH model is too cumbersome and inefficient for use in a ship synthesis model which will be used often. Although the resistance prediction is a good routine, it is too expensive to run often and should be improved.

The results of the SWATH Model show general agreement in principal characteristics with ships in the data base for which comparisons have been made. Thus the model can be used for SWATH design studies and average ships will result.

There are six areas of study where improvements can be made to the model: (a) a seakeeping and ship motion extension, (b) a sensitivity analysis, (c) more detailed weight and center of gravity data, (d) better estimating relationships for arrangement area, (e) a reanalysis of electric generation requirements and (f) a powering study and a new method for determining horsepower.

The advantages of the SWATH configuration include limited motions and loss of speed in a seaway. Although the program now calculates a set of reasonable dimensions for the ship, it does not calculate any ship motion or speed reduction in a seaway data. This information would be very useful in determining the in-service performance of the ship. Preliminary analyses of motions data for SWATHs have been made (7, 25, 26, 27) and estimation methods can be derived. Many variables are involved, however, and the calculation may be complex. A motions routine could be added to the program after the VCG routine.

The effects on the outputs of variations in certain parameters and assumptions is another area for study. One assumption which would be

easy to vary and which should produce major variations is the assumed box length. Variations of strut length plus or minus 20 feet would provide a range of values within the data base. Altering one card in the DIM routine could affect this change. Although somewhat more difficult to vary, some of the assumed geometry could be varied. For instance, the strut could be turned around on the hull to investigate the change in resistance.

Certainly better and more detailed data for weights, vertical center of gravity location and required arrangement areas would be useful in insuring that the best possible data is input to the program. Unfortunately, new data becomes available slowly and it must be added to the data base and the relationships must be reevaluated. This is a time-consuming and dull task, but it must be done if the model is to stay current and be improved.

The need for reassessment of the electric power requirements and the possibility of applying a service factor to reduce the size of the installed generator is mentioned above. The approach which has been used in these models appears to be too simple. This simplistic approach is the reason for overestimation. A more detailed analysis of the real power requirements as a function of the operational condition, environment and time of day, for instance and a detailed load analysis is recommended to determine the actual requirements for electric power.

The most important area where improvement is required is in the horsepower prediction. The present HPCALC uses a 400 term expansion for wave drag which must be calculated for each speed. This routine is inefficient. The generation of an array of drag coefficient values as a

function of many geometric parameters and a speed seems a logical approach to solving this problem. Given the table of drag coefficients as functions of speed and geometry, a resistance estimate could be made in the same manner as that used in the DD07 and Destroyer and Cutter Models-interpolation of a coefficient value in a large array. This procedure is considerably more efficient than the iterative calculation used in this program. The difficulty will arise from the generation of the drag coefficient array. The most significant geometric parameters must be chosen as the dimensions of this array. This means that the significant variables must first be reduced to seven or fewer to make the problem tractable by computer. The evaluation of the array elements in a seven dimensional array also poses some complex programming problems. A series of drag coefficients for strut wave making and friction drag has been calculated for limited cases by Chapman⁽¹²⁾ for a range of water-plane areas and speeds.

Finally it must be emphasized that the SWATH model is intended as a design tool. It must be validated by manual calculations and drawings. It must be updated as more data is available. It provides only feasible designs and may reject a set of input requirements which are nearly feasible solely on the basis that a program constraint is violated. It should not be used as a optimization routine or as part of an optimization program; it is intended for presenting consistent design parameters to the decision maker in a readily useable format. Optimization criteria and decisions are left to the decision maker.

REFERENCES CONSULTED

1. Leopold, R., Johnson, R.S., Hadler, J.B., Genalis, P., "The Low-Waterplane Multi Hull Ship-Principles, Status and Plans for Naval Development", AIAA/SNAME, Advanced Marine Vehicles Conference, July, 1972.
2. Major, R.A., "Column Stabilized Buoy Tender", 13.46 Design Project, Massachusetts Institute of Technology, 1968.
3. Stevens, R.M., "SWATH Ship Presentation to ANVCE Interim Evaluation", 24 March 1976.
4. Lang, T.G., and Higdon, D.T., "Hydrodynamics of the 190 Ton Stable Semi-Submerged Platform (SSP)", AIAA/SNAME, Advanced Marine Vehicles Conference, February 1974, AIAA No. 74-328.
5. Lang, T.G., and Chapman, R.G., "Hydrodynamic Design of the SSP-A 190 Ton High Speed Stable Semi-Submerged Platform of the S³ Type", NUC TN 573, July 19, 1971, Revised October 1971.
6. Lin, W., Day, W.G. Jr., "The Still-Water Resistance and Propulsion Characteristics of Small-Water Plane-Area Twin-Hull (SWATH) Ships", AIAA/SNAME, Advanced Marine Vehicles Conference, February, 1974, AIAA No. 74-325.
7. Pien, P.C., and Lee, C.M., "Motion and Resistance of a Low-Water Plane Catamaran", 9th Symposium on Naval Hydrodynamics, Volume 1, ONR, ACR-203, August 1972.
8. Sarchin, T.H., Chatterton, D.A. and Kennell, G.G., "Small Water Plane Area Twin Hull (SWATH) Combatant Ships Feasibility Design Studies", NAVSEC Report No. 6114-74-8, Volume 1, January, 1974.
9. --- "Designated Task Statement HEC/MEC", United States Coast Guard Headquarters, Naval Engineering Division, 16 January 1975.
10. Lucas, R.S., and Brooks, R., "The Coastal Surveillance Cutter and It's Role in the Coastal Zone", Report to Commandant, United States Coast Guard, December, 1974.
11. Goodwin, M.J., "Ship Synthesis Model for Coast Guard Cutters", Thesis O.E., Massachusetts Institute of Technology, May, 1975.

12. Chapman, R. B., "Hydrodynamic Drag of Semi-Submerged Ships", ASME, Journal of Basic Engineering, Volume 94, Series D, No. 4, December 1972, pages 879-884.
13. Kerwin, J. E., "User's Guide to 1975 DUCKS", Massachusetts Institute of Technology, 1975.
14. --- Lecture Notes, "Advanced Marine Vehicles" Professional Summer, Massachusetts Institute of Technology, 1975.
15. Lang, T. G., et al., "Naval Feasibility Study of The S³, A New Semi-Submerged Ship Concept", Naval Undersea Research and Development Center, NUC TP 235.
16. Lang, T. G., "S³-Semi Submerged Ship Concept and Experimental Hydrodynamic Coefficients", Naval Engineers Journal, Volume 84, No. 2, April 1972, Pages 33-41.
18. --- "Semi-Submersible Ship - Vessel With A Future", Ocean Industry, Volume 6, No. 11, November 1971, Pages 21-23.
19. Hawkins, S., and Sarchin, T., "The Small Water Plane Area Twin Hull (SWATH) Program --- A Status Report", AIAA/SNAME, Advanced Marine Vehicles Conference, February, 1974, AIAA No. 74-324.
20. Aronne, E. L., Lev, F. M., and Nappi, N. S., "Structural Weight Determination for SWATH Ships", AIAA/SNAME, Advanced Marine Vehicles Conference, February 1974, AIAA No. 74-326.
21. McClure, A., "Semi-Submersible Supply Vessel Design for North Sea Operation, Ocean Industry, Volume 10, No. 2, February 1975.
22. Wernli, R. L., and Chapman, R. B., "Operating Instructions for "Drag" Computer Program", NUC TN 1385, July 1974.
23. Reed, M. R., "Ship Synthesis Model for Naval Surface Ships", Massachusetts Institute of Technology, O. E. Thesis, May 1976.
24. Harrington, R. L., editor, Marine Engineering, SNAME, 1971.
25. Lang, T. G., "S³ - New Type of High Performance Semi-Submerged Ship", ASME, Journal of Engineering for Industry, Volume 94, Series B, No. 4, November 1972, Pages 1172-1178.
26. Lang, T. G., "S³-Semi Submerged Ship Concept and Experimental Hydrodynamic Coefficients", Naval Engineers Journal, Volume 84 No. 2, April 1972, Pages 33-41.

27. Salvesen, N., "Seakeeping Characteristics of Small Water Plane Area Twin Hull Ships", AIAA, Journal of Hydronautics, Volume 7, No. 1, January 1973, Pages 3-10.

APPENDIX A

USER'S GUIDE

This appendix describes the input information required by the model in sufficient detail for the SWATH designer to prepare a set of input data cards for the computer. Guidelines for input values which may be varied to suit design requirements are noted and suggested values are given. A list of payload input data is provided as the beginning of a "shopping guide". Note that electrical requirement data is missing from this guide. These guidelines for input values and the "shopping guide" are only starting points for the design process. In order for the computer to produce reliable results the values of input values must be as realistic and accurate as possible. Previous designs may form a good starting point for such input data. A compilation of principal dimensions of previous SWATH designs is to be found in Section 6.1 of this thesis.

The input data deck for this program has been patterned after that of Goodwin to make use of the two programs by the same designer relatively easy. There are, of course, differences in the input data requirements due to the differences in the hull forms.

The minimum number of types of data cards in the input deck is 14. Several cards of one type may be required or desirable to describe the ship adequately. Where this is the case, a notation will be made in the description.

Card Type I: This card controls the reading of an input data deck.

The values which can be used are:

0--which will cause the program to stop, and

1--which will cause the program to read the following input data.

This control index must be entered in card column 1. (FORMAT I1)

Card Type II: This card provides a heading which will be printed out above the output. All 80 card columns may be used for any alphanumeric description desired. (FORMAT 20A4)

Card Type III: This card gives the total number of armament, aircraft and cargo payload data cards which follow in the data deck. The maximum number is 20. This number should be entered on the card in columns 1 and 2 right justified. (FORMAT I2)

Card Type IV: This is a set of cards containing the armament, aircraft and cargo payload data. The number of these cards is the number entered in card type III. Each of the values entered on this card must contain a decimal point; descriptive data entered on this card is in alphanumeric characters. (FORMAT 5A4, 12F5.0)

Each of this type of card must have the following format:

Columns 1-20: Any alphanumeric title describing the remainder of the data on the card.

Columns 21-25: Cargo weight in tons.

Columns 26-30: Cargo vertical center of gravity entered as the ratio of the expected cargo vertical center (VCG) divided by the depth of the ship to the main deck, D.

Columns 31-35: Group 7 weight in tons.

Columns 36-40: Group 7 vertical center of gravity location as the ratio of VCG/D.

Columns 41-45: Ammunition weight in tons.

Columns 46-50: Ammunition vertical center of gravity ratio,
VCG/D.

Columns 51-55: Aircraft weight in tons.

Columns 56-60: Aircraft vertical center of gravity ratio, VCG/D.

Columns 61-65: Electrical load in kilowatts.

Columns 66-70: Deckhouse area required for this payload item in
square feet.

Columns 71-75: Hull area requirement in square feet. If this
payload item has no specific requirement for
area in the deckhouse, all the arrangement area
required should be listed in the hull.

Columns 76-80: Group 7 acquisition cost in thousands of dollars
corrected to the year in which the cost estimate
is to be made.

Except for the moment arms, all the values input in these cards are summed by the MAIN program and only the sum is used in calculations. It makes no difference to the program whether these data are input on one or several cards. For each input card, however, the VCG/D value must apply to the weight which immediately precedes it. All values which are to be included in the total Group 7 light ship weight must be input on these cards. Any make up feed, hydraulic oil or similar special fluid must be included as a cargo item as the program does not account for them.

If there is no payload data, a 1 should be entered in column 2 of card type III and a single blank "payload" card should be included for card type IV.

Card Type V: This card gives the total number of electronics input data cards which follow in the data deck. The maximum number is 20. This number should be entered on the card right justified in columns 1 and 2. (FORMAT I2).

Card Type VI: This is a set of electronics input data cards. The number of these cards is the number entered in card type V. Each of these cards has the same format--a description of the input and a list of data for calculations. Each data entry must contain a decimal point. (FORMAT 5A4,6F5.0). Each card has the following format:

Columns 1-20: Any alphanumeric title describing the remainder of the data on the card.

Columns 21-25: Group 4 weight in tons.

Columns 26-30: Group 4 vertical center of gravity ratio, VCG/D.

Columns 31-35: Electrical load in kilowatts.

Columns 36-40: Deckhouse area required for this payload item in square feet.

Columns 41-45: Hull deck area required, that is, the remaining area required in square feet.

Columns 46-50: Group 4 acquisition cost in thousands of dollars corrected for the year in which the cost estimate is to be made.

These data may be arranged in any convenient way except that for each weight item there must be a VCG/D entry immediately following. It is particularly important to insure that only the required deck area is to be placed in the deckhouse; if an area may go either in the hull or deckhouse, it should be entered as a hull area.

This is the only way in which group 4 weights, vertical centers and costs are entered into the program. Therefore all group 4 weights to be entered into the light ship weight including navigation equipment must be entered on these cards.

If there is no electronics data, a 1 should be entered in column 2 of card type V and a single blank "electronics" card should be included for card type VI.

Card Type VII: This card is used to specify the number of officers, Chief Petty Officers and enlisted men comprising the crew. All numbers should be right-justified integers. (FORMAT 3I5).

Columns 1-5: Number of Officers.

Columns 6-10: Number of Chief Petty Officers.

Columns 11-15: Number of enlisted men.

Card Type VIII: This card is used to specify the cost indices and the labor rate to be used in computing the cost of the ship. Values for cost indices and labor rate are provided in Figures 31 and 32 in Section 6.12. Each of these values must contain a decimal point. (FORMAT 6F5.0) The values must be entered on the card as follows:

Columns 1-5: Labor rate in dollars per hour, for example, 5.85.

Columns 6-10: Group 1 cost index, for example, 1.65.

Columns 11-15: Group 2 cost index.

Columns 16-20: Group 3 cost index.

Columns 21-25: Group 5 cost index.

Columns 26-30: Group 6 cost index.

Card Type IX: This card contains the Military Mission Specifications.

All values on this card must contain a decimal point. (FORMAT 3F5.0).

Columns 1-5: Endurance days for dry provisions.

Columns 6-10: Weight of aircraft fuel in tons.

Columns 11-15: Vertical center of gravity ratio, VCG/D, for the
aircraft fuel.

Card Type X: This card gives the job option input (JOPT). Two options are available:

1-- which allows the user to input the sustained speed desired and have the computer calculate the required horsepower, and which requires the use of input card type XI A, or

2--which allows the user to input the machinery plant particulars and have the computer calculate the speed, and requires input card type XI B.

This control index must be entered in card column 2. (FORMAT I2)

Card Type XI A: This card describes the vehicle performance specifications. It is used when a JOPT value of 1 is specified on card Type X. All values require a decimal point. (FORMAT aFb.0)

The inputs are as follows:

Columns 1-5: Sustained speed in knots.

Columns 6-10: Endurance speed in knots.

Columns 11-20: Endurance range in nautical miles.

Columns 21-25: Propulsive coefficient.

Only one value of propulsive coefficient is input in this model. SWATH model test data have shown little variation in values of propulsive coefficient from approximately 0.74 to 0.70. A value of 0.70 is suggested for use in the program.

Card Type XI B: This card describes the machinery specifications. It is used when a JOPT value of 2 is specified on card type X. Due to the several possible arrangements and types of machinery plants applicable to the SWATH, this is a complex entry. The inputs are as follows:

Columns 1-5: Maximum sustained horsepower/1000. Requires a decimal point. (FORMAT F5.0)

Columns 6-10: Total group 2 weight in tons. Requires decimal.

Columns 11-15: Specific fuel consumption at maximum horsepower, pounds per shaft horsepower-hour. Requires decimal.

Columns 16-20: Specific fuel consumption at half horsepower, pounds per shaft horsepower-hour. Requires decimal.

Columns 21-25: Endurance speed in knots. Requires decimal.

Columns 26-35: Endurance range in nautical miles. Requires decimal.

Columns 36-40: Propulsion auxiliaries electrical load in kilowatts
Requires decimal point.

Columns 41-45: Propulsive coefficient. Requires decimal.

Columns 46-50: Group 2 acquisition cost in thousands of dollars,
corrected for inflation for the year in which the
cost estimate is to be made. Requires decimal.

Columns 51-55: Weight of lubricating oil, in tons. Requires decimal.

Column 56: Location of propulsor. The program accepts only the
value 1 for propulsor located in the hulls.
Integer.

Columns 57-61: Length of propulsor space in feet. Requires
decimal point.

Column 62: Location of prime mover. If the prime mover is to
be installed in the hulls the value of 1 should be
input; if the prime mover is to be located in the
box structure the value 2 should be used. Integer.

Columns 63-67: Length of the prime mover space in feet. Decimal.

Columns 68-72: Width of the prime mover space in feet. Decimal.

Columns 73-77: Height of the prime mover space in feet. Decimal.

Card Type XII: This card contains information about the options to be
used in the calculation and the basic input parameter for the program,
the ship size, expressed as length. The card must be of the follow-
ing format:

Columns 1-2: Machinery type option input. A right-justified
integer is entered in column 2. The various
options are:

MTYPE=0 - This causes the program to return to card type I
to read in new input data.

MTYPE=1 - A Diesel plant will be installed

MTYPE=2 - A Diesel-electric plant is specified.

MTYPE=3 - A gas turbine plant is specified.

MTYPE=4 - Specifies a gas turbine-electric plant.

If JOPT is 2 on card X, any value of MTYPE except 0 may be specified.

If an MTYPE value other than 0-4 is specified and horsepower required
is less than 30000 and the hull diameter is more than 18 feet, the program
defaults to Diesel propulsion located in the hulls. Allowing this default
option to occur is NOT recommended.

Columns 3-4: Materials Option. A right-justified integer is
entered in Column 4. The options are:

MOPT=1 - A steel hull and box with aluminum superstructure is
specified.

MOPT=2 - An all aluminum structure is specified.

Columns 5-9: Free Surface Correction in feet. Requires a deci-
mal point. The free surface correction need not
be a positive number; a negative free surface
correction is interpreted as a reduced value of KG.

Columns 10-14: Length of the ship's hull in feet. This entry
requires a decimal point.

Columns 15-19: Design and builders margin entered as a decimal
fraction such as 0.15. A margin of 15% is
commonly used for preliminary design studies
on SWATHS.

Card Type XII may be repeated many times using variations of length or options and the same payload description. Each card XII is interpreted as another design case. It is often advantageous to generate a range of ship sizes and types to assist in determining an optimum. It is suggested that due to the iteration required in the ship dimension routine length variations be started from shorter ships and continue to longer ships, however this is not required.

Card Type XIII: This card is an indicator which directs the computer to read a completely new input case with a new payload and performance description. A value of 0 in column 2 of this card will cause a new card type I to be read.

Card Type XIV: This card is a card type I. If more data is to follow, a value of 1 must be entered in column 1; if a value of 0 is entered in column 1, the computer will stop.

A sample listing of the required input data cards is given below. The data shown refers to a 240 foot Medium Endurance Cutter for Fisheries Law Enforcement.

1	GROUP 7	0.	0.	16.7	1.06	4.9	.8925.	1.1	15.	2000.	200.301.2
1	GROUP 4	90.	1.0	25.	887.	1239.2157.					
	13	10	80								
	5.80	2.25	2.18	1.63	1.84	1.98					
	20.91.	.11									
1	19.7	12.	3000.	.70							
2	1.5	240.	.15								
0											
1	***COAST GUARD SWATH SYNTHESIS MODEL*** 240 FT MEC FOR FLT MAY 76 GT \$ FY 76***										
1	GROUP 7	0.	0.	16.7	1.06	4.9	.8925.	1.1	15.	2000.	200.301.2
1	GROUP 4	90.	1.0	25.	887.	1239.2157.					
	13	10	80								
	5.80	2.25	2.18	1.63	1.84	1.98					
	20.91.	.11									
1	24.	12.	3000.	.70							
3	1.5	240.	.15								
0											
1	***COAST GUARD SWATH SYNTHESIS MODEL*** 240 FT MEC FOR FLT MAY 76 GT \$ FY 76***										
1	GROUP 7	0.	0.	16.7	1.06	4.9	.8925.	1.1	15.	2000.	200.301.2
1	GROUP 4	90.	1.0	25.	887.	1239.2157.					
	13	10	80								
	5.80	2.25	2.18	1.63	1.84	1.98					
	20.91.	.11									
2	32.	283.	.50	.64	12.	3000.	.70.	.708999.	5.251	35.1	27. 14. 14.
3	1.5	240.	.15								
0											

TABLE A-I
PAYLOAD DESCRIPTION DATA

A. SHIP SYSTEM LEVEL

Ship	Group	Weight	KG	KG/D	KW	DHAR	HLAR	Cost $\times 10^{-3}$
378' WHEC	400	11.30	22.99	.826				
	401	19.15	28.82	1.035				
	402	10.35	37.90	1.362				
	403	9.20	25.98	.934				
	404	29.03	34.58	1.043				
	450	5.44	29.65	1.065				
	4 Total	84.47	30.88	1.109	117.8	1307	468	2280
	700	25.66	38.87	1.397				
	701	2.23	20.02	.719				
	702	3.55	25.08	.901				
	750	2.08	24.97	.897				
	751	0.42	34.00	1.222				
	7 Total	33.95	35.27	1.267	46.46	1409	2256	196
210' WMEC	400	2.63	28.19	1.529				
	401	2.91	24.58	1.334				
	402	1.11	14.18	.769				
	403	5.45	19.26	1.045				
	404	3.42	43.93	2.384				
	450	3.15	38.97	2.114				
	4 Total	18.67	28.88	1.568	21.99	319		190
	700	3.40	32.46	1.761				
	701	2.00	21.00	1.139				
	702	1.60	16.50	.895				
	750	0.40	8.00	.434				
	751	0.						
	7 Total	7.40	24.59	1.334	0.0		385	76
SWATH CUTTER	4 Total	90.00	64.00	1.00				
	7 Total	16.70	67.50	1.055				
SWATH AGOR	4 Total	1.92			5.20			

TABLE A-I (Cont.)

3. PAYLOAD ITEM DESCRIPTIONS:

Item	Group	Weight Tons	KG refer- ence Main Dk	DHAR sq ft	HLAR sq ft	Cost x 10 ⁻³ 1968 dollars
ECM DE Basic	404	4.5	+15.5	270		260
ECM WLR-8	404	1.7	+12.	20	100	345
RADAR SPS 10 IFF	408	.9	+19.5	70		50
RADAR SPS 29	408	7.5	+	180		150
RADAR SPS 53	408	.14	+20.	15		14
RADIO DE non ASW	409	9.7	-5.5		800	270
RADIO small ship	409	4.0	+5.	200	100	60
SONAR UQN-4	412	.5	+10.	10		23
SONAR ETAS	412	22.8	+4.		210	1670
SONAR 505	412	8.5	9.0		440	530
NTDS DDG	413	40.0	+15.5	1350		3800
GFCS MK 86	402	7.93	+20.	350		2640
GFCS MK 56	402	10.6			160	110
GFCS MK 92	402	10.0	+15	180		3120
NIXIE	403	10.0				59
FCS CHAFFROC	405	.5	+25.	50		64
FCS HARPOON	405	.4	+30.	20		347
UBFCS MK 116	406	6.	+13.	90		833
LAMPS CONTROL	406	9.4	+20.	300		2300
LAMPS PACKAGE	406	.4	+13.	25		587
5"/38 SM	700	29.7	+8.	180	70	55
50 cal. MG	700	.15	+15.			2
76mm OTO MELARA	700	6.0	+10.		100	430
CHAFFROC	704	1.3	+36.	100		100
HARPOON						
LAUNCHER	704	66.0	-3.			2700
HARPOON BOX/4	704	3.84	+14.	100		44
TT MK 32 TRIPLE	708	3.5	+3.			27
LAMPS HELOS (2)	805	17.86	+7.			
SRR HELO		7.	+9.7			
HH-3 HELO		9.8	+9.7			
76mm ROUND		.015				
5"/38 ROUND		.0435				
CHAFFROC		.048				
MK 48 TORPEDO		1.78				

APPENDIX B
PROGRAM LISTING


```

REAL LEN,KGIRY,NOFF,NCPO,NENL
REAL MCST
COMMON/AA/ENDDAY,NOFF,NCPO,NENL
COMMON/BB/CN,DHV,ENCVOL,DT,AREADH,AREAHL,LEN
COMMON/CC/SHPM,SHPE,VSUS,VEND,RSEND, SPCMHP,SPCHHP,MTYPE,JOPT
1,HOPT,PC
COMMON/DD/ELKW,AVGKW,ELoad,BLOAD,PALOAD
COMMON/EE/GR4WI(20),GR4CG(20),GR7WT(20),GR7CG(20),AMOWT(20),
1AMOCG(20),ACWT(20),ACCG(20), CARGOW(20),CARGOC(20)
COMMON/FF/TITLE(5,40),HEAD(20),NOARM,NOELT
COMMON/GG/FRSC,KGTRY,DETRY,DH,BBOX,ES,XLS,CWP
COMMON/HH/CGFUEL,CGLO,CGCREW,CGPE,CGPS,CCARGO,CGAMMO,CGAC,CACFUL
COMMON/JJ/H,SEP,XLB,DB,AG,XP,MBLOC1,MBLOC2
COMMON/KK/ELLD(20),DHAR(20),HLAR(20),ELD(20),DHA(20),HLA(20)
1,GR7CST(20),GR4CST(20)
COMMON/LL/ATFUEL,WILO,WICREW,WTPS,WCARGO,WTAMMO,WTAC,WACFUL
COMMON/MM/CSTG1,CSTG2,CSTG3,CSTG4,CSTG5,CSTG6,CSTG7,DCST,CCST,MCST
COMMON/NN/DOLHR,G1IND,G2IND,G3IND,G5IND,TOTCST
COMMON/OO/XMLOC1,YMLOC1,XMLOC2,YMLOC2,ZMLOC2
COMMON/RR/IREAD,IWRITE
COMMON/SS/SHF(12),AKNOT(12)
COMMON/WW/WTG1,WTG2,WTG3,WTG4,WTG5,WTG6,WTG7,WLSHIP,WFULLD,DBMAR
IREAD=5
IWRITE=6
2 READ(IREAD,124) INDEX
124 FORMAT(I1)
IF(INDEX.EQ.0) STOP
READ(IREAD,123) (HEAD(I),I=1,20)
123 FORMAT(20A4)
C ARMAment, AIRCRAFT AND CARGO INPUT
READ(IREAD,100) NOARM
100 FORMAT(I2)
READ(IREAD,101) (TITLE(J,I),J=1,5),CARGOW(I),CARGOC(I),GR7WT(I),
1GR7CG(I),AMOWT(I),AMOCG(I),ACWT(I),ACCG(I),ELLD(I),DHAR(I),
2HLAR(I),GR7CST(I),I=1,NOARM)
101 FORMAT(5A4,12F5.0)

```


C SUMS FOR PAYLOAD DATA

WCARGO=0.

WTG7=0.

WTAMMO=0.

WTAC=0.

ELOAD=0.

BLOAD=0.

AREADH=0.

AREAHL=0.

CSTG7=0.

DO 10 I=1,NOARM

WCARGO=WCARGO+CAK30W(I)

WTG7=WTG7+GR7WT(I)

WTAMMO=WTAMMO+AMOWT(I)

WTAC=WTAC+ACWT(I)

BLOAD=BLOAD+ELLD(I)

GR7CST(I)=GR7CST(I)*1000.

CSTG7=CSTG7+GR7CST(I)

AREADH=AREADH+DHAR(I)

AREAHL=AREAHL+HLAR(I)

ELECTRONICS INPUT

READ(IREAD,102) NOELT

102 FORMAT(I2)

READ(IREAD,103) ((TITLE(J,I+20),J=1,5),GR4WT(I),GR4CG(I),ELD(I),

1DHA(I),HLA(I),GR4CST(I),I=1,NOELT)

103 FORMAT(5A4,6F5.0)

C GROUP 4 WEIGHTS INCLUDED IN WLSHIP

C SUM ELECTRONICS DATA

WTG4=0.

CSTG4=0.

DO 11 I=1,NOELT

WTG4=WTG4+GR4WT(I)

ELOAD=ELOAD+ELD(I)

GR4CST(I)=GR4CST(I)*1000.

CSTG4=CSTG4+GR4CST(I)

AREADH=AREADH+DHA(I)

MAIN0037
MAIN0038
MAIN0039
MAIN0040
MAIN0041
MAIN0042
MAIN0043
MAIN0044
MAIN0045
MAIN0046
MAIN0047
MAIN0048
MAIN0049
MAIN0050
MAIN0051
MAIN0052
MAIN0053
MAIN0054
MAIN0055
MAIN0056
MAIN0057
MAIN0058
MAIN0059
MAIN0060
MAIN0061
MAIN0062
MAIN0063
MAIN0064
MAIN0065
MAIN0066
MAIN0067
MAIN0068
MAIN0069
MAIN0070
MAIN0071
MAIN0072

MAIN0073
MAIN0074
MAIN0075
MAIN0076
MAIN0077
MAIN0078
MAIN0079
MAIN0080
MAIN0081
MAIN0082
MAIN0083
MAIN0084
MAIN0085
MAIN0086
MAIN0087
MAIN0088
MAIN0089
MAIN0090
MAIN0091
MAIN0092
MAIN0093
MAIN0094
MAIN0095
MAIN0096
MAIN0097
MAIN0098
MAIN0099
MAIN0100
MAIN0101
MAIN0102
MAIN0103
MAIN0104
MAIN0105
MAIN0106
MAIN0107
MAIN0108

```
11 AREABL=AREABL+HLA(I)
G4CST=CSTG4
G7CST=CSTG7
C MANNING INPUT
  READ(IREAD,104) NOOFF,NOCPO,NJCREW
104 FORMAT(3I5)
  NOFF=FLOAT(NOOFF)
  NCPO=FLOAT(NOCPO)
  NENL=FLOAT(NOCREW)
C COST INDICES INPUT
  READ(IREAD,110) DOLHR,G1IND,G3IND,G5IND,G6IND
110 FORMAT(6F5.0)
C MILITARY MISSION CONSUMABLES INPUT
  READ(IREAD,105) ENDDAY,WACFUL,CACFUL
105 FORMAT(3F5.0)
  HPMS=0.
  GR2CST=0.
C JOB OPTION INPUT
C (1 COMPUTE MAX HP, 2 COMPUTE SPEED)
  READ(IREAD,106) JOPT
106 FORMAT(I2)
  IF(JOPT.EQ.2) GOTO 1
  VEHICLE PERFORMANCE INPUT
  READ(IREAD,107) VSUS,VEND,RGEND,PC
107 FORMAT(2F5.0,F10.0,F5.0)
  GOTO 9
C MACHINERY SPECIFICATIONS INPUT
  1 READ(IREAD,108) HPMS,WTG2,SFCMHP,SFCHHP,VEND,RGEND,PALOAD,PC,
1CSTG2,WTLO,MBLOC1,XMLOC1,MBLOC2,YMLOC2,ZMLOC2
108 FORMAT(5F5.0,F10.0,4F5.0,I1,F5.0,I1,3F5.0)
  HPMS=HPMS*1000.
  CSTG2=CSTG2*1000.
  GR2CST=CSTG2
C OPTIONS INPUT
  9 READ(IREAD,109) MTYPE,MOPT,FRSC,LEN,DBMAR
109 FORMAT(2I2,3F5.0)
```



```

C
C
MTYP=1 DIESEL,MTYPE=2 DIESEL-ELECTRIC,MTYPE=3 GAS TURBINE,MTYPE=4 GT-ELEC
MOPT=1 STEEL HULL AND BOX W/ALUM. DECKHOUSE, MOPT=2 ALL ALUMINUM SHIP
IF(MTYPE.EQ.0) GOTO 2
DBMAR=1.+DBMAR
CSTG2=GR2CST
CSTG4=G4CST
CSTG7=G7CST
KGTRY=LEN/(.0036786*LEN+5.5368)
DPTRY=.004606265*LEN**2.427
CN=105.048*LEN+6.196155*LEN*LEN+.005973*LEN*LEN*LEN
CALL XECUTE(HPMS)
GO TO 9
END
MAIN0109
MAIN0110
MAIN0111
MAIN0112
MAIN0113
MAIN0114
MAIN0115
MAIN0116
MAIN0117
MAIN0118
MAIN0119
MAIN0120
MAIN0121

```


XECU0001
 XECU0002
 XECU0003
 XECU0004
 XECU0005
 XECU0006
 XECU0007
 XECU0008
 XECU0009
 XECU0010
 XECU0011
 XECU0012
 XECU0013
 XECU0014
 XECU0015
 XECU0016
 XECU0017
 XECU0018
 XECU0019
 XECU0020
 XECU0021
 XECU0022
 XECU0023
 XECU0024
 XECU0025
 XECU0026
 XECU0027
 XECU0028
 XECU0029
 XECU0030
 XECU0031
 XECU0032
 XECU0033
 XECU0034
 XECU0035
 XECU0036

```

SUBROUTINE XECUTE(HPMS)
  REAL LEN,KGTRY
  COMMON/BB/CN,DHV,ENCVOL,DT,AREADH,AREAH,LEN
  COMMON/CC/SHPM,SHPE,VSUS,VEND,RGEND,      SFCMHP,SFCHHP,MTYPE,JOPT
1,MOPT,PC
  COMMON/GG/FRSC,KGTRY,DPTRY,DH,BBOX,BS,XLS,CWP
  COMMON/II/JNDEX,LNDEX
  COMMON/RR/IREAD,K
  COMMON/SS/SHP(12),AKNOT(12)
  COMMON/WW/WT:1,WTG2,WTG3,WTG4,WTG5,WTG6,WTG7,WLSHIP,WPULLD,DBMAR
  DIMENSION AE(50)
  EXCKG=0.
  JNDEX=1
  LNDEX=1
7 CALL DIM(R)
  IF(LEN.LT.0.) GOTO 999
  REMOVE THE FOLLOWING CARD FOR AN UNRESTRICTED RUN
  IF(JNDEX.GT.5.OR.LNDEX.GT.5) GO TO 99
  CALL HPCALC
  IF(LEN.LT.0.) GOTO 998
  CALL UGLYDK(10,1,1,AKNOT,SHP,ESL,ESR,AE)
  IF(JOPT.EQ.2) GOTO 1
  CALL EVALDK(10,1,AKNOT,VSUS,SHPM,AE)
  CALL EVALDK(10,1,AKNOT,VEND,SHPE,AE)
  SHPM=SHPM/.8
  GO TO 99
1 VMAX=(HPMS*200./LEN)**.33333
4 CALL EVALDK(10,1,AKNOT,VMAX,SHP1,AE)
  VMAX1=.95*VMAX
  CALL EVALDK(10,1,AKNOT,VMAX1,SHP2,AE)
  DELHP=(SHP1-SHP2)/(VMAX-VMAX1)
  VMAX1=VMAX-(SHP1-.8*HPMS)/DELHP
  IF(ABS(VMAX1-VMAX).LE.VMAX1*.005) GOTO 3
  VMAX=VMAX1
  GOTO 4
3 VSUS=VMAX1

```



```

SHPM=HPMS
CALL EVALDK (10,1,AKNOT,VEND,SHPE,AE)
99 CONTINUE
  IF(MTYPE.EQ.1) GO TO 100
  IF(MTYPE.EQ.2) GO TO 200
  IF(MTYPE.EQ.3) GO TO 300
  IF(SHPM.GT.30000..OR.DH.LT.(10.+.0003*SHPM)) GO TO 997
  GO TO 500
100 CONTINUE
  IF(SHPM.GT.14000..OR.DH.LT.14.) GO TO 997
  GO TO 500
200 CONTINUE
  IF(SHPM.GT.30000..OR.DH.LT.(10.+.0003*SHPM)) GO TO 997
  GO TO 500
300 CONTINUE
  IF(SHPM.GT.8000..AND.BS.LT.6.) GO TO 997
  IF(SHPM.GT.70000.) GO TO 997
500 CONTINUE
  CALL EPLANF
  CALL LIQ
  IF(JOPT.EQ.2) GOTO 6
  CALL MACHBX
  CALL VOLUME
  IF(LEN.LT.0.) GOTO 996
  CALL HEIGHT
  IF(ABS(WFULD-DPTRY).LT.9.) GO TO 8
  IF(LNDEX.GE.2) GOTO 9
  NHALF=1
  FACTOR=.6
  GO TO 63
  9 FACTOR=(DPTRY-WFULD-DP1+WT1)/(DPTRY-DP1)
  03 DP1=DPTRY
  WT1=WFULD
  DPTRY=DPTRY-(DPTRY-WFULD)/FACTOR
  IF(FACTOR.GE.0.) GO TO 10
  IF(DPTRY.LT.0.) GO TO 60
XECU0037
XECU0038
XECU0039
XECU0040
XECU0041
XECU0042
XECU0043
XECU0044
XECU0045
XECU0046
XECU0047
XECU0048
XECU0049
XECU0050
XECU0051
XECU0052
XECU0053
XECU0054
XECU0055
XECU0056
XECU0057
XECU0058
XECU0059
XECU0060
XECU0061
XECU0062
XECU0063
XECU0064
XECU0065
XECU0066
XECU0067
XECU0068
XECU0069
XECU0070
XECU0071
XECU0072

```



```

DPTRY=(.8**NHALF)*DP1
GO TO 85
60 DPTRY=(2.**NHALF)*DP1
65 NHALF=NHALF+1
10 IF(LNDEX.GT.20) GOTO 995
LNDEX=LNDEX+1
GOTO 7
9 CONTINUE
LNDEX=1
CALL VCG(CFULLD)
IF(ABS(CFULLD-KGTRY).LT.1.) GO TO 11
IF(JNDEX.GT.21) GOTO 994
IF(CFULLD.LT.KGTRY) GOTO 12
13 KGTRY=(CFULLD+KGTRY)/2.
JNDEX=JNDEX+1
GOTO 7
12 IF(R.LT..1) GO TO 13
EXCKG=KGTRY-CFULLD
11 CONTINUE
CALL COST(LEN)
CALL OUTPUT(EXCKG,2)
RETURN
994 CALL OUTPUT(0.,1)
WRITE(K,106)
106 FORMAT(///' NO BALANCE BETWEEN ASSUMED AND CALC KG WITHIN 1.0 FEET
1 COULD BE MADE IN 20 ITERATIONS'///)
GOTO 1000
995 CALL OUTPUT(0.,1)
WRITE(K,105)
105 FORMAT(///' NO BALANCE BETWEEN WEIGHT AND DISPLACEMENT WITHIN 5
1 TONS COULD BE MADE IN 20 ITERATIONS'///)
GOTO 1000
996 CALL OUTPUT(0.,1)
WRITE(K,104)
104 FORMAT(///' TOO LARGE A VOLUME REQUIRED FOR SOLUTION USING INPUT
1 LENGTH, TRY A LONGER SHIP'///)

```

XECU00073
XECU00074
XECU00075
XECU00076
XECU00077
XECU00078
XECU00079
XECU00080
XECU00081
XECU00082
XECU00083
XECU00084
XECU00085
XECU00086
XECU00087
XECU00088
XECU00089
XECU00090
XECU00091
XECU00092
XECU00093
XECU00094
XECU00095
XECU00096
XECU00097
XECU00098
XECU00099
XECU0100
XECU0101
XECU0102
XECU0103
XECU0104
XECU0105
XECU0106
XECU0107
XECU0108

XECU0109
 XECU0110
 XECU0111
 XECU0112
 XECU0113
 XECU0114
 XECU0115
 XECU0116
 XECU0117
 XECU0118
 XECU0119
 XECU0120
 XECU0121
 XECU0122
 XECU0123
 XECU0124
 XECU0125
 XECU0126

```

GOTO 1000
997 CALL OUTPUT(C.,1)
    WRITE(K,103)
103 FORMAT('///' MACHINERY TYPE SELECTION,SHIP SIZE OR HORSEPOWER REQUI
    REMENTS OUTSIDE MODEL LIMITS.'/' INPUT MACHINERY DATA FOR MTYPE=3
20R JOPT=2'///)
GOTO 1000
998 CALL OUTPUT(C.,1)
    WRITE(K,101)
101 FORMAT('///' HPCALC ERROR. CHECK INPUTS'///)
GOTO 1000
999 CALL OUTPUT(C.,1)
    WRITE(K,1001)
1001 FORMAT('///' SHIP PARAMETER INPUT GIVES DIMENSIONS OUT OF RANGE'//)
1000 WRITE(K,102)
102 FORMAT(' PROGRAM PROCEEDING TO NEXT INPUT CASE'///)
    RETURN
    END
  
```


SUBROUTINE DIM(R)
 REAL LEN,KGTRY
 COMMON/BB/CN,DHV,ENCVOL,DT,AREADH,AREAHL,LEN
 COMMON/GG/FRSC,KGTRY,DISP,DH,BBOX,BSTR,STRL,CWP
 COMMON/JJ/H,SEP,XLB,DB,AG,XF,MBLOC1,MBLOC2
 DPTRY=DISP/1.014
 RLENDH=12.33+.013*LEN
 THIS CALCULATION APPROXIMATES HULLS AS ELLIPTICAL NOSES OF LENGTH
 3 DH, A PARALLEL MIDDLE BODY AND A CONICAL TAIL OF LENGTH 5 DH.
 DH=LEN/RLENDH
 2 VPMB=(LEN-8.*DH)*DH*.785398
 THERE WILL ALWAYS BE SOME PARALLEL MIDDLE BODY. L/D = 10 MIN.
 IF(LEN-8.*DH.LT.2.*DH) GO TO 1000
 VAB=1.30899*DH*DH*DH
 VPB=1.57079*DH*DH*DH
 VHULS=2.*(VPMB+VAB+VPB)
 IF(VHULS/35..GT..55*DPTRY) GO TO 3
 DH=DH+.25
 GO TO 2
 3 H=1.75*DH
 VCNTS=1.6*DPTRY
 STRUT SIZING BASED ON STABILITY REQUIREMENTS, CHECK DISPLACEMENT,
 GML,GMF. STRUT BEAM INCREMENTED LAST FOR RESISTANCE PURPOSES
 BSTR=.42*DH
 BSTRS=4.
 6 BS=AMAX1(ESTR,BSTRS)
 CWP=.34
 9 STRL=.4*LEN
 10 VSTRIS=2.*((STRL*BS*CWP)*(H-DH)+STRL*(.5*BS*(DH-.5*DH*SQRT(1.-BS*
 1BS/(DH*DH)))-.25*DH*DH*ARSIN(BS/DH)))
 SVI=VHULS+VSTRIS+VCNTS
 DPTRY1=SVT/35.
 IF(ABS(DPTRY1-DPTRY).LE.5.) GO TO 20
 R1=STRL/LEN
 IF(R1.GE..80) GO TO 15
 STRL=STRL+1.


```

GO TO 10
15 CONTINUE
  IF(CWP.GE..94) GO TO 30
  CWP=CWP+.002
  GO TO 10
30 R2=BS/DH
  IF(R2.GT..55) GO TO 1000
  BS=BS+.05
  GO TO 10
20 FKB=(VHULS*DH*.5+VSTARTS*(DH+.5*(H-DH))+VCNTS*DH*.5)/SVT
  FBG=KGTRY-FKB
  AWP=STAL*BS*CWP
  CIL=-4.2491+5.2141*CWP
  GML=2.*CIL*STRL*STRL*STRL*BS/SVT-FBG
  IF(GML.GE..1*STRL) GO TO 40
  GO TO 1000
40 CONTINUE
  CHANGE GMT WITH SEPARATION PARAMETER
  SEP=.22*LEN
  GMT=.2*DH
  SEPT=.4*LEN
41 GMT1=SEP*SEP*AWP/(2.*SVT)-FBG-FRSC
  IF(GMT1.GT.GMT) GO TO 50
  IF(SEP.GT.SEPT) GO TO 1000
  SEP=SEP+1.
  GO TO 41
50 CONTINUE
  BSTR=BS
  R=FKB+SEP*SEP*AWP/(2.*SVI)-FRSC-GMT1-KGTRY
  PLACE STRUT ON HUL
  XF=.52*LEN
  SIZE BOX
  XLB=STRL+20.
  BBOX=SEP+DH
  DB=13.
  AG=1.+0.07*LEN

```

```

DIM 0037
DIM 0038
DIM 0039
DIM 0040
DIM 0041
DIM 0042
DIM 0043
DIM 0044
DIM 0045
DIM 0046
DIM 0047
DIM 0048
DIM 0049
DIM 0050
DIM 0051
DIM 0052
DIM 0053
DIM 0054
DIM 0055
DIM 0056
DIM 0057
DIM 0058
DIM 0059
DIM 0060
DIM 0061
DIM 0062
DIM 0063
DIM 0064
DIM 0065
DIM 0066
DIM 0067
DIM 0068
DIM 0069
DIM 0070
DIM 0071
DIM 0072

```



```
IF(LEN.GE.200.) A3=15.  
RETURN  
1000 LEN=-10.0  
RETURN  
END
```

```
DIM 0073  
DIM 0074  
DIM 0075  
DIM 0076  
DIM 0077
```


SUBROUTINE HPCALC

REAL LEN

COMMON/BB/CN,DHV,ENCVOL,DT,AREADH,AREAHL,LEN

COMMON/CC/SHPM,SHPE,VSUS,VEND,RGEND, SFCMHP,SECHHP,MTYPE,JOPT

1,MOPT,PC

COMMON/GG/FRSC,KGTRY,TONS,DH,BBOX,TA,CA,CWP

COMMON/JJ/H,SEP,XLB,DB,AG,XA,MBLOC1,MBLOC2

COMMON/SS/POW(12),VKNTS(12)

DOUBLE PRECISION BN,BT,QN,QT

INPUT SHIP CHARACTERISTICS

L = NUMBER OF HULL SEGMENTS +2, NOT COUNTING THE NOSE AND TAIL.

THERE WILL BE NO CONTROL SURFACES IN THIS CALCULATION

THIS CALCULATION ASSUMES ELLIPTICAL NOSES AND PARABOLIC TAILS ON

THE HULLS AND FULLY PARABOLIC STRUTS WITH NO TAPER. ONLY ONE STRUT

AND TWO HULL CASES ARE ALLOWED. THE LENGTHS OF THE NOSES AND TAILS

ARE TAKEN AS 3 TIMES DH AND 5 TIMES DH RESPECTIVELY.

VOL=0.0

AREA=0.0

PI = 3.1415926536

YA=3.*TA

EA=CA-8.*TA

DELT=0.

W=9.*LEN

EFHG=DB

F=H-0.5*DH

AN = LENGTH OF NOSE SECTION

AT = LENGTH OF TAIL SECTION

AN=3.*DH

AT=5.*DH

WETTED SURFACE AREA AND VOLUME OF TAILS

VOLT = VOLUME OF A SINGLE TAIL SECTION

VOLT2 = VOLUME OF BOTH TAIL SECTIONS

ARET = WETTED SURFACE AREA OF A SINGLE TAIL SECTION

ARET2 = WETTED SURFACE AREA OF BOTH TAIL SECTIONS

PARABOLIC TAIL

66 ARET=0.66666*PI*AT*DH

HPCL0001
HPCL0002
HPCL0003
HPCL0004
HPCL0005
HPCL0006
HPCL0007
HPCL0008
HPCL0009
HPCL0010
HPCL0011
HPCL0012
HPCL0013
HPCL0014
HPCL0015
HPCL0016
HPCL0017
HPCL0018
HPCL0019
HPCL0020
HPCL0021
HPCL0022
HPCL0023
HPCL0024
HPCL0025
HPCL0026
HPCL0027
HPCL0028
HPCL0029
HPCL0030
HPCL0031
HPCL0032
HPCL0033
HPCL0034
HPCL0035
HPCL0036


```

VOLT=2.0/15.0*PI*AT*DH*DH
67 CONTINUE
VOLT2 = 2.0*VOLT
ARET2 = 2.0*ARET
C WETTED SURFACE AREA AND VOLUME OF HULLS
C VH = VOLUME OF A SINGLE HULL SEGMENT
C VOLH = VOLUME OF A SINGLE HULL, NO NOSE OR TAIL.
C VOLH2 = VOLUME OF BOTH HULLS, NO NOSE OR TAIL SECTIONS
C AH = AREA OF A SINGLE HULL SEGMENT.
C AREH = AREA OF A SINGLE HULL, NO NOSE OR TAIL.
C AREH2 = AREA OF BOTH HULLS, NO NOSE OR TAIL SECTIONS
C SL = HULL SEGMENT LENGTH
SL=LEN-8.*DH
IF (SL.GT.0.0) GO TO 68
GO TO 1000
68 VOLH=PI/4.*(DH*DH*SL)
AREH=PI*DH*SL
VOLH2 = 2.0*VOLH
AREH2 = 2.0*AREH
C WETTED SURFACE AREA AND VOLUME OF NOSES
C VOLN = VOLUME OF SINGLE NOSE SECTION
C VOLN2 = VOLUME OF BOTH NOSE SECTIONS
C AREN = SURFACE AREA OF SINGLE NOSE SECTION
C AREN2 = AREA OF BOTH NOSE SECTIONS
C PROLATE SPHEROID
50 EN= SQRT(1.0-DH*DH*0.25/(AN*AN))
AREN=PI*DH*(DH/4.+AN/2./EN*ARSIN(EN))
VOLN=PI/6.C*AN*DH**2
VOLN2 = 2.0*VOLN
AREN2 = 2.0*AREN
C VOLHT = TOTAL VOLUME OF SINGLE HULL WITH NOSE AND TAIL SECTIONS.
C VOLHT2 = TOTAL VOLUME OF BOTH HULLS WITH NOSE AND TAIL SECTIONS.
C VOLHT = VOLN+VOLT+VOLH
C VOLHT2 = 2.0*VOLHT
C WETTED SURFACE AREA AND VOLUME OF STRUTS
C VOLAS = VOLUME OF AFT STRUT

```

```

HPCL0037
HPCL0038
HPCL0039
HPCL0040
HPCL0041
HPCL0042
HPCL0043
HPCL0044
HPCL0045
HPCL0046
HPCL0047
HPCL0048
HPCL0049
HPCL0050
HPCL0051
HPCL0052
HPCL0053
HPCL0054
HPCL0055
HPCL0056
HPCL0057
HPCL0058
HPCL0059
HPCL0060
HPCL0061
HPCL0062
HPCL0063
HPCL0064
HPCL0065
HPCL0066
HPCL0067
HPCL0068
HPCL0069
HPCL0070
HPCL0071
HPCL0072

```



```

C CA = CHORD OF AFT STRUT
C YA = LENGTH OF AFT STRUT NOSE
C EA = LENGTH OF AFT STRUT CENTER SECTION
C WA = LENGTH OF AFT STRUT TAIL
C XAT = DISTANCE TO REAR OF AFT STRUT
C XATC = DISTANCE TO FRONT OF AFT STRUT TAIL
C XA = DISTANCE TO CENTER OF AFT STRUT
C XANC = DISTANCE TO REAR OF AFT STRUT NOSE
C XAN = DISTANCE TO FRONT OF AFT STRUT
C DELT = PERCENT CHANGE IN THICKNESS OF STRUT (+ OR -) IN FEET PER FOOT DEPTH
C TA = THICKNESS OF CENTER OF AFT STRUT AT WATERLINE
C F = DEPTH OF HULL CENTERLINE
C TX = THICKNESS AT ARBITRARY POSITION IN STRUT AT WATERLINE.
C TZ = THICKNESS OF STRUT AT THE POSITION OF TX AND DEPTH Z.
      VOLAS = 0.0
      DELA = 0.0
      ASIA = 0.0
      WA = CA-YA-EA
      XAT = XA-CA/2.0
      XAN = XA+CA/2.0
      XANC = XAN-YA
      XATC = XAT+WA
      NFLAG = 0
      IFLAG = 0
C XS = ARBITRARY LENGTH POSITION FOR VOLUME INTEGRATION
C DEL = INCREMENTAL LENGTH THAT STRUT IS DIVIDED INTO FOR FOLLOWING ITERATION
      DEL = CA/500.0
      XS = XAT
      DO 500 M = 1,501
      IF(XS.LT.XATC) GO TO 501
      IF(XS.LT.XANC) GO TO 502
      XSS = XS-XANC
      TX = TA*(1.0-(XSS/YA)**2)
      GO TO 503
C CALCULATE POSITION IN STRUT NOSE AND THICKNESS AT WATERLINE
C TX FOR PARABOLIC NOSE

```

HPCL00073
 HPCL00074
 HPCL00075
 HPCL00076
 HPCL00077
 HPCL00078
 HPCL00079
 HPCL00080
 HPCL00081
 HPCL00082
 HPCL00083
 HPCL00084
 HPCL00085
 HPCL00086
 HPCL00087
 HPCL00088
 HPCL00089
 HPCL00090
 HPCL00091
 HPCL00092
 HPCL00093
 HPCL00094
 HPCL00095
 HPCL00096
 HPCL00097
 HPCL00098
 HPCL00099
 HPCL0100
 HPCL0101
 HPCL0102
 HPCL0103
 HPCL0104
 HPCL0105
 HPCL0106
 HPCL0107
 HPCL0108


```

1ZA**2)
C MAKE COMPUTATIONS AND ADDITIONS FOR NATURAL STRUT HULL INTERSECTION
TTD = TZ/DIA
THETA=ARSIN(TTD)
DDZ = 0.5*DIA*(1.0-SQRT(1.0-TTD*TTD))
ASIA = ASIA+DIA*THETA*SQR(((DIA-DIA1)/2.0)**2+DEL**2)
VOLAS = VOLAS+(TZ*(DDZ+DIA/2.0)/(THEIA*DIA**2)/4.0)*DEL
DELA = DELA+DDZ*SQR(((TX-TX1)/2.0)**2+DEL**2)
GO TO 506
506 DIA1 = DIA
TX1 = TX
Z1 = Z
C VOLAST = VOLUME OF AFT STRUT TAIL
C VOLASC = VOLUME OF AFT STRUT CENTER SECTION
C VOLASN = VOLUME OF AFT STRUT NOSE
IF(XS.LT.XATC) GO TO 499
IF(NFLAG.EQ.0) VOLAST = VOLAS
NFLAG = 1
IF(XS.LT.XANC) GO TO 499
IF(IFLAG.EQ.0) VOLASC = VOLAS-VOLAST
IFLAG = 1
499 XS = XS+DEL
500 CONTINUE
VOLASN = VOLAS-VOLASC-VOLAST
C AREAS = WETTED SURFACE AREA OF SINGLE AFT STRUT
C AREAS2 = WETTED SURFACE AREA OF BOTH AFT STRUTS
AREAS = 2.0*DELA
AREAS2 = 2.0*AREAS
C IF SINGLE STRUT CONFIGURATION, SET FORWARD STRUT VALUES TO 0.0
110 VOLFS = 0.0
PSIA = 0.0
DELF = 0.0
VOLFST = 0.0
VOLFSC = 0.0
VOLFSN = 0.0
CF=0.

```

HPCL0145
 HPCL0146
 HPCL0147
 HPCL0148
 HPCL0149
 HPCL0150
 HPCL0151
 HPCL0152
 HPCL0153
 HPCL0154
 HPCL0155
 HPCL0156
 HPCL0157
 HPCL0158
 HPCL0159
 HPCL0160
 HPCL0161
 HPCL0162
 HPCL0163
 HPCL0164
 HPCL0165
 HPCL0166
 HPCL0167
 HPCL0168
 HPCL0169
 HPCL0170
 HPCL0171
 HPCL0172
 HPCL0173
 HPCL0174
 HPCL0175
 HPCL0176
 HPCL0177
 HPCL0178
 HPCL0179
 HPCL0180

HPCL0181
HPCL0182
HPCL0183
HPCL0184
HPCL0185
HPCL0186
HPCL0187
HPCL0188
HPCL0189
HPCL0190
HPCL0191
HPCL0192
HPCL0193
HPCL0194
HPCL0195
HPCL0196
HPCL0197
HPCL0198
HPCL0199
HPCL0200
HPCL0201
HPCL0202
HPCL0203
HPCL0204
HPCL0205
HPCL0206
HPCL0207
HPCL0208
HPCL0209
HPCL0210
HPCL0211
HPCL0212
HPCL0213
HPCL0214
HPCL0215
HPCL0216

```

C AREFS = WETTED SURFACE AREA OF SINGLE FORWARD STRUT
C AREFS2 = WETTED SURFACE AREA OF BOTH FORWARD STRUTS
111 AREFS = 2.0*DELF
    AREFS2 = 2.0*AREFS
C VOLFS2 = VOLUME OF BOTH FORWARD STRUTS
C VOLAS2 = VOLUME OF BOTH AFT STRUTS
    VOLFS2 = 2.0*VOLFS
    VOLAS2 = 2.0*VOLAS
C WPLA = INTERSECTION AREA OF SINGLE HULL AND STRUTS
C WPLA2 = INTERSECTION AREA OF BOTH HULLS AND STRUTS
    WPLA = ASIA+PSIA
    WPLA2 = 2.0*WPLA

***      MEAN STRUT DEPTHS      ***
C ZAP,ZAC,ZAN ARE MEAN DEPTHS OF AFT STRUT TAIL,CENTER,AND NOSE SECTION
457 ZAT= 1.5*VOLASI/(WA*TA)
    ZAN= 1.5*VOLASN/(YA*TA)
C IF NO CENTER SECTION SET ZAC
    ZAC= ZAT
    IF (ABS(EA).GE.0.0001*CA) ZAC=VOLASC/(EA*TA)
459 AREAF = 0.0
    AREAF2 = 0.0
    AREFF = 0.0
    AREFF2 = 0.0
    VOLAF = 0.0
    VOLAF2 = 0.0
    VOLFF = 0.0
    VOLFF2 = 0.0
    WAF = 0.0
    CFINF=0.
    CFINA=0.
C ARUD = WETTED SURFACE AREA OF SINGLE RUDDER
C APGD = WETTED SURFACE AREA OF SINGLE PROP GUARD
460 ARUD=0.
    APGD=0.
C VOL = TOTAL VOLUME OF ALL SUBMERGED PARTS FOR SINGLE HULL
C VOL2 = TOTAL VOLUME OF ALL SUBMERGED PARTS FOR DUAL HULL

```



```

VOL = VOL1+VOLN+VOLH+VOLFS+VOLAS+VOLFF+VOLAF
VOL2 = 2.0*VOL
C AREA1 = TOTAL WETTED AREA OF SINGLE HULL WITH NOSE AND TAIL SECTIONS
C MINUS INTERSECTION AREA OF STRUTS AND FINS
C AREA2 = TOTAL WETTED SURFACE AREA OF BOTH HULLS WITH NOSE AND TAIL SECTIONS
C MINUS INTERSECTION AREA OF ALL STRUTS AND FINS
    AREA1 = AREN+AREI+AREH-WAF-WPLA
    AREA2 = 2.0*AREA1
C AREA1 = TOTAL WETTED SURFACE AREA FOR SINGLE HULL
C AREA2 = TOTAL WETTED SURFACE AREA FOR DUAL HULL
    AREAT = AREA1+ARE2+AREAS+AREFF+AREAF+ARUD+APGD
    AREAT2 = 2.0*AREAT
C TONS = TONNAGE OF VESSEL
    TONS=VOL/17.5
192 AREA=AREAT*2.
C
C RHO=DENSITY
    RHO= 1.9905
C RHN = WIND DRAG COEFFICIENT
    80 RHN = 0.00115*EFH3*SEP/(RHO*AREA)
    84 DIL = 0.0
C THICKNESS TO CHORD RATIOS OF FWD AND AFT STRUTS AND FINS
    85 TOCA = TA*(1.0+DELF*0.25*(ZAT+ZAN))/CA
    TOCF = 0.0
    TOC3 = 0.0
    TOC4 = 0.0
C EDDY MAKING RESISTANCE FACTORS FOR STRUTS AND FINS
C SDF = EDDY MAKING RESISTANCE FACTOR FOR FORWARD STRUT
C SDA = EDDY MAKING RESISTANCE FACTOR FOR AFT STRUT
C SD3 = EDDY MAKING RESISTANCE FACTOR FOR FORWARD FIN
C SD4 = EDDY MAKING RESISTANCE FACTOR FOR AFT FIN
    SDA=1.0+TOCA+TOCA*60.0*TOCA*TOCA*TOCA*TOCA
    SDF=0.
C
C *** VELOCITY GENERATION ***
C
C CONSTANTS USED WITHIN LOOP
C VISC=VISCOSITY

```

HPCL0217
 HPCL0218
 HPCL0219
 HPCL0220
 HPCL0221
 HPCL0222
 HPCL0223
 HPCL0224
 HPCL0225
 HPCL0226
 HPCL0227
 HPCL0228
 HPCL0229
 HPCL0230
 HPCL0231
 HPCL0232
 HPCL0233
 HPCL0234
 HPCL0235
 HPCL0236
 HPCL0237
 HPCL0238
 HPCL0239
 HPCL0240
 HPCL0241
 HPCL0242
 HPCL0243
 HPCL0244
 HPCL0245
 HPCL0246
 HPCL0247
 HPCL0248
 HPCL0249
 HPCL0250
 HPCL0251
 HPCL0252


```

VISC=.00001279
BACT =32.0*3.14159*3.14159 /(W*AREA)
I=10
DELTA=3.
SPEED=6.
DO 400 K=1,I
IF(K.NE.1) SPEED=SPEED+DELTA
FPS=SPEED*1.6788
SPEED IS SPEED IN KNOTS
VKNTS IS SPEED IN KNOTS
FPS IS SPEED IN FEET PER SECOND
*** WAVEMAKING RESISTANCE ***
C AK = EQUATION CONSTANT
C BACT = EQUATION CONSTANT
C AK= 32.1725/(FPS*FPS)
C FACT =BACT*AK
C INITIALIZE WAVE-DRAG COEFFICIENTS AT ZERO FOR FOLLOWING SUMMATION
C WRSTF = WAVE-DRAG COEFFICIENT OF FORWARD STRUTS ONLY
C WRSTA = WAVE-DRAG COEFFICIENT OF AFT STRUTS ONLY
C WRST = WAVE-DRAG COEFFICIENT OF ALL STRUTS AND STRUT INTERFERENCE, NO HULL
C WRHL = WAVE-DRAG COEFFICIENT OF HULL ALONE
C WWA = WAVE-DRAG COEFFICIENT OF HULL AND AFT STRUT INTERFERENCE
C WWP = WAVE-DRAG COEFFICIENT OF HULL AND FORWARD STRUT INTERFERENCE
C R = TOTAL WAVE-DRAG COEFFICIENT
C WRSTF = 0.0
C WRSTA = 0.0
C WRST = 0.0
C WRHL = 0.0
C WWP = 0.0
C WWA = 0.0
C R = 0.0
C ALL = MULTIPLICATION FACTOR IN FOLLOWING ITERATION
C ALL IS 1.0 FOR FIRST ITERATION TERM AND 2.0 FOR ALL OTHERS
C ALL = 1.0
C START WAVEMAKING SUMMATION, CONSISTS OF 400 TERMS
C DO 401 K2=1,400

```


C COMPUTE HYPERBOLIC FUNCTIONS

C G = SINH(2X)

C CH2 = COSH(2X)

C CH = COSH(X)

C SH = SINH(X)

C SO INDICATES SQUARED TERM

G=4.0*3.14159*PI*QAT(K2-1)/(AK*W)

CH2= SQRT(1.0+3*G)

CHSO =0.5*(CH2+1.0)

CH= SORT(CHSO)

SH= SORT(CHSO-1.0)

C PA = MULTIPLICATION FACTOR IN ITERATION

PA = FACT*CHSO*ALL/CH2

ALL = 2.0

AM = CH*AK

BT=CH*AM

C IF TWO HULLS INCLUDE WAVEMAKING INTERFERENCE FACTOR

FA=FA*(1.0+DCOS(DBLE(AK*SEP*CH*SH)))*2.

C ***** WAVEMAKING - AFT STRUT *****

C STRUT DEPTH FACTORS

UAT=EXP(SNGL(-BT*ZAT))

UAC=EXP(SNGL(-BT*ZAC))

UAN=EXP(SNGL(-BT*ZAN))

VAT= TA*(1.-UAT+DELT*ZAT*(1.-(1.+BT*ZAT)*UAT)/(BT*ZAT))/(PI*BT)

VAN= TA*(1.-UAN+DELT*ZAN*(1.-(1.+BT*ZAN)*UAN)/(BT*ZAN))/(PI*BT)

VAC= TA*(1.-UAC+DELT*ZAC*(1.-(1.+BT*ZAC)*UAC)/(BT*ZAC))/(PI*BT)*4.0

1)

C NORMALIZED STRUT SEGMENT LENGTHS

QAN= YA*AM

OAC= EA*AM*0.5

OAT= WA*AM

C I AND J FUNCTIONS FOR PARABOLIC AFT STRUT TAIL SECTION ASSUMING XATC= ZERO

BIAT=-0.5*(COS(QAT)+QAT*SIN(QAT)-1.0)*VAT/(QAT*QAT)

BJAT= 0.5*(SIN(QAT)-QAT*COS(QAT))*VAT/(QAT*QAT)

C I AND J FOR PARABOLIC AFT STRUT NOSE SECTION ASSUMING XANC=ZERO

BJAN = 0.5*(SIN(QAN)-QAN*COS(QAN))*VAN/(QAN*QAN)

HPCL0207
HPCL0290
HPCL0291
HPCL0292
HPCL0293
HPCL0294
HPCL0295
HPCL0296
HPCL0297
HPCL0298
HPCL0299
HPCL0300
HPCL0301
HPCL0302
HPCL0303
HPCL0304
HPCL0305
HPCL0306
HPCL0307
HPCL0308
HPCL0309
HPCL0310
HPCL0311
HPCL0312
HPCL0313
HPCL0314
HPCL0315
HPCL0316
HPCL0317
HPCL0318
HPCL0319
HPCL0320
HPCL0321
HPCL0322
HPCL0323
HPCL0324


```

BIAN = 0.5*(COS(QAN)+QAN*SIN(QAN)-1.0)*VAN/(QAN*QAN)
GO TO 981
C ADD CENTER SECTION TO STRUT FOR TOTAL I ANDJ FOR XA=ZERO
981 BJA=SIN(QAC)*(BIAN-BIAT+VAC+VAC-.25*(VAT+VAN))+COS(QAC)*(BJAN+BJAT
1)
BIA=COS(QAC)*(BIAN+BIAT+.25*(VAT-VAN))-SIN(QAC)*(BJAN-BJAT)
C TRANSLATE STRUT TO PROPER LOCATION FOR XA
BA= XA*AM
AIA= -BJA*SIN(BA) + BIA*COS(BA)
AJA= BJA*COS(BA) + BIA*SIN(BA)
C CALCULATIONS FOR ELLIPSOIDAL NOSE AND TAIL SECTIONS FOR XN AND XT BOTH ZERO
C BIN, BJN, BIT, AND BJT ARE I AND J TERMS FOR NOSE AND TAIL
C B COEFFICIENT IMPLIES NON TRANSLATED VALUE
C A COEFFICIENT IMPLIES TRANSLATED VALUE
C NONDIMENSIONAL HULL NOSE AND TAIL SECTION LENGTHS
ON=AN*AM
QT=AT*AM
C HULL WAVEMAKING DEPTH FACTOR
ABB= EXP(-F*AM*AM/AK)/16.0
AAA= ABB*2.0/(AM*AM)
BIN = AAA*(DCOS(QN)+QN*DSIN(QN)-1.0)/(AN*AN)
BIT =-AAA*(DCOS(QI)+QT*DSIN(QI)-1.0)/(AT*AT)
BJN=AAA*(DSIN(QN)-QN*DCOS(QN))/(AN*AN)
BJT=AAA*(DSIN(QI)-QT*DCOS(QI))/(AT*AT)
C CORRECTION OF BIT, BJT FOR PARABOLIC TAIL
AZ=12.0*AAA/(AM*AM*AT*AT*AT)
C USE EXPANSION FOR SMALL VALUES OF QT FOR NUMERICAL ACCURACY, USE TRIG
C TERMS FOR LARGER VALUES
IF(QI.LT.0.05) GO TO 8744
BBB=AZ*(1.-DCOS(QI))*(1.-QT*QT/2.)-DSIN(QI)*QT*(1.-QT*QT/6.0))
BIT=BIT+BIT+BBB
BJT=BJT*2.+AZ*(DSIN(QI)*(1.-QT*QT/2.)-QT*DCOS(QI)*(1.-QT*QT/6.0))
GO TO 7744
8744 BIT =BIT*2.0 +AZ*QT*QT*QT*QT/24.0
BJT =BJT*2.0 +AZ*QT*QT*QT*QT*QT/(-30.0)
7744 CONTINUE

```



```

C TRANSLATE NOSE AND TAIL TO PROPER LOCATIONS
7745 BN=(LEN-3.*DH)*AM
      BT=5.*DH*AM
C REAL AND IMAGINARY CONTRIBUTIONS FROM NOSE AND TAIL
      AIN=-BJN*DSIN(BN)+BIN*DCOS(BN)
      AJN=BJN*DCOS(BN)+BIN*DSIN(BN)
      AIT=-BJT*DSIN(BT)+BIT*DCOS(BT)
      AJT=BJT*DCOS(BT)+BIT*DSIN(BT)
C ADJUST I AND J FOR NOSE AND TAIL DIAMETERS
      AIN=AIN*DH*DH
      AJN=AJN*DH*DH
      AIT=AIT*DH*DH
      AJT=AJT*DH*DH
C INITIALIZE HULL I AND J FUNCTIONS WITH NOSE AND TAIL VALUES
      AIH=AIN+AIT
      AJH=AJN+AJT
      AJP=0.
      AIP=0.
      WRST=WRST+FA*((AJA+AJP)**2+(AIF+AIA)**2)
      WRSTA=WRSTA+FA*(AJA*AIA+AIA*AIA)
      WRSTP=WRSTP+FA*(AJP*AJP+AIF*AIF)
      WWA=WWA+2.0*A*(AIH*AIA+AJH*AJA)
      WWF=WWF+2.0*FA*(AIH*AIF+AJH*AJP)
      WRHL=WRHL+(AJH**2+AIH**2)*FA
401 R= P+((AJA+AJP+AJH)**2+(AIA+AIF+AIH)**2)*FA
      *** FRICTIONAL RESISTANCE ***
C CALCULATE REYNOLDS NUMBERS
C REF = REYNOLDS NUMBER OF FORWARD STRUT
C REA = REYNOLDS NUMBER OF AFT STRUT
C REH = REYNOLDS NUMBER OF HULL
C REFNA = REYNOLDS NUMBER OF AFT FIN
C REFNF = REYNOLDS NUMBER OF FORWARD FIN
      REF = FPS*CF/VISC
      REA = FPS*CA/VISC
      REH = FPS*LEN/VISC
      REFNF = FPS*CFINF/VISC

```

HPCL0361
 HPCL0362
 HPCL0363
 HPCL0364
 HPCL0365
 HPCL0366
 HPCL0367
 HPCL0368
 HPCL0369
 HPCL0370
 HPCL0371
 HPCL0372
 HPCL0373
 HPCL0374
 HPCL0375
 HPCL0376
 HPCL0377
 HPCL0378
 HPCL0379
 HPCL0380
 HPCL0381
 HPCL0382
 HPCL0383
 HPCL0384
 HPCL0385
 HPCL0386
 HPCL0387
 HPCL0388
 HPCL0389
 HPCL0390
 HPCL0391
 HPCL0392
 HPCL0393
 HPCL0394
 HPCL0395
 HPCL0396


```

REPNA = FPS*CFINA/VISC
IF(REF.LT.100.0) REF = 100.0
IF(REA.LT.100.0) REA = 100.0
IF(REH.LT.100.0) REH = 100.0
IF(REPNF.LT.100.0) REPNF = 100.0
IF(REFNA.LT.100.0) REFNA = 100.0
C INITIAL GUESSES OF COEFFICIENT OF FRICTION FOR FOLLOWING ITERATION
CFP=.003
CPA=.003
CPH=.003
EPINF = .003
EPINA = .003
DO 90 K3=1,15
  CFP=(.242/DLOG10(DBLE(REF*CFP)))**2
  CPA=(.242/DLOG10(DBLE(REA*CPA)))**2
  EPINF=(.242/DLOG10(DBLE(REPNF*EPINF)))**2
  EPINA=(.242/DLOG10(DBLE(REFNA*EPINA)))**2
  CPH=(.242/DLOG10(DBLE(REH*CPH)))**2
  C ADD 0.0005 TO SCHOENHERR VALUES
  CFP=(CFP+.0005)/AREA
  CPA=(CPA+.0005)/AREA
  CPH=(CPH+.0005)/AREA
  EPINA=(EPINA+.0004)/AREA
  EPINF=(EPINF+.0004)/AREA
C RVF = FRICTIONAL DRAG OF FORWARD STRUTS
C RVA = FRICTIONAL DRAG OF AFT STRUTS
C RVH = FRICTIONAL DRAG OF HULL
C RVFNF = FRICTIONAL DRAG OF FORWARD FINS
C RVFNA = FRICTIONAL DRAG OF AFT FINS
C RVRUD = FRICTIONAL DRAG OF RUDDER
C RVPGD = FRICTIONAL DRAG OF PROP GUARD
C RFE = TOTAL FRICTIONAL DRAG
  RVF = CFP*SDF*AREFS
  RVA = CPA*SDA*AREAS
C RVH ACCORDING TO NAVSEC IS

```



```

RVH = CPH*AREAH
C INCREASE HULL FRICTION DRAG BY 10 PERCENT TO ACCOUNT FOR EDDY MAKING DRAG
RVH = RVH*1.10
RVFNF=0.
RVFNA=0.
RVFNA = ARUD*CFA
RVFUD = APGD*EFINF
RVF = 2.0*RVF
RVA = 2.0*RVA
RVH = 2.0*RVH
RVFNF = 2.0*RVFNF
RVFNA = 2.0*RVFNA
RVFUD = 2.0*RVFUD
RVFUD = 2.0*RVFUD
30 RFE = RVF+RVA+RVH+RVFNA+RVFNF+RVFUD+RVFUD
*** SPRAY DRAG RESISTANCE ***
C
RSPR = 0.0
RSPRA = 0.0
C TSPA = FROUDE NUMBER OF AFT STRUTS
TSPA=FPS/SORT(CA-BA)
C IF FROUDE NUMBER IS NOT SUFFICIENTLY LARGE THEN NO SPRAY DRAG
4010 IF(TSPA.LT.5.7) GO TO 4011
C RSPRR = SPRAY DRAG OF AFT STRUT
RSPRR= (0.011*CA*TA+0.08*TA*TA)*CFA/.004
C CORRECTION FOR UNDEVELOPED SPRAY DRAG
IF(TSPA.LT.13.0) RSPR = RSPRR*(TSPA-5.7)/7.3
C RSPRT = TOTAL SPRAY DRAG
4011 RSPRT = RSPR+RSPRR
RSPRT=2.*RSPRT
*** TOTAL DRAG ***
C
C RR = TOTAL DRAG COEFFICIENT
RR = RFE+R+RSPRT+RWN+DIL
C ADD 6 PERCENT APPENDAGE RESISTANCE
RR = RR*1.06
VKNTS(K)=SPEED
POW(K)=RR*AREA*RH0*FPS*FPS*0.5*FPS/(550.*PC)

```

HPCL0433
 HPCL0434
 HPCL0435
 HPCL0436
 HPCL0437
 HPCL0438
 HPCL0439
 HPCL0440
 HPCL0441
 HPCL0442
 HPCL0443
 HPCL0444
 HPCL0445
 HPCL0446
 HPCL0447
 HPCL0448
 HPCL0449
 HPCL0450
 HPCL0451
 HPCL0452
 HPCL0453
 HPCL0454
 HPCL0455
 HPCL0456
 HPCL0457
 HPCL0458
 HPCL0459
 HPCL0460
 HPCL0461
 HPCL0462
 HPCL0463
 HPCL0464
 HPCL0465
 HPCL0466
 HPCL0467
 HPCL0468

400 CONTINUE
RETURN
1000 LEN=-10.0
RETURN
END

HPCL0469
HPCL0470
HPCL0471
HPCL0472
HPCL0473


```

SUBROUTINE UGLYDK(NIN,NCL,NCR,XIN,YIN,ESL,ESR,AE)
APRIL 1975 DUCK SRIES J.E.KERWIN
DIMENSION XIN(1),YIN(1),AE(1),H(30),D(30),A(900),S(30)
DATA HALF/0.5E00/,TWO/2.0E00/,SIX/6.0E00/,RAD/1.745329E-02/
NM1=NIN-1
NM2=NM1-1
NM3=NM2-1
NEO=NM2
DO 1 N=1,NM1
H(N)=XIN(N+1)-XIN(N)
D(N)=(YIN(N+1)-YIN(N))/H(N)
IF(NCL.EQ.2) NEO=NEO+1
IF(NCR.EQ.2) NEO=NEO+1
NSQ=NEO**2
DO 4 N=1,NSQ
A(N)=0.0
J=1
L=1
IF(NCL.LF.2) GO TO 6
A(1)=TWO*H(1)
A(2)=H(1)
SLP=ESL*RAD
S(1)=(D(1)-TAN(SLP))*SIX
J=J+1
L=L+NEO+1
A(L-1)=H(1)
DO 5 N=1,NM2
IF(N.GT.1) A(L-1)=H(N)
A(L)=TWO*(H(N)+H(N+1))
IF(N.LT.NM2) A(L+1)=H(N+1)
IF(N.EQ.2.AND.NCL.EQ.1) A(L-1)=A(L-1)-H(N)**2/H(N+1)
IF(N.EQ.1.AND.NCL.EQ.1) A(L)=A(L)+(1.0+H(N)/H(N+1))*H(N)
IF(N.EQ.NM2.AND.NCR.EQ.1) A(L)=A(L)+(1.0+H(N+1)/H(N))*H(N+1)
IF(N.EQ.NM3.AND.NCR.EQ.1) A(L+1)=A(L+1)-H(N+2)**2/H(N+1)
S(J)=(D(N+1)-D(N))*SIX
J=J+1

```

```

UGLD0001
UGLD0002
UGLD0003
UGLD0004
UGLD0005
UGLD0006
UGLD0007
UGLD0008
UGLD0009
UGLD0010
UGLD0011
UGLD0012
UGLD0013
UGLD0014
UGLD0015
UGLD0016
UGLD0017
UGLD0018
UGLD0019
UGLD0020
UGLD0021
UGLD0022
UGLD0023
UGLD0024
UGLD0025
UGLD0026
UGLD0027
UGLD0028
UGLD0029
UGLD0030
UGLD0031
UGLD0032
UGLD0033
UGLD0034
UGLD0035
UGLD0036

```



```

5  L=L+NBO+1
   IF(NCR.LT.2) GO TO 7
   A(L-1)=H(NM1)
   A(L)=-TWO*H(NM1)
   L=L-NEO
   A(L)=-H(NM1)
   SLP=ESR*RAO
   S(J)=(D(NM1)+FAN(SLP))*SIX
7  CALL SIMQ(A,S,NEO,KERROR)
   HOLD=S(NEQ)
   IF(NCL.EQ.2) GO TO 8
   DO 9 N=1,NM2
     M=NM2-N+2
     S(M)=S(M-1)
     IF(NCL.EQ.0) S(1)=0.0
     BUG=d(1)/H(2)
     IF(NCL.EQ.1) S(1)=(1.0+BUG)*S(2)-BUG*S(3)
     IF(NCE.EQ.0) S(NIN)=0.0
     BUG=H(NM1)/H(NM2)
     IF(NCA.EQ.1) S(NIN)=(1.0+BUG)*S(NM1)-BUG*S(NM2)
     IF(NCR.EQ.2) S(NIN)=HOLD
     DO 10 N=1,NM1
       AE(N)=(S(N+1)-S(N))/(SIX*H(N))
       M=N+NM1
       AE(M)=HALF*S(N)
       M=M+NM1
       AE(M)=D(N)-H(N)*(TWO*S(N)+S(N+1))/SIX
       M=M+NM1
10  AE(M)=YIN(N)
     RETURN
     END

```


UGLD00037
UGLD00038
UGLD00039
UGLD00040
UGLD00041
UGLD00042
UGLD00043
UGLD00044
UGLD00045
UGLD00046
UGLD00047
UGLD00048
UGLD00049
UGLD00050
UGLD00051
UGLD00052
UGLD00053
UGLD00054
UGLD00055
UGLD00056
UGLD00057
UGLD00058
UGLD00059
UGLD00060
UGLDC0061
UGLD00062
UGLD00063
UGLD00064
UGLD00065
UGLD00066
UGLD00067

```

5  L=L+NEO+1
   IF(NCR.LT.2) GO TO 7
   A(L-1)=H(NM1)
   A(L)=-TWO*H(NM1)
   L=L-NEO
   A(L)=-H(NM1)
   SLP=ESR*RAO
7  S(J)=(D(NM1)+TAN(SLP))*SIX
   CALL SIMO(A,S,NEO,KERROR)
   HOLD=S(NEO)
   IF(NCL.EQ.2) GO TO 8
   DO 9 N=1,NM2
     M=NM2-N+2
9    S(M)=S(M-1)
     IF(NCL.EQ.0) S(1)=0.0
     BUG=d(1)/H(2)
     IF(NCL.EQ.1) S(1)=(1.0+BUG)*S(2)-BUG*S(3)
     IF(NCE.EQ.0) S(NIN)=0.0
     BUG=H(NM1)/H(NM2)
     IF(NCA.EQ.1) S(NIN)=(1.0+BUG)*S(NM1)-BUG*S(NM2)
     IF(NCR.EQ.2) S(NIN)=HOLD
     DO 10 N=1,NM1
       AE(N)=(S(N+1)-S(N))/(SIX*H(N))
       M=N+NM1
       AE(M)=HALF*S(N)
       M=M+NM1
       AE(M)=D(N)-H(N)*(TWO*S(N)+S(N+1))/SIX
       M=M+NM1
10    AE(M)=YIN(N)
       RETURN
       END

```



```

SUBROUTINE EVALDK(NIN,NOUT,XIN,XOUT,YOUT,A)
APRIL 1975 SPLINE PROGRAM SERIES J.E.KERWIN
DIMENSION XIN(1),XOUT(1),YOUT(1),A(1)
NM1=NIN-1
MOUT=IABS(NOUT)
IF(NOUT.GT.0) GO TO 1
DEL=(XIN(NIN)-XIN(1))/(MOUT-1)
DO 2 N=1,MOUT
  XOUT(N)=XIN(1)+(N-1)*DEL
  J=1
DO 3 N=1,MOUT
  IF(XOUT(N).GE.XIN(2)) GO TO 4
  J=1
GO TO 5
IF(XOUT(N).LT.XIN(NM1)) GO TO 6
J=NM1
GO TO 5
IF(XOUT(N).GE.XIN(J+1)) GO TO 7
9 IF (XOUT(N).LT.XIN(J)) GO TO 8
5 H1=XOUT(N)-XIN(J)
H2=H1**2
H3=H1*H2
J2=J+NM1
J3=J2+NM1
J4=J3+NM1
YOUT(N)=A(J)*H3+A(J2)*H2+A(J3)*H1+A(J4)
GO TO 3
J=J+1
GO TO 6
8 J=J-1
GO TO 9
CONTINUE
RETURN
END

```

EVLD0001
 EVLD0002
 EVLD0003
 EVLD0004
 EVLD0005
 EVLD0006
 EVLD0007
 EVLD0008
 EVLD0009
 EVLD0010
 EVLD0011
 EVLD0012
 EVLD0013
 EVLD0014
 EVLD0015
 EVLD0016
 EVLD0017
 EVLD0018
 EVLD0019
 EVLD0020
 EVLD0021
 EVLD0022
 EVLD0023
 EVLD0024
 EVLD0025
 EVLD0026
 EVLD0027
 EVLD0028
 EVLD0029
 EVLD0030
 EVLD0031
 EVLD0032
 EVLD0033
 EVLD0034

SIMQ00001
SIMQ00002
SIMQ00003
SIMQ00004
SIMQ00005
SIMQ00006
SIMQ00007
SIMQ00008
SIMQ00009
SIMQ00010
SIMQ00011
SIMQ00012
SIMQ00013
SIMQ00014
SIMQ00015
SIMQ00016
SIMQ00017
SIMQ00018
SIMQ00019
SIMQ00020
SIMQ00021
SIMQ00022
SIMQ00023
SIMQ00024
SIMQ00025
SIMQ00026
SIMQ00027
SIMQ00028
SIMQ00029
SIMQ00030
SIMQ00031
SIMQ00032
SIMQ00033
SIMQ00034
SIMQ00035
SIMQ00036

```

SUBROUTINE SIMQ(A,B,N,KS)
  DIMENSION A(1),B(1)
  TOL=0.0
  KS=0
  JJ=-N
  DO 65 J=1,N
    JY=J+1
    JJ=JJ+N+1
    BIGA=0
    IT=JJ-J
    DO 30 I=J,N
      IJ=IT+I
      IF (ABS(BIGA) -ABS(A(IJ))) 20,30,30
      BIGA=A(IJ)
      IMAX=I
    20 CONTINUE
    IF (ABS(BIGA) -TOL) 35,35, 40
    35 KS=1
    RETURN
    40 I1=J+N*(J-2)
    IT=IMAX-J
    DO 50 K=J,N
      I1=I1+N
      I2=I1+IT
      SAVE=A(I1)
      A(I1)=A(I2)
      A(I2)=SAVE
    50 A(I1)=A(I1)/BIGA
      SAVE=B(IMAX)
      B(IMAX)=B(J)
      B(J)=SAVE/BIGA
      IF(J-N) 55,70,55
    55 IOS=N*(J-1)
      DO 65 IX=JY,N
        IXJ=IOS+IX
        IT=J-IX

```


SIMQ00037
SIMQ00038
SIMQ00039
SIMQ00040
SIMQ00041
SIMQ00042
SIMQ00043
SIMQ00044
SIMQ00045
SIMQ00046
SIMQ00047
SIMQ00048
SIMQ00049
SIMQ00050
SIMQ00051
SIMQ00052
SIMQ00053

```

DO 60 JX=JY,N
IXJX=N*(JX-1)+IX
JJX=IXJX+IT
60 A(IXJX)=A(IXJX)-(A(IXJ)*A(JJX))
65 B(IX)=B(IX)-(B(J)*A(IXJ))
70 NY=N-1
IT=N*N
DO 80 J=1,NY
IA=IT-J
IB=N-J
IC=N
DO 80 K=1,J
B(IB)=B(IB)-A(IA)*B(IC)
IA=IA-N
80 IC=IC-1
RETURN
END

```


EPLT0001
EPLT0002
EPLT0003
EPLT0004
EPLT0005
EPLT0006
EPLT0007
EPLT0008
EPLT0009
EPLT0010
EPLT0011
EPLT0012
EPLT0013
EPLT0014
EPLT0015
EPLT0016
EPLT0017
EPLT0018
EPLT0019
EPLT0020
EPLT0021
EPLT0022
EPLT0023
EPLT0024
EPLT0025
EPLT0026
EPLT0027
EPLT0028
EPLT0029
EPLT0030

```

SUBROUTINE EPLANT
  REAL LEN,NOFF,NCPO,NENL,NAC,KW,KW1
  COMMON/AA/ENDDAY,NOFF,NCPO,NENL
  COMMON/BB/CN,DHV,ENCVOL,DAVG,AREADH,AREAHL,LEN
  COMMON/CC/SHPE,SHPE,VSUS,VE,RE,SFCH,MTYPE,JOPT,MOPT,PC
  COMMON/DD/ELKW,AVGKW,ELOAD,BLOAD,PALOAD
  IF(JOPT.EQ.2) GOTO 1
  PALOAD=1.
  IF(MTYPE.EQ.2) PALOAD=15.
  IF(MTYPE.EQ.3) PALOAD=71.
  IF(MTYPE.EQ.4) PALOAD=71.
  1 OALOAD=.0002695*CN
  NAC=NOFF+NCPO+NENL
  HLOAD=.917*NAC
  AVLOAD=15.+ .376*NAC*CN/100000.
  KW=ELOAD+BLOAD+PALOAD+OALOAD+HLOAD+AVLOAD
  AVGKW=KW-BLOAD
  KW1=1.25*(1.02*KW+ELOAD)
  ELKW=100.
  2 IF(ELKW.GE.KW1) GOTO 3
  IF(ELKW.LT.240.) GOTO 4
  IF(ELKW.LT.900.) GOTO 5
  ELKW=ELKW+500.
  GOTO 2
  4 ELKW=ELKW+50.
  GOTO 2
  5 ELKW=ELKW+250.
  GOTO 2
  3 RETURN
  END

```



```

SUBROUTINE LIQ
REAL NOFF,NCPO,NENL,NAC
COMMON/AA/ENDDAY,NOFF,NCPO,NENL
COMMON/CC/SHPM,SHPE,VUS,VE,KE,SFCH,MTYPE,JOPT,MOPT,PC
COMMON/DD/ELKW,AVGKW,ELoad,BLOAD,PALOAD
COMMON/LL/WTfuel,WTLO,WTcrew,WTPE,WTPS,WCARGO,WTAMMO,WTAC,WACFUL
NAC=NOFF+NCPO+NENL
WTPS=.186*NAC
IF(JOPT.EQ.2) GOTO 1
WTLO=.001*SHPM+5.
IF(MTYPE.EQ.3) GO TO 2
IF(MTYPE.EQ.4) GO TO 2
IF(MTYPE.EQ.2) GO TO 6
SFC=.5-.08*SHPE/SHPM
SHPH=SHPM/2.
IF(SHPM.GT.7000..AND.SHPE.LT.SHPH) SFC=.5-.16*SHPE/SHPM
GO TO 3
6 SFC=.54-.03*SHPE/SHPM
SHPH=SHPM/2.
IF(SHPM.GT.7000..AND.SHPE.LT.SHPH) SFC=.54-.16*SHPE/SHPM
GO TO 3
2 WTLO=.0001*SHPM+3.5
IF(MTYPE.EQ.3) GO TO 7
SFC=.92-.3*SHPE/SHPM
IF(SHPM.GT.8000..AND.SHPM.LT.30000.) GO TO 9
IF(SHPM.GT.30000.) SFC=.63-.2*SHPE/SHPM
GO TO 3
9 SFC=.77-.16*SHPE/SHPM
GO TO 3
7 SFC=.85-.28*SHPE/SHPM
IF(SHPM.GT.8000..AND.SHPM.LT.30000.) GO TO 10
IF(SHPM.GT.30000.) SFC=.49-.18*SHPE/SHPM
GO TO 3
10 SFC=.64-.16*SHPE/SHPM
GO TO 3
1 SFC=SFCM+(1.-SHPE/SHPM)*2.*(SFCH-SFCM)

```

```

LIQ 0001
LIQ 0002
LIQ 0003
LIQ 0004
LIQ 0005
LIQ 0006
LIQ 0007
LIQ 0008
LIQ 0009
LIQ 0010
LIQ 0011
LIQ 0012
LIQ 0013
LIQ 0014
LIQ 0015
LIQ 0016
LIQ 0017
LIQ 0018
LIQ 0019
LIQ 0020
LIQ 0021
LIQ 0022
LIQ 0023
LIQ 0024
LIQ 0025
LIQ 0026
LIQ 0027
LIQ 0028
LIQ 0029
LIQ 0030
LIQ 0031
LIQ 0032
LIQ 0033
LIQ 0034
LIQ 0035
LIQ 0036

```


LIQ 0037
LIQ 0038
LIQ 0039
LIQ 0040
LIQ 0041
LIQ 0042
LIQ 0043

3 FRMAIN=SFC*SHPE
FRHOTL=.32*NAC
PRGEN=.65*AVGKW
PR=FRMAIN+FRHOTL+PRGEN
WTFUEL=FR*RE/(1788.*VE)
RETURN
END

SUBROUTINE MACHBX

REAL KGTRY

COMMON/CC/SHPM, SHPE, VSUS, VEND, RGEND,

SFCMHP, SFCCHP, MTYPE, JOPT

1, MOPT, PC

COMMON/GG/FRSC, KGTRY, DPTRY, DH, BBOX, BS, XLS, CWP

COMMON/JJ/H, SEP, XLB, DB, AG, XF, MBLOC1, MBLOC2

COMMON/QQ/XMLOC1, YMLOC1, ZMLOC1, XMLOC2, YMLOC2, ZMLOC2

MBLOC1=1>PROP IN HULL; MBLOC2=1, P.M. IN HJLL; MBLOC2=2, P.M. IN BOX

IF (MTYPE.EQ.1) GO TO 2

IF (MTYPE.EQ.2) GO TO 31

IF (MTYPE.EQ.3) GO TO 41

IF (MTYPE.EQ.4) GO TO 5

2 CONTINUE

MBLOC1=1

XMLOC1=25.

YMLOC1=DH

ZMLOC1=DH

MBLOC2=1

XMLOC2=28.

YMLOC2=DH

ZMLOC2=DH

IF (SHPM.GT.7000.) GO TO 21

GO TO 10

21 MBLOC2=2

XMLOC2=56.

YMLOC2=3.*DH

ZMLOC2=DB

GO TO 10

31 MBLOC2=2

XMLOC2=28.

YMLOC2=3.*DH

ZMLOC2=DB

MBLOC1=1

XMLOC1=25.

YMLOC1=DH

ZMLOC1=DH

MCBX0001
 MCBX0002
 MCBX0003
 MCBX0004
 MCBX0005
 MCBX0006
 MCBX0007
 MCBX0008
 MCBX0009
 MCBX0010
 MCBX0011
 MCBX0012
 MCBX0013
 MCBX0014
 MCBX0015
 MCBX0015
 MCBX0017
 MCBX0018
 MCBX0019
 MCBX0020
 MCBX0021
 MCBX0022
 MCBX0023
 MCBX0024
 MCBX0025
 MCBX0026
 MCBX0027
 MCBX0028
 MCBX0029
 MCBX0030
 MCBX0031
 MCBX0032
 MCBX0033
 MCBX0034
 MCBX0035
 MCBX0036

MCBX00037
 MCBX00038
 MCBX00039
 MCBX00040
 MCBX00041
 MCBX00042
 MCBX00043
 MCBX00044
 MCBX00045
 MCBX00046
 MCBX00047
 MCBX00048
 MCBX00049
 MCBX00050
 MCBX00051
 MCBX00052
 MCBX00053
 MCBX00054
 MCBX00055
 MCBX00056
 MCBX00057
 MCBX00058
 MCBX00059
 MCBX00060
 MCBX00061
 MCBX00062
 MCBX00063
 MCBX00064
 MCBX00065

```

IF(SHPM.GT.15000.) XMLOC1=50.
GO TO 10
+1 MBLOC2=2
  XMLOC2=20.+00024*SHPM
  YMLOC2=3.*DH
  ZMLOC2=9.
  MBLOC1=1
  XMLOC1=25.
  YMLOC1=DH
  ZMLOC1=DH
IF(SHPM.GT.8000..AND.BS.GT.6.) GO TO 43
GO TO 10
43 MBLOC2=1
  XMLOC2=20.+00048*SHPM
  YMLOC2=DH
  ZMLOC2=DH
GO TO 10
5 MBLOC2=2
  XMLOC2=20.+00024*SHPM
  YMLOC2=3.*DH
  ZMLOC2=9.
  MBLOC1=1
  XMLOC1=25.
  YMLOC1=DH
  ZMLOC1=DH
IF(SHPM.GT.15000.) XMLOC1=50.
10 CONTINUE
  RETURN
  END

```



```

SUBROUTINE VOLUME
REAL LEN,NOFF,NCPO,NENL,KGTRY,NAC
COMMON/AA/D,NOFF,NCPO,NENL
COMMON/BB/CN,DHV,ENCVOL,DI,AREADH,AREAHL,LEN
COMMON/CC/SHPM,SHPE,VSUS,VEND,RGEND, SFCMHP,SFCHHP,MTYPE,JOPT
1,MOPT,PC
COMMON/GG/FRSC,KGTRY,DPTRY,DH,BBOX,BS,XLS,CWP
COMMON/JJ/H,SEP,XLB,DB,AG,XF,MBLOC1,MBLOC2
COMMON/LL/WTFUEL,WILO,WTCREW,WTPS,WCARGO,WTAMMO,WTAC,WACFUL
COMMON/PP/VMB,TANKVL,AVAA,DHAA,ODA,XMFDA,CSDA,OSRDA,OHDA,CPODA,
1CPOHDA,CBDA,CHDA,CODA,CSTDA,OSDA,WDA,RLDA,CLDA,UTDA,SGDA,ACDA,XICD
2A,AMDA,PHDA,WSDA,VMAX
COMMON/OO/XMLOC1,YMLOC1,ZMLOC1,XMLOC2,YMLOC2,ZMLOC2
KNDEX=0
VMX=0.
NAC=NOFF+NCPO+NENL
THV=2.*( (.785398*DH*DH*(LEN-8.*DH)+3.665191*DH*DH*DH)
VFUEL=WTFUEL*43.
VLO=WILO*39.
VFW=.186*NAC*36.
VACFUL=WACFUL*44.1
TANKVL=(VFUEL+VLO+VFW+VACFUL)*1.2
IF(MBLOC2.EQ.1) GO TO 1
MACHINERY IN BOX
VMX=XMLOC2*YMLOC2*ZMLOC2
VMH=1.570796*XMLOC1*DH*DH
GO TO 2
1 VMH=1.570796*(XMLOC1+XMLOC2)*DH*DH
GO TO 2
2 DHV=.007*LEN*LEN*LEN
3 STV=2.*( (XLS*BS*CWP)*(H-DH+AG)+XLS*(.5*BS*(DH-.5*DH*SQR(1.-BS*BS/
1(DH*DH)))-.25*DH*DH*ARSIN(BS/DH)))
FILV=XLS*BS*BS
BOXV=XLB*BBOX*13.
BAA=BOXV/13.
4 TEV=THV+STV+FILV+BOXV+DHV
VOL 0001
VOL 0002
VOL 0003
VOL 0004
VOL 0005
VOL 0006
VOL 0007
VOL 0008
VOL 0009
VOL 0010
VOL 0011
VOL 0012
VOL 0013
VOL 0014
VOL 0015
VOL 0016
VOL 0017
VOL 0018
VOL 0019
VOL 0020
VOL 0021
VOL 0022
VOL 0023
VOL 0024
VOL 0025
VOL 0026
VOL 0027
VOL 0028
VOL 0029
VOL 0030
VOL 0031
VOL 0032
VOL 0033
VOL 0034
VOL 0035
VOL 0036

```


CN=TEV-DHV	VOL 0037
SGDA=.0042*CN+450.	VOL 0038
RHV=TANKVL+VMH+SGDA*9.	VOL 0039
IF (THV.GT.RHV) GO TO 5	VOL 0040
CAN ADD LIQUIDS TO STRUT TO ATTAIN BALANCE	VOL 0041
VHULSS=THV+.3*STV	VOL 0042
IF (VHULSS.GT.RHV) GO TO 5	VOL 0043
GO TO 1000	VOL 0044
HULLS CHECK OUT - NOW CHECK DECKHOUSE	VOL 0045
5 RDHA=1.1*(2.37*LEN+24.+00225*CN+AREADH)	VOL 0046
DHAA=DHV/9.	VOL 0047
ASSUME ONE USEABLE PLATFORM IN STRUTS OVER 75 PERCENT OF LENGTH	VOL 0048
SAAA=XLS*BS*CBP*1.5	VOL 0049
IF (RDHA.GT.DHAA) GO TO 1000	VOL 0050
AVAA=BAAA+SAAA	VOL 0051
TAAA=DHAA+BAAA+SAAA	VOL 0052
ODA=2.12*LEN-232.	VOL 0053
IF (ODA.LT.0.) ODA=0.	VOL 0054
XMFDA=11.9*NAC+500.	VOL 0055
CSDA=4.23*NAC	VOL 0056
OSRDA=73.*NOFF	VOL 0057
OHDA=12.*NOFF	VOL 0058
CPODA=40.*NCPO	VOL 0059
CPOHDA=8.*NCPO	VOL 0060
CBDA=22.*NENL	VOL 0061
CHDA=5.*NENL	VOL 0062
CODA=2.37*LEN-76.	VOL 0063
CSTDA=300.+021*D*NAC	VOL 0064
OSDA=.00539*CN	VOL 0065
WDA=.00314*CN-157.	VOL 0066
IF (WDA.LT.0.) WDA=0.	VOL 0067
RLDA=145.	VOL 0068
CLDA=40.	VOL 0069
ACDA=.00088*CN	VOL 0070
XICDA=.88*LEN+4.	VOL 0071
AMDA=.0097*CN	VOL 0072

PHDA=100.+.00225*CN	VOL 0073
WSDA=5.*LEN-475.	VOL 0074
VMXA=VMX/9.	VOL 0075
UTDA=0.	VOL 0076
IF(JOPT.EQ.2) GO TO 6	VOL 0077
UTDA=700.	VOL 0078
IF(MBLOC2.EQ.1) GO TO 6	VOL 0079
UTDA=200.	VOL 0080
6 TRAA=1.1*(AREADH+AREAHL+ODA+XMFDA+CSDA+JCSRDA+OHDA+CPOHDA+	VOL 0081
1CBDA+CHDA+CODA+CSIDA+OSDA+WDA+RLDA+CLDA+UIDA+ ACDA+XICDA+AMDA+	VOL 0082
2PHDA+WSDA+VMXA)	VOL 0083
IF(TRAA.GT.TAAA) GO TO 10	VOL 0084
REDUCE DECKHOUSE VOLUME	VOL 0085
DHSV=.00223*LEN*LEN*LEN	VOL 0086
DHSAA=DHSV/9.	VOL 0087
DHAMIN=AMAX1(DHSAA,RDHA)	VOL 0088
TAAA=DHAMIN+BAAA+SAAA	VOL 0089
IF(TRAA.GT.TAAA) GO TO 11	VOL 0090
DHV=9.*DHAMIN	VOL 0091
DHAA=DHAMIN	VOL 0092
GO TO 13	VOL 0093
12 DHV=DHSV	VOL 0094
DHAA=DHV/9.	VOL 0095
13 ENCVOL=CN+DHV	VOL 0096
VMB=VMX+VMH	VOL 0097
RETURN	VOL 0098
11 DHAR=TRAA-AVA1	VOL 0099
DHSV=DHAR*9.	VOL 0100
GO TO 12	VOL 0101
ADD ANOTHER DECK IN BOX	VOL 0102
10 DB=22.	VOL 0103
BOXV=BOXV*1.6923	VOL 0104
BAAA=XLB*BOX*2.	VOL 0105
IF(KNDEX.GT.1) GO TO 1000	VOL 0106
KNDEX=KNDEX+1	VOL 0107
GO TO 4	VOL 0108

C

C

VOL 0109
VOL 0110
VOL 0111

1000 LEN=-10.0
RETURN
END

WGHT0001
WGHT0002
WGHT0003
WGHT0004
WGHT0005
WGHT0006
WGHT0007
WGHT0008
WGHT0009
WGHT0010
WGHT0011
WGHT0012
WGHT0013
WGHT0014
WGHT0015
WGHT0016
WGHT0017
WGHT0018
WGHT0019
WGHT0020
WGHT0021
WGHT0022
WGHT0023
WGHT0024
WGHT0025
WGHT0026
WGHT0027
WGHT0028
WGHT0029
WGHT0030
WGHT0031
WGHT0032
WGHT0033
WGHT0034
WGHT0035
WGHT0036

```

SUBROUTINE WEIGHT
REAL LEN,NOFF,NCPO,NENL,NAC
COMMON/AA/D,NOFF,NCPO,NENL
COMMON/BB/CN,DHV,ENCVOL,DT,AREADH,AREAHL,LEN
COMMON/CC/SHPM,SHPE,VSUS,VEND,EGEND,      SPCMHP,SPCHHP,MTYPE,JOPT
1,MOPT,PC
COMMON/DD/ELKW,AVGKW,ELOAL,BLOAD,PALOAD
COMMON/GG/FRSC,KGTRY,DPTRY,DH,BBOX,BS,XLS,CWP
COMMON/JJ/H,SEP,XLB,DB,AG,XF,MBLOC1,MBLOC2
COMMON/LL/WTFUEL,WILO,WTCREW,WTFE,WTPS,WCARGO,WTAMMO,WTAC,WACFUL
COMMON/MW/WTG1,WTG2,WTG3,WIG4,WTG5,WTG6,WTG7,WLSHIP,WFULLD,DBMAR
IF(DB,LE,13.) GO TO 1
TWO DECK BOXES--STEEL FIEST,TEST MOPT,THEN ALUMINUM
WT1=.82285*DPTRY-54.+0049*DPTRY=DPTRY/CN
IF(MOPT,EQ.2) WT1=.542222*DPTRY-34.84444*DPTRY*DPTRY/CN
GO TO 2
C
ONE DECK BOXES
1 WT1=.83335*DPTRY-41.8151=DPTRY*DPTRY/CN
IF(MOPT,EQ.2) WT1=.577857*DPTRY-32.000039*DPTRY*DPTRY/CN
C
THE WEIGHT EQUATIONS ARE BASED ON WT1 + 15 PERCENT -- REDUCE 15 %
2 WT1=.85*WT1
WT111=.000353*DHV
WTG1=WT1+WT111
IF(JOPT,EQ.2) GO TO 3
WTG2=.03754*SHPM**.925
IF(MTYPE,EQ.2) WTG2=.1109828*SHPM**.86
IF(MTYPE,EQ.3) WTG2=.339053*SHPM**.634
IF(MTYPE,EQ.4) WTG2=.4777*SHPM**.692
IF(MTYPE,EQ.3.AND.MBLOC2,EQ.2) WTG2=WTG2+.001*SHPM-2.033
IF(MTYPE,EQ.1.AND.MBLOC2,EQ.2) WTG2=WTG2+.001*SHPM-2.033
3 CONTINUE
C
GOODWIN DATA AND ASSUMPTIONS USED FOR GROUP THREE WEIGHTS
WT300=.054*ELKW
IF(ELKW.GE.500.) WT300=41.54+.01068*ELKW
IF(ELKW.GE.800.) WT300=5.38+.06748*ELKW
WT301=.01335*ELKW

```


WGHT0037
WGHT0038
WGHT0039
WGHT0040
WGHT0041
WGHT0042
WGHT0043
WGHT0044
WGHT0045
WGHT0046
WGHT0047
WGHT0048
WGHT0049
WGHT0050
WGHT0051
WGHT0052
WGHT0053

```

WT3R=.0001534*ENCVOL
WTG3=WT300+WT301+WT3R
VOL=ENCVOL/100000.
D007 GROUP 5 CURVE REDUCED 20 PERCENT FITS SWATHS --USED HERE
WTG5=-2.3072*VOL*VOL+65.456*VOL
WTG6 CURVE FITTED TO SWATH DATA AVAILABLE AS FUNCTION OF ENCVOL
WTG6=.05318*ENCVOL**.6266
WLSHIP=(WTG1+WTG2+WTG3+WTG4+WTG5+WTG6+WTG7)*DBMAR
CALCULATE LOADS
NAC=NOFF+NCPO+NENL
WTCREW=.0737*NAC
WTPE=.105*NOFF+.0737*NCPO+.029*NENL
WTPS=(.0222+.00202*D)*NAC+.00135*D*NAC+.186*NAC
WFULLD=WLSHIP+WTCREW+WTPE+WTLO+WTFUEL+WCARGO+WTAMMO+WTAC+
1*ACFTL
RETURN
END

```

C
C
C


```

SUBROUTINE VCG(CFULD)
REAL LEN
COMMON/AA/D,OFF,CPD,ENL
COMMON/BB/CN,DHV,ENCVOL,DT,AREADH,AREAHL,LEN
COMMON/CC/SHPM,SHPE,VSUS,VE,RE,SFCM,SFCH,MTYPE,JOPT,MOPT,PC
COMMON/EE/GR4WT(20),GR4CG(20),GR7WT(20),GR7CG(20),AMOWT(20),
1AMOCG(20),ACWT(20),ACCG(20),CARGOW(20),CARGOC(20)
COMMON/FF/TITLE(5,40),HEAD(20),NOARM,NOELT
COMMON/GG/FRSC,KGTRY,DPTRY,DH,BBOX,BS,XLS,CWP
COMMON/HH/CGFUEL,CGLO,CGCREW,CGPE,CGPS,CCARGO,CGMMO,CGAC,CACFUL
COMMON/JJ/H,SEP,XLB,DB,AG,XF,MBLOC1,MBLOC2
COMMON/LL/WTFUEL,WFLO,WTCREW,WTPS,WCARGO,WTMMO,WTAC,WACFUL
COMMON/OO/CGC1,CGC2,CGG3,CGG4,CGG5,CGG6,CGG7,CLSHIP,CFULLD
COMMON/WW/WTG1,WTG2,WTG3,WTG4,WTG5,WTG6,WTG7,WLSHIP,WFULLD,DBMAE
DECKS=1.
IF(DB.GT.13.) DECKS=2.
DT=H+AG+DB
CGG1=.005*DT
IF(DECKS.EQ.1..AND.MOPT.EQ.1) CGG1=.58*DT
IF(DECKS.EQ.1..AND.MOPT.EQ.2) CGG1=.57*DT
CGG2=.15*DT
IF(MTYPE.EQ.1..AND.SHPM.GT.7000.) CGG2=.65*DT
IF(MTYPE.EQ.2) CGG2=.39*DT
IF(MTYPE.EQ.3..AND.MBLOC2.EQ.2) CGG2=.40*DT
IF(MTYPE.EQ.3..AND.MBLOC2.EQ.1) CGG2=.22*DT
IF(MTYPE.EQ.4) CGG2=.43*DT
7 CGG3=.869*DT
IF(DECKS.EQ.2.) CGG3=.782*DT
CGG5=.67*DT
IF(DECKS.EQ.2.) CGG5=.78*DT
CGG6=.88*DT
IF(DECKS.EQ.2.) CGG6=.77*DT
G4MMO=0.
DO 10 I=1,NOELT
10 G4MMO=G4MMO+GR4WT(I)*GR4CG(I)
CGG4=0.

```

VCG 0001
VCG 0002
VCG 0003
VCG 0004
VCG 0005
VCG 0006
VCG 0007
VCG 0008
VCG 0009
VCG 0010
VCG 0011
VCG 0012
VCG 0013
VCG 0014
VCG 0015
VCG 0016
VCG 0017
VCG 0018
VCG 0019
VCG 0020
VCG 0021
VCG 0022
VCG 0023
VCG 0024
VCG 0025
VCG 0026
VCG 0027
VCG 0028
VCG 0029
VCG 0030
VCG 0031
VCG 0032
VCG 0033
VCG 0034
VCG 0035
VCG 0036


```

IF(G4MOM.GT.1.) C334=G4MOM*DT/WTG4
ACMOM=0.
G7MOM=0.
AMOMOM=0.
CGMOMOM=0.
DO 20 I=1,NOARM
ACMOM=ACMOM+ACWT(I)*ACCG(I)
G7MOM=G7MOM+GR7WT(I)*GR7CG(I)
AMOMOM=AMOMOM+AMONT(I)*AMOCG(I)
20 CGMOMOM=CGMOMOM+CARGOW(I)*CARGOC(I)
CGG7=0.
IF(G7MOM.GT.1.) C337=G7MOM*DT/WTG7
CCARGO=0.
IF(CGOMOM.GT.1.) CCARGO=CGOMOM*DT/WCARGO
CGAC=0.
IF(ACMOM.GT.1.) CGAC=ACMOM*DT/WTAC
CGAMMO=0.
IF(AMOMOM.GT.1.) CGAMMO=AMOMOM*DT/WTAMMO
CACFL=CACFUL*DT
CLSHIP=(CGG1*WTG31+CGG2*WTG2+CGG3*WTG3+C334*WTG4+CGG5*WTG5+CGG6*
1WTG6+CGG7*WTG7)*DBMAR/WLSHIP
CGFUEL=.5*DH
CGLO=.83*DT
CGCREW=.89*DT
CGPE=CGCREW
CGPW=.5*DH
CGGS=.83*DT
CGPV=.85*DT
CGPS=(((.0222+.00202*D)*CGPV+.00135*D*CGGS+.186*CGPW)/(.2082+.00337
1*D)
XLDMOM=(CGFUEL*WTFUEL+CGLO*WTLO+CGCREW*WTCREW+CGPE*WTPE+CGPS*WTPS+
1CCARGO*WCARGO+CGAMMO*WTAMMO+CGAC*WTAC+CACFL *WACFUL)
CFULLD=(CLSHIP*WLSHIP+XLDMOM)/WFULLD
CFULD=CFULLD
RETURN
END

```

```

VCG 0037
VCG 0038
VCG 0039
VCG 0040
VCG 0041
VCG 0042
VCG 0043
VCG 0044
VCG 0045
VCG 0046
VCG 0047
VCG 0048
VCG 0049
VCG 0050
VCG 0051
VCG 0052
VCG 0053
VCG 0054
VCG 0055
VCG 0056
VCG 0057
VCG 0058
VCG 0059
VCG 0060
VCG 0061
VCG 0062
VCG 0063
VCG 0064
VCG 0065
VCG 0066
VCG 0067
VCG 0068
VCG 0069
VCG 0070
VCG 0071
VCG 0072

```


COST0001
COST0002
COST0003
COST0004
COST0005
COST0006
COST0007
COST0008
COST0009
COST0010
COST0011
COST0012
COST0013
COST0014
COST0015
COST0016
COST0017
COST0018
COST0019
COST0020
COST0021
COST0022
COST0023
COST0024
COST0025
COST0026
COST0027
COST0028
COST0029
COST0030
COST0031
COST0032
COST0033
COST0034
COST0035
COST0036

SUBROUTINE COST(LEN)
REAL MCST
REAL LEN,LABCST,MAICST,LOA
COMMON/CC/SHPM,SHPE,VSUS,VE,RE,SFCM,SFCH,MYPE,JOPT,MOPT,PC
COMMON/MM/CSTG1,CSTG2,CSTG3,CSTG4,CSTG5,CSTG6,CSTG7,DCST,CCST,MCST
COMMON/NN/DOLHR,31IND,G2IND,G3IND,G5IND,G6IND,TOTCST
COMMON/WW/WTG1,WTG2,WTG3,WTG4,WTG5,WTG6,WTG7,WLSHIP,WFULLD,DBMAR
W1=WTG1*DBMAR
W2=WTG2*DBMAR
W3=WTG3*DBMAR
W4=WTG4*DBMAR
W5=WTG5*DBMAR
W6=WTG6*DBMAR
W7=WTG7*DBMAR
G1MH=10.** (ALOG10(W1)*.75217+2.97276)
G2MH=10.** (ALOG10(W2)*1.0273+2.3437)
G3MH=10.** (ALOG10(W3)*1.07776+2.62981)
G4MH=10.** (ALOG10(W4)*1.07776+2.62981)
G5MH=10.** (ALOG10(W5)*.763428+3.2366)
G6MH=10.** (ALOG10(W6)*.9742+2.74181)
G7MH=10.** (ALOG10(W7)*.75217+2.97276)
31MC=10.** (ALOG10(W1)*.954243+2.790484)
IF(MOPT.EQ.2) G1MC=1.3*G1MC
32MC=CSTG2
IF(JOPT.EQ.2) GO10 1
G2MC=10.** (ALOG10(W2)*1.018885+3.634328)
IF(MTYPE.EQ.2) G2MC=G2MC+200000.
IF(MTYPE.EQ.3) G2MC=451640.*W2**53
IF(MTYPE.EQ.4) G2MC=451640.*W2**53+2000000.
1 33MC=10.** (ALOG10(W3)*1.072551+3.667812)
G4MC=CSTG4
G5MC=10.** (ALOG10(W5)*.870900+3.974192)
G6MC=10.** (ALOG10(W6)*1.068265+3.603833)
G7MC=CSTG7
G1LC=G1MH*DOLHR*1.98
G2LC=G2MH*DOLHR*1.98

G3LC=G3MH*DOLHR*1.98
 G4LC=G4MH*DOLHR*1.98
 G5LC=G5MH*DOLHR*1.98
 G6LC=G6MH*DOLHR*1.98
 G7LC=G7MH*DOLHR*1.98
 G1MC=G1MC*G1IND*1.1
 IF(JOPT.EQ.2) GOTO 2
 G2MC=G2MC*G2IND
 G3MC=G3MC*G3IND*1.1
 G5MC=G5MC*G5IND*1.1
 G6MC=G6MC*G6IND*1.1
 G2MC=G2MC*1.1
 G4MC=G4MC*1.1
 G7MC=G7MC*1.1
 LABCST=G4LC+G2LC+G3LC+G4LC+G5LC+G6LC+G7LC
 MATCST=G1MC+G2MC+G3MC+G4MC+G5MC+G6MC+G7MC
 LOA=1.*LEN
 FACTOR=(.114*LOA-1.6)/100.
 DLC=FACTOR*LABCSI
 FACTOR=(-.01*LOA+7.5)/100.
 DMC=FACTOR*MATCST
 FACTOR=(.014*LOA+7.)/100.
 CLC=FACTOR*LABCST
 FACTOR=(-.015*LOA+6.5)/100.
 CMC=FACTOR*MATCST
 TOTCST=LABCST+MATCST+DLC+DMC+CLC+CMC
 ORICST=.02*TOTCST
 SPARES=(.09*G2MC+.08*G3MC+.25*G4MC+.1*G5MC)/1.1
 RETRO=.04*TOTCST
 ADMIN=.035*TOTCST
 CSTG1=G1LC+G1MC
 CSTG2=G2LC+G2MC
 CSTG3=G3LC+G3MC
 CSTG4=G4LC+G4MC
 CSTG5=G5LC+G5MC
 CSTG6=G6LC+G6MC

2

COST0037
 COST0038
 COST0039
 COST0040
 COST0041
 COST0042
 COST0043
 COST0044
 COST0045
 COST0046
 COST0047
 COST0048
 COST0049
 COST0050
 COST0051
 COST0052
 COST0053
 COST0054
 COST0055
 COST0056
 COST0057
 COST0058
 COST0059
 COST0060
 COST0061
 COST0062
 COST0063
 COST0064
 COST0065
 COST0066
 COST0067
 COST0068
 COST0069
 COST0070
 COST0071
 COST0072

CSIG7=G7LC+G7MC
DCST=DLC+DMC
CCST=CLC+CMC
MCST=ORICST+SPARES+KETRO+ADMIN
TOTCST=TOTCST+MCST
RETURN
END

COST0073
COST0074
COST0075
COST0076
COST0077
COST0078
COST0079

OUTP00001
 OUTP00002
 OUTP00003
 OUTP00004
 OUTP00005
 OUTP00006
 OUTP00007
 OUTP00008
 OUTP00009
 OUTP00010
 OUTP00011
 OUTP00012
 OUTP00013
 OUTP00014
 OUTP00015
 OUTP00016
 OUTP00017
 OUTP00018
 OUTP00019
 OUTP00020
 OUTP00021
 OUTP00022
 OUTP00023
 OUTP00024
 OUTP00025
 OUTP00026
 OUTP00027
 OUTP00028
 OUTP00029
 OUTP00030
 OUTP00031
 OUTP00032
 OUTP00033
 OUTP00034
 OUTP00035
 OUTP00036

```

SUBROUTINE OUTPUT(EXCKG,I1)
REAL LEN,NOFF,NCPO,NENL,KGTRY,MCST
COMMON/AA/D,NOFF,NCPO,NENL
COMMON/BB/CN,DHV,ENCVOL,DT,AREADH,AREAHL,LEN
COMMON/CC/SHPM,SHPE,VSUS,VE,RE,SFCM,SFCH,MTYPE,JOPT,MOPT,PC
COMMON/DD/ELKW,AVKW,ELoad,BLOAD,PALOAD
COMMON/EE/GR4WT(20),GR4CG(20),GR7WT(20),GR7CG(20),AMOWT(20),
1AMOCG(20),ACWT(20),ACCG(20),CARGOW(20),CARGOC(20)
COMMON/FF/TITLE(5,40),HEAD(20),NOARM,NOELT
COMMON/GG/FRSC,KGTRY,DPTRY,DH,BBOX,BS,XLS,CWP
COMMON/HH/CGFUEL,CLO,CGCREW,CGPE,CGPS,CCARGO,CGAMMO,CGAC,CACFUL
COMMON/II/JNDEX,INDEX
COMMON/JJ/H,SEP,XLB,DB,AG,XF,MBLOC1,MBLOC2
COMMON/KK/ELLD(20),DHAR(20),HLAR(20),ELD(20),DHA(20),HLA(20),
1GR7CST(20),GR4CST(20)
COMMON/LL/WFUEL,WLO,WTCREW,WTP2,WTPS,WCARGO,WTAMMO,WTAC,WACFUL
COMMON/MM/CSTG1,CSTG2,CSTG3,CSTG4,CSTG5,CSTG6,CSTG7,DCST,CCST,MCST
COMMON/NN/DOLHR,G1IND,G2IND,G3IND,G5IND,G6IND,TOTCST
COMMON/OO/CGG1,CGG2,CGG3,CGG4,CGG5,CGG6,CGG7,CLSHIP,CFULLD
COMMON/PP/VMB,TANKVL,AVAA,DHAA,ODA,XMFDA,CSDA,OSRDA,OHDA,CPODA,
1CPCHDA,CBDA,CHDA,CODA,CSTDA,OSDA,WDA,RLDA,CLDA,UTDA,SGDA,ACDA,XICD
2A,AMDA,PHDA,WSDA,VMXA
COMMON/QQ/XMLOC1,YMLOC1,ZMLOC1,XMLOC2,YMLOC2,ZMLOC2
COMMON/RR/IREAD,IWRITE
COMMON/WW/WTG1,WTG2,WTG3,WTG4,WTG5,WTG6,WTG7,WLSHIP,WFULLD,DBMAR
WRITE(IWRITE,100) HEAD
100 FORMAT('1',2JA4/)
WRITE(IWRITE,101)
101 FORMAT(T30,'*****INPUT DATA*****')//' ARMAMENT,AIRCRAFT AND CARGO
1INPUTS'//,T9,'ITEM',T26,'CARGO CARGO GROUP 7 GROUP 7 AMMO',T66
2,'AMMO AIRCRAFTAIRCRAFT ELECT AREA IN AREA IN GROUP 7',T25,
3,'WEIGHT VCG #HEIGHT VCG WEIGHT VCG WEIGHT VCG',T90
4,'LOAD DECKHSE HULL COST'//
WRITE(IWRITE,102)((TITLE(J,I),J=1,5),CARGOW(I),CARGOC(I),GR7WT(I),
1GR7CG(I),AMOWT(I),AMOCG(I),ACWT(I),ACCG(I),ELLD(I),DHAR(I),HLAR(I),
2,GR7CST(I),I=1,NOARM)

```



```

102 FORMAT(' ',5A4,F8.1,F8.3,F8.1,F8.3,F8.1,F8.3,F8.3,F8.3,F8.0,
1F8.0,F8.0)
WRITE(IWRITE,103)
103 FORMAT(/' ELECTRONICS INPUT'//T9,' ITEM',T24,' GROUP 4 GROUP 4',T41,
1'ELECT AREA IN AREA IN GROUP 4',T24,' WEIGHT VCG LOAD',T48,
2'DECKHSE HULL COST'/)
WRITE(IWRITE,104)((TITLE(J,I+20),J=1,5),3R4WT(I),GR4C3(I),ELD(I),
1DHA(I),HLA(I),GR4CST(I),I=1,NOELT)
104 FORMAT(' ',5A4,F8.1,2F8.3,3F8.0)
WRITE(IWRITE,105)
105 FORMAT(/' MANNING INPUT'/)
WRITE(IWRITE,106) NOFF,NCPO,NENL
106 FORMAT(' NO. OF OFFICERS = ',F5.0,5X,' NO. OF CPOS = ',F5.0,5X,
1'NO. OF ENLISTED MEN = ',F5.0,/)
WRITE(IWRITE,121)
121 FORMAT(' COST INDICES INPUT'/)
WRITE(IWRITE,119) DOLHR,G1IND,G2IND,G3IND,G5IND,G6IND
119 FORMAT(' LABOR RATE = ',F5.2,' DOLLARS/HR'/' GROUP 1 INDEX = ',
1F5.2/' GROUP 2 INDEX = ',F5.2/' GROUP 3 INDEX = ',F5.2/' GROUP
25 INDEX = ',F5.2/' GROUP 6 INDEX = ',F5.2/)
WRITE(IWRITE,120)
120 FORMAT(' INDICES INCLUDE EFFECTS OF INFLATION AND SPECIAL MAT
1ERIAL COSTS'/)
WRITE(IWRITE,107)
107 FORMAT(' MILITARY MISSION CONSUMABLES INPUT'/)
WRITE(IWRITE,108) D,WACFJL,CACFUL
108 FORMAT(' NO. ENDURANCE DAYS = ',F5.0,' WEIGHT AIRCRAFT FUEL = ',
1F7.1,' VCG AIRCRAFT FUEL = ',F8.3)
DBMAR=DBMAR-1.
WRITE(IWRITE,109)
109 FORMAT(/' VEHICLE PERFORMANCE INPUT')
IF(JOPT.EQ.2) GOTO 2
WRITE(IWRITE,110) VSUS,VE,RE,PC
110 FORMAT(/' MAX SUSTAINED SHP COMPUTED'/' SUSTAINED SPEED = ',F8.2
1,' KTS'/' ENDURANCE SPEED = ',F8.2,' KTS'/' ENDURANCE RANGE = ',
2F8.0,' MILES'/' PROP COEFF = ',F5.3/)

```

```

OUTP00037
OUTP00038
OUTP00039
OUTP00040
OUTP00041
OUTP00042
OUTP00043
OUTP00044
OUTP00045
OUTP00046
OUTP00047
OUTP00048
OUTP00049
OUTP00050
OUTP00051
OUTP00052
OUTP00053
OUTP00054
OUTP00055
OUTP00056
OUTP00057
OUTP00058
OUTP00059
OUTP00060
OUTP00061
OUTP00062
OUTP00063
OUTP00064
OUTP00065
OUTP00066
OUTP00067
OUTP00068
OUTP00069
OUTP00070
OUTP00071
OUTP00072

```



```

GOTO 3
2 WRITE(IWRITE,111) SHPM,WIG2,SFCM,SFCH,VE,RE,PALOAD,PC,CSTG2,WTLO,
  1MBLOC1,XMLOC1,MBLOC2,XMLOC2,YMLOC2,ZMLOC2
111 FORMAT(' MAX SUSTAINED SPEED COMPUTED',, MAX SUSTAINED SHE = ',
  1F8.0,, GROUP 2 HEIGHT = ',F8.1,' IONS',, SFC MAX POWER = ',F5.3
  2,' LBS/SHP-HR',, SFC HALF POWER = ',F5.3,' LBS/SHP-HR',, ENDURAN
  3CE SPEED = ',F8.2,' KTS',, ENDURANCE RANGE = ',F3.0,' MILES',, P
  4ROP AUX ELECT LOAD = ',F8.3,' KW',, PROP COEFFICIENT = ',F5.3,,
  5' GROUP 2 COST = ',F9.0,' DOLLARS',, WEIGHT OF LUBE OIL = ',F8.1,
  6' TONS',, PROPULSOR LOCATION = ',I1,' 1=HULL',, PROPULSOR LENGT
  7H = ',P5.2,' FEET',, PRIME MOVER LOC = ',I1,' 2=BOX',, MACHY S
  8PACE DIMS (L X W X H) = ',F5.2,' X ',F5.2,' X ',F5.2,' FEET',)
3 WRITE(IWRITE,112) MIYPE,FRSC,DBMAR,LEN,MOPF
112 FORMAT(' OPTIONS',, MIYPE = ',I2,, FREE SURFACE CORRECTION =
  1',F5.2,' FT',, DESIGN AND BUILDERS MARGIN = ',F5.3,, LENGTH =
  2',F5.1,' FT',, MATERIAL = ',I2,' 1=STL,2=AL',)
  IF(I1.EQ.1) RETURN
  WRITE(IWRITE,113)
113 FORMAT(//,T33,'*****OUTPUT*****',, LENGTH BEAM DRAFT DIAM
  1LSTRUT BSTRUT CWP LBOX BBOX DBOX DISPLACEMENT SHPMAX VSJS
  2 SHPEND',)
  WRITE(IWRITE,114) LEN,BBOX,H,DH,XLS,BS,CWP,XLB,EBOX,DB,DPTRY,SHPM,
  1VSUS,SHPE
114 FORMAT(' ',F6.1,F3.2,F7.2,F6.2,F8.2,F7.2,F6.3,F7.2,2F6.2,F11.2,F10
  1.2,F6.2,F9.2)
  VOL=ENCVOL-DHV
  WRITE(IWRITE,115) ELKW
115 FORMAT(' ELECTRIC PLANT CAPACITY/GEN = ',F3.0,' KW',)
  FFE=1.+DBMAR
  R1=WTG1/WFULLD*FFF
  R2=WTG1/WLSHIP*FFF
  R3=WTG2/WFULLD*FFF
  R4=WTG2/WLSHIP*FFF
  R5=WTG3/WFULLD*FFF
  R6=WTG3/WLSHIP*FFF
  R7=WTG4/WFULLD*FFF

```

GOTO 3

OUTP0109
 OUTP0110
 OUTP0111
 OUTP0112
 OUTP0113
 OUTP0114
 OUTP0115
 OUTP0116
 OUTP0117
 OUTP0118
 OUTP0119
 OUTP0120
 OUTP0121
 OUTP0122
 OUTP0123
 OUTP0124
 OUTP0125
 OUTP0126
 OUTP0127
 OUTP0128
 OUTP0129
 OUTP0130
 OUTP0131
 OUTP0132
 OUTP0133
 OUTP0134
 OUTP0135
 OUTP0136
 OUTP0137
 OUTP0138
 OUTP0139
 OUTP0140
 OUTP0141
 OUTP0142
 OUTP0143
 OUTP0144

```

R8=WTG4/WLSHIP*FFF
R9=WTG5/WFULLD*FFF
R10=WTG5/WLSHIP*FFF
R11=WTG6/WFULLD*FFF
R12=WTG6/WLSHIP*FFF
R13=WTG7/WFULLD*FFF
R14=WTG7/WLSHIP*FFF
R15=WLSHIP/WFULLD
R16=1.
WRITE(IWRITE,116) WTG1,CGG1,R1,R2,CSTG1,WTG2,CGG2,R3,R4,CSTG2,WTG3
1,CGG3,R5,R6,CSTG3,WTG4,CGG4,R7,R8,CSTG4,WTG5,CGG5,R9,R10,CSTG5,WTG
20,CGG6,R11,R12,CSTG6,WTG7,CGG7,R13,R14,CSTG7,WLSHIP,CLSHIP,R15,R16
3,TOTCST
116 FORMAT(' ',8X,'WEIGHTS          VCG      WI/WFULLD  WT/WLSHIP   CO
1ST'//,F10.1,3F12.3,F12.0/' WTG2',F10.1,3F12.3,F12.0/' WTG3',
2,F10.1,3F12.3,F12.0/' WTG4',F10.1,3F12.3,F12.0/' WTG5',F10.1,3F12.
33,F12.0/' WTG6',F10.1,3F12.3,F12.0/' WTG7',F10.1,3F12.3,F12.0//,
4' WLSHIP',F8.1,3F12.3,F12.0,' = TOTAL COST'//)
R1=WFUEL/WFULLD
R2=WTLO/WFULLD
R3=WTCREW/WFULLD
R4=WTPE/WFULLD
R5=WTPS/WFULLD
R6=WCARGO/WFULLD
R7=WTAMMO/WFULLD
R8=WTAC/WFULLD
R9=WACFUL/WFULLD
CACFL=CACFUL*DT
WRITE(IWRITE,117) WFFUEL,CGFUEL,R1,WTLO,CGLO,R2,WTCREW,CGCREW,R3,
1WTPE,CGPE,R4,WTPS,CGPS,R5,WCARGO,CCARGO,R6,WTAMMO,CGAMMO,R7,WTAC,
2CGAC,R8,WACFUL,CACFL,R9,WFULLD,CFULLD
117 FORMAT(' FUEL',F10.1,2F12.3/' LUB OIL',F7.1,2F12.3/' CREW',F10.1,
12F12.3/' PER EFF',F7.1,2F12.3/' PER STR',F7.1,2F12.3/' CARGO',F9.1
2,2F12.3/' AMMO',F10.1,2F12.3/' AIR CFT',F7.1,2F12.3/' A/C FUEL',
3F6.1,2F12.3//,WFULLD,F8.1,F12.3//)
WRITE(IWRITE,122) EXCKG
  
```


122 FORMAT(' A MARGIN ON KG OF ',F6.3,' FT EXISTS ABOVE THE FULL LOAD
1KG VALUE GIVEN '//)
WRITE(IWRITE,118) DCST,CCST,MCST
118 FORMAT(' NOTE 35B MARGIN INCLUDED IN WLSHIP AND COST ESTIMATES B
10T NOT IN INDIVIDUAL WEIGHT GROUPS'// OVERHEAD AND PROFIT A
2RE INCLUDED IN INDIVIDUAL WEIGHT GROUP COSTS'// TOTAL COST
3INCLUDES A DESIGN COST OF',F12.0,' DOLLARS'// ',19X,'A CONST SERVI
4CES COST OF',F12.0,' DOLLARS'// ',19X,'AND A MISC. ITEM COST OF',
5F12.0,' DOLLARS'// MISC.ITEM COST INCLUDES ORI OUTFIT, SPAR
6ES, RETROFIT COSTS, AND ADMINISTRATIVE COSTS(RIO)'//)
WRITE(IWRITE,123) VOL,DHV
123 FORMAT(' VOLUME HULLS,STRUTS&BOX = ',F10.0,' CU FT'//, VOLUME OF
1 DECKHOUSE = ',F10.0,' CU FT'//)
AAVOM=VOL-VMB-TANKVL+DHV
R1=VMB/ENCVOL
R2=TANKVL/ENCVOL
R3=AAVOM/ENCVOL
WRITE(IWRITE,124) VMB,R1,TANKVL,R2,AAVOM,R3
124 FORMAT(' T26, VOLUME(CU FT) VOL/ENCVOL'//, MACHINERY ROOM',T28
1,F10.0,F15.3/ TANKAGE',T28,F10.0,F15.3/ ARRANGEMENTS',T28,F10.0,
2F15.3/)
AR=AVAA+DHAA
WRITE(IWRITE,125) AR,AVAA,DHAA
125 FORMAT(' TOTAL ARRANGEMENTS AREA = ',F9.0/ HULL ARRANGEMENTS ARE
1A = ',F9.0/ DKHSE ARRANGEMENT AREA = ',F8.0/)
WRITE(IWRITE,126)
126 FORMAT(' ',T30,'AREA(SQ FT) AREA/TOT AREA'//)
R4=ODA/AR
R5=XMFDA/AR
R6=CSDA/AR
R7=OSFDA/AR
R8=OHDA/AR
WRITE(IWRITE,127) ODA,R4,XMPDA,R5,CSDA,R6,OSRDA,R7,OHDA,R8
127 FORMAT(' OFFICE SPACE',T30,F10.0,F13.3/ MESSING FACILITIES',T30,
1F10.0,F13.3/ CREW SPECIAL',T30,F10.0,F13.3/ OFFICER S.R.',T30,
2F10.0,F13.3/ OFFICER SANITARY',T30,F10.0,F13.3)

OUTP0181
 OUTP0182
 OUTP0183
 OUTP0184
 OUTP0185
 OUTP0186
 OUTP0187
 OUTP0188
 OUTP0189
 OUTP0190
 OUTP0191
 OUTP0192
 OUTP0193
 OUTP0194
 OUTP0195
 OUTP0196
 OUTP0197
 OUTP0198
 OUTP0199
 OUTP0200
 OUTP0201
 OUTP0202
 OUTP0203
 OUTP0204
 OUTP0205
 OUTP0206
 OUTP0207
 OUTP0208
 OUTP0209
 OUTP0210
 OUTP0211
 OUTP0212
 OUTP0213
 OUTP0214
 OUTP0215
 OUTP0216

R4=CPODA/AR
 R5=CPOHDA/AR
 R6=CBDA/AR
 R7=CHDA/AR
 R8=CODA/AR
 WRITE(IWRITE,128) CPODA,R4,CPOHDA,R5,CBDA,R6,CHDA,R7,CODA,R8
 128 FORMAT(' CPO S.R.',T30,F10.0,F13.3/' CPJ SANITARY',T30,F10.0,F13.3
 1/' CREW BERTHING',T30,F10.0,F13.3/' CREW SANITARY',T30,F10.0,F13.3
 2/' C.O. S.R.,CABIN & PANTRY',T30,F10.0,F13.3)
 R4=CSTDA/AR
 R5=OSDA/AR
 R6=WDA/AR
 R7=RLDA/AR
 R8=CLDA/AR
 WRITE(IWRITE,129) CSTDA,R4,OSDA,R5,WDA,R6,RLDA,R7,CLDA,R8
 129 FORMAT(' COMMISSARY STORES',T30,F10.0,F13.3/' OTHER STORES',T30,
 1F10.0,F13.3/' WORKSHOPS',T30,F10.0,F13.3/' REPAIR LOCKERS',T30,
 2F10.0,F13.3/' CHAIN LOCKER',T30,F10.0,F13.3)
 R4=UTDA/AR
 R5=SGDA/AR
 R6=ACDA/AR
 R7=XICDA/AR
 R8=AMDA/AP
 R9=PHDA/AR
 PDA=.1*AR
 R10=PDA/AP
 R11=WSDA/AR
 R12=VMXA/AR
 WRITE(IWRITE,130) UTDA,R4,SGDA,R5,ACDA,R6,XICDA,R7,AMDA,R8,PHDA,R9
 1,PDA,R10,WSDA,R11,VMXA,R12
 130 FORMAT(' UPTAKES',T30,F10.0,F13.3/' STEERING GEAR & FINS',T30,
 1F10.0,F13.3/' A/C & FAN SPACES',T30,F10.0,F13.3/' I.C. SPACES',T30
 2,F10.0,F13.3/' AUX MACHINERY SPACES',T30,F10.0,F13.3/' PILOT HOUSE
 3,CHARTROOM & CIC',T30,F10.0,F13.3/' PASSAGES',T30,F10.0,F13.3/' MO
 4ORING STATIONS',T30,F10.0,F13.3/' MAIN MACHINERY IN BOX',T30,F10.0
 5,F13.3)

OUTP0217
 OUTP0218
 OUTP0219
 OUTP0220
 OUTP0221
 OUTP0222
 OUTP0223
 OUTP0224
 OUTP0225
 OUTP0226
 OUTP0227
 OUTP0228
 OUTP0229
 OUTP0230
 OUTP0231
 OUTP0232
 OUTP0233
 OUTP0234
 OUTP0235
 OUTP0236
 OUTP0237
 OUTP0238
 OUTP0239
 OUTP0240
 OUTP0241
 OUTP0242
 OUTP0243
 OUTP0244
 OUTP0245
 OUTP0246
 OUTP0247
 OUTP0248
 OUTP0249
 OUTP0250
 OUTP0251
 OUTP0252

```

ARE=AREADH+AREAHL
R1=ARE/AR
HABSPC=XMFDA+CSDA+OSRDA+OHDA+CPODA+CPOHDA+CBDA+CHDA+CODA
EXAR=AR-1.1*(HABSPC+ODA+CSTDA+OSDA+WDA+RLDA+CLDA+UTDA+ACDA+XICDA
1+AMDA+PHDA+ARE+WSDA+VMXA)
R2=EXAR/AR
WRITE(IWRITE,131) ARE,R1,EXAR,R2
131 FORMAT(' INPUT AREA',T30,F10.0,F13.3/' EXCESS AREA',T30,F10.0,F13.
13/)
WRITE(IWRITE,132)
132 FORMAT(' CREW SPECIAL INCLUDES SICKBAY,BARBERSHOP,MOVIE LOCKER, L
1AUNDRY,AND SHIPS STORE'////)
HABSPC=HABSPC*9.
COEF1=HABSPC/(NOFF+NCP0+NENL)
COEF2=WTG2/SHPM
COEF3=VMB/SHPM
COEF4=WTG1/ENCVOL
COEF5=WFULLD/ENCVOL
COEF6=WLSHIP/ENCVOL
COEF7=CSTG4/TOTCST
COEF8=CSTG7/TOTCST
COEF9=CFULLD/DI
WRITE(IWRITE,133) COEF1,COEF2,COEF3,COEF4,COEF5,COEF6,COEF7,COEF8,
1COEF9
133 FORMAT(' HAB VOL/MAN = ',F10.1,' CUFT/MAN'/' GR2WT/HP = ',F6.4,
1' TONS/HP'/' MACH ROOM VOL/HP = ',F7.4,' CUFT/HP'/' GR1WT/ENCVOL =
2',F7.5,' TONS/CUFT'/' WFULLD/ENCVOL = ',F7.5,' TONS/CUFT'/' WLSHI
3P/ENCVOL = ',F7.5,' TONS/CUFT'/' GR4COST/TOTCOST = ',F6.3/' GR7COS
4T/TOTCOST = ',F6.3/' VCG/D = ',F6.3//)
C REMOVE THE FOLLOWING 4 CARDS FOR AN UNRESTRICTED RUN
IF(JNDEX.GT.5.OR.LNDEX.GT.5) GO TO 1000
RETURN
1000 WRITE(IWRITE,134) SHPM,SHPE
134 FORMAT(' WARNING--AFTER FIVE HPCALC ITERATIONS, SHPM AND SHPE FIX
1ED AT ',F10.2,' AND ',F9.2//)
RETURN
  
```


APPENDIX C
SAMPLE OUTPUT

•••••ИВРИТ ПАТЯ•••••

[illegible]

21 ELECTRONICS INPUT

Banking Input

CCST INDICES INPUT

861 9 8003
13001 5 80343
1.88

MEASURES INCLUDE EFFECTS OF INFLATION AND SPECIAL NATIONAL COSTS

DC. ENDURANCE DAYS = 20. WEIGHT AIRCRAFT FULL = 91.0 VCG AIRCRAFT FULL = 0.110

001.3 • 42703 37M1

LENGTH = 209.0 FT

PACMAN PROCEEDING TO NEXT INPUT CASE

***** INPUT ERROR *****

[illegible][illegible]

II12H
GROUP 4 GSCUF 4 ELECT AREA IN AREA IN GROUP 4
WEIGHT VCG ACAL BECAUSE HUL COST

SECOP 4 90.0 1,000 25,000 887. 1239.2157000.

NO. OF OFFICERS = 13, NO. CF CFOS = 10, NO. CF ENLISTED MEN = 80.

LOEC RATE = 5.00 DOLLARS/HOUR

GROUP 1 INDEX	=	2.25
GROUP 2 INDEX	=	2.18
GROUP 3 INDEX	=	1.63
GROUP 5 INDEX	=	1.94
GROUP 6 INDEX	=	1.98

ABILITY MISSION CAPABLES INFU

EC. ENCURENCE DAYS = 20. WEIGHT AIRCRAFT FUEL = 91.0 VCG AIRCRAFT FUEL = 0.110

MAX SUSTAINED SHP COMPUTED
SUSTAINIC SPEED = 19.70 KTS
EMCUNRANCE SPD = 12.00 KTS
EMCUNRANCE RANGE = 3000. MILES
EFFICE COEFF = 0.700

TYPE = 2
FREE SURFACE CORRECTION = 6.5C FT
CESSION AND EULIDERS MARGIN = 0.150
LENGTH = 240.0 FT
MATERIAL = 1 1=STL2=AL

LUNGER 22AN DRAFT DIAM 15100T 15100T CUP 180X 28C1 CBOX DISPLACEMENT SHPMAX VSUS SHPEND

200.0 01.50 26.37 16.70 193.00 7.20 7.542 213.00 01.50 13.00 3267.55 15270.62 19.70 2673.20

ELECTRIC PLANT CAPACITY/GEN = 750. KW

WEIGHTS WCG WT/WEU10 WT/WEU11 CCST

W001	1361.2	33.276	0.479	0.552	0035366.
W002	900.1	22.375	0.155	0.179	12197838.
W003	127.6	49.856	0.045	0.052	2818957.
W004	90.0	57.372	0.032	0.037	3099681.
W005	245.1	34.439	0.086	0.099	4063828.
W006	183.8	50.487	0.065	0.075	3036624.
W007	16.7	60.814	0.006	0.007	430906.

WISHP 2034.1 35.051 0.867 1.000 40991846. = TOTAL COST

FUEL 253.2 8.392 0.077

ICE OIL 20.3 47.619 0.006

CREW 7.6 51.061 0.002

FIB FPP 4.4 51.061 0.001

FIB STR 28.4 21.406 0.009

CARGO 0.0 0.0 0.0

APRC 8.9 51.061 0.001

AIR CPT 25.0 63.109 0.006

A/C FUEL 91.0 0.311 0.028

WEU10 3268.9 32.843

A MARGIN ON KG OF 0.0 FT EXISTS ABOVE THE FULL LOAD KG VALUE GIVEN

BCE 266 MARGIN INCLUDED IN WISHP AND CCST ESTIMATES BUT NOT IN INDIVIDUAL WEIGHT GROUPS

OVERHEAD AND PROFIT ARE INCLUDED IN INDIVIDUAL WEIGHT GROUP COSTS

TOTAL COST INCLUDES A DESIGN COST OF 3386424. DOLLARS

A CONST SERVICES COST OF 1549607. DOLLARS

AND A MISC. ITEM COST OF 5178419. DOLLARS

BISC ITEM COST INCLUDES CR1 OUTFIT, SPARES, RETECPT COSTS, AND ADMINISTRATIVE COSTS (RIO)

VOLUME HULLS, STRUCTURES = 390306. CU FT

VOLUME CP TECHHOUSE = 53503. CU FT

VOLUME (CU FT) VCL/INCL

BACHINERY ROOM 40453. 0.091

TANKAGE 19660. 0.044

ASSANGEMENTS 303697. 0.865

[illegible][illegible]

ELECTRONICS INPUT

GROUP #	90.0	1,000	25,000	887.	1239,2157000.

NO. OF OFFICERS = 13. NO. CF CPOS = 1C. NO. CF INLISTED MEN = 80.

PRICE RATE = 5.80 DOLLARS/HR

INDICES OF INFLATION AND SPECIAL MATERIAL COSTS

MC. ENDURANCE DAYS = 2C. WEIGHT AIRCRAFT FUEL = 91.0 VCG AIRCRAFT FUEL = 0.110

MAX SUSTAINED SHP COMPUTED

CITATIONS

TYPE = J
GRIFF SURFACE CORRECTION = 0.50 FT
CORRECTION AND BUILDERS MARGIN = C.15C
LENGTH = 240.0 FT
INTERVAL = 1 1=511.2=AL

LENGTH BEAM DRAFT DIAM LSSBOT BSBOT CAP LBOX BBOX DBOX DISPLACEMENT SHPRAI VSUS SHPEND
240.0 77.33 27.18 15.53 193.00 6.72 C.942 213.00 77.33 13.00 2053.30 30610.90 24.00 2040.30

ELECTRIC PLANT CAPACITY/GEN = 750. MW

WEIGHTS	VCG	WT/WPULLD	WT/WISHP	CCST
WGT1 1232.4	32.007	C.496	C.570	4084324.
WGT2 274.3	12.141	C.110	C.129	2375840.
WGT3 121.3	87.955	C.049	C.057	2662360.
WGT4 90.0	55.184	C.036	C.042	3055661.
WGT5 226.1	36.974	C.091	C.106	1800220.
WGT6 172.9	48.562	C.070	C.081	3594545.
WGT7 16.7	50.496	C.007	C.008	430506.

WISHP 2453.7 33.412 C.859 1.000 54191424. = TOTAL COST

PULL 234.9	7.767	C.002
LUB OIL 7.4	45.803	C.003
CRN 7.6	43.114	C.003
PER EFF 4.4	43.114	C.002
EFF STR 28.4	20.384	C.010
CARGO 0.0	0.0	C.0
ARMO 4.9	49.114	C.002
AIR CPT 25.0	68.703	C.009
A/C PULL 91.0	6.070	C.032
WPULLD 2657.2	30.667	

A MARGIN ON KG OP 0.0 FT EXISTS ABOVE THE FULL LOAD KG VALUE GIVEN

NOTE PER MARGIN INCLUDED IN WISHP AND CCST ESTIMATES PUT MGT IN INDIVIDUAL WEIGHT GROUPS
OVERHEAD AND PROFIT ARE INCLUDED IN INDIVIDUAL WEIGHT GROUP CCST
TOTAL COST INCLUDES A DESIGN COST OF 3721665. DOLLARS
A CONST SERVICE COST OF 1742819. DOLLARS
AND A MISC. ITEM COST OF 7213530. DOLLARS

MISC ITEM COST INCLUDES CBI OUTFIT, SPARES, RETROFIT COSTS, AND ADMINISTRATIVE COSTS (MIO)

VOLUME BULLS, STRUTSBOX = 360017. CU FT
VOLUME CP DECKHOUSE = 42469. CU FT

	VOLUME (CU FT)	VOLUME (CU FT)
MACHINERY ROOM	24082	C.060
TANKAGE	16109	C.085
ARRANGEMENTS	360296	C.895

Information Processing Center

Information

019. - 0187 6267287800 15003
0202. - 0187 6267287800 15003

APCA (FC 71) 1111/101 1000

OFFICE SPACE	177.	C.012
MISSING FACILITIES	1728.	C.073
CHIN SOCIAL	636.	C.019
OFFICER S.B.	949.	C.041
OFFICER SALARY	156.	C.007
CIC S.C.	460.	C.017
CIC SALARY	80.	C.003
COIN BERTHING	1760.	C.076
COIN SALARY	400.	C.019
C.C. S.B. CABIN & ENTRY	691.	C.021
COURTSHIP STOPS	341.	C.015
CHUB STOPS	1940.	C.040
SCENES	971.	C.042
BEARD LOCKERS	145.	C.046
CHAIN LOCKER	80.	C.002
ROTATES	700.	C.030
STREETING HELP & PTES	154.	C.083
W.C. PAN SPACES	217.	C.013
I.C. SPACES	215.	C.009
AND RECHISTRY SPACES	392.	C.152
PICT HOUSE, CARTOON & CIC	910.	C.040
FRAGS	2302.	C.100
RECORDING STATIONS	725.	C.031
MAIL RECHISTRY IN PCX	6.	C.6
EDUT AREA	426.	C.100
EXCESS AREA	141.	C.095

CROW SPECIAL INCLUDES SIGNRAY, BABYRUSCH, MOVIE LOCER, LAURENCE, AND SHIPS STORE

BAB VOL/HAB = 559.2 CUPY/HAB
GRAT/MP = 0.0071 TCMS/MP
RACR/BCR VOL/MP = 0.9233 CUPY/MP
CALIN/23CCL = 0.6236 TONS/CUPY
MULTI/23CCL = 0.6710 TONS/CUPY
MIS/MP/BCR VOL = 0.6610 TONS/CUPY
607CCST/TCOST = 0.957
607CCST/TCOST = 0.008
455E1 = 0.956

Index

0000IKPM CAT0000

[illegible][illegible]

DATE	DESCRIPTION	AMOUNT	BALANCE
1980	1980	2500.00	2500.00
1981	1981	1000.00	1500.00
1982	1982	500.00	1000.00
1983	1983	250.00	750.00
1984	1984	125.00	625.00
1985	1985	62.50	562.50
1986	1986	31.25	531.25
1987	1987	15.62	515.62
1988	1988	7.81	507.81
1989	1989	3.90	503.90
1990	1990	1.95	501.95
1991	1991	0.97	500.97
1992	1992	0.49	500.48
1993	1993	0.24	500.24
1994	1994	0.12	500.12
1995	1995	0.06	500.06
1996	1996	0.03	500.03
1997	1997	0.01	500.01
1998	1998	0.00	500.00
1999	1999	0.00	500.00
2000	2000	0.00	500.00
2001	2001	0.00	500.00
2002	2002	0.00	500.00
2003	2003	0.00	500.00
2004	2004	0.00	500.00
2005	2005	0.00	500.00
2006	2006	0.00	500.00
2007	2007	0.00	500.00
2008	2008	0.00	500.00
2009	2009	0.00	500.00
2010	2010	0.00	500.00
2011	2011	0.00	500.00
2012	2012	0.00	500.00
2013	2013	0.00	500.00
2014	2014	0.00	500.00
2015	2015	0.00	500.00
2016	2016	0.00	500.00
2017	2017	0.00	500.00
2018	2018	0.00	500.00
2019	2019	0.00	500.00
2020	2020	0.00	500.00
2021	2021	0.00	500.00
2022	2022	0.00	500.00
2023	2023	0.00	500.00
2024	2024	0.00	500.00
2025	2025	0.00	500.00
2026	2026	0.00	500.00
2027	2027	0.00	500.00
2028	2028	0.00	500.00
2029	2029	0.00	500.00
2030	2030	0.00	500.00
2031	2031	0.00	500.00
2032	2032	0.00	500.00
2033	2033	0.00	500.00
2034	2034	0.00	500.00
2035	2035	0.00	500.00
2036	2036	0.00	500.00
2037	2037	0.00	500.00
2038	2038	0.00	500.00
2039	2039	0.00	500.00
2040	2040	0.00	500.00
2041	2041	0.00	500.00
2042	2042	0.00	500.00
2043	2043	0.00	500.00
2044	2044	0.00	500.00
2045	2045	0.00	500.00
2046	2046	0.00	500.00
2047	2047	0.00	500.00
2048	2048	0.00	500.00
2049	2049	0.00	500.00
2050	2050	0.00	500.00
2051	2051	0.00	500.00
2052	2052	0.00	500.00
2053	2053	0.00	500.00
2054	2054	0.00	500.00
2055	2055	0.00	500.00
2056	2056	0.00	500.00
2057	2057	0.00	500.00
2058	2058	0.00	500.00
2059	2059	0.00	500.00
2060	2060	0.00	500.00
2061	2061	0.00	500.00
20			

GROUP	90.0	1,000	25,000	107.	1239.2157000.
GROUP 9	90.0	1,000	25,000	107.	1239.2157000.

NO.	NAME	NO. CP CPES	NO. CP INFLTRD AIN	NO.
13.	MC. CP OFFICERS	10.	10.	10.

LABOR DAY =	5.96 COLLABS/HR
GF CUP 1 INDEX =	2.25
GROUP 2 INDEX =	2.18
GF CUP 3 INDEX =	1.67
GF CUP 5 INDEX =	1.84
GF CUP 6 INDEX =	1.98

INDICES INCLUDE EFFECTS OF TOPLICAL AND SPECIAL DENTAL COSTS

FC. ENDURANCE DAYS - 20. WEIGHT AIRCRAFT FUEL - 91.0 VSC AIRCRAFT FUEL - 0.110

031NDW03 374DS C3N1VJ5NS XRU

RAY SUSTAINED \$MP = 12002.

HEIGHT = 281.0 YRS = 63.400

11/15/2011 10:00 AM

SLX 00'71 - C25DS 3CNV9Q291

PERFORMANCE RANGE = 3000. MILES

FRCF_AIR_ELECT_LOAD = 70.50C

PRCF COEFFICIENT = 0.700

GPCUF 2 CCSF = 10664656. FOLLOW

110001 43 423111

1133 00 51 8 45:361 8061JJ333
7104-1 1 8 40:14771 435704714

PRIME ACAPB LCC = 12.80K

• (H I 6 I 7) SWID 3CV35 2H3R0

100

SCROLLS

1. The first group of people who are interested in the results of the study are the researchers themselves. They want to know if the study was successful in achieving its objectives and if the results are consistent with their expectations.

1914

DESIGN AND BUILDERS MARGIN = 6.3%

REC'D - 249.9 P

17-2'135-1 1 = 17151370

100

243

TOTAL ARRANGEMENTS AREA = 23195.
 BOIL ARRANGEMENTS AREA = 18456.
 CRUSE ARRANGEMENTS AREA = 4739.

AREA(SQ FT) AREA/100 AREA

OFFICE SPACE	277.	C.012
MESSING FACILITIES	1726.	C.074
CREW SPECIAL	436.	C.019
OFFICER S.B.	949.	C.041
OFFICER SANITARY	156.	C.007
CPC S.B.	400.	C.017
CIC SANITARY	80.	C.003
CREW BERTHING	1760.	C.076
CREW SANITARY	400.	C.017
C.O. S.B., CABIN & ENTRY	493.	C.021
COMMUNISIBY STORES	343.	C.015
OTHER STORES	1985.	C.086
WORKSHOPS	1000.	C.043
REPAIR LOCKERS	145.	C.006
CHAIN LOCKER	40.	C.002
OPTAKES	0.	C.C
STEERING GEAR & PINS	1997.	C.086
A/C & E.A. SPACES	324.	C.014
I.C. SPACES	215.	C.035
AUX MACHINERY SPACES	3573.	C.154
PILOT HOUSE, CHARTROOM & CIC	929.	C.040
PASSAGES	2320.	C.100
HCCING STATIONS	725.	C.031
MAIN MACHINERY IN ECK	0.	0.0
INLET AREA	4326.	C.187
EXCESS AREA	886.	C.038

CREW SPECIAL INCLUDES SICKBAY, BARBERSHCP, ACVIE LOCKER, LAUNDRY, AND SHIPS STORE

BAR VOL/BAF = 559.2 CUFT/BAF
 GR267/HP = 0.0088 TONS/HP
 BACH ROCH VOL/HP = 0.7824 CUFT/HE
 GR261/ENCVCL = 0.00310 TONS/CUFT
 BUILD/ENCVCL = 0.00734 TONS/CUFT
 BUSHIP/ENCVOL = 0.00613 TONS/CUFT
 GR4CCST/TOICOST = 0.081
 GR7CCST/TOICOST = 0.011
 VCO/E = 0.542

LENGTH BEAR DECK BY DIAH 135000 310000 CIP 1000 1000 DBOX DISPLACEMENT SUPPLY VSUS SHIPEND
 155.0 50.91 10.91 10.01 125.00 0.54 C.50 105.00 50.91 13.00 071.33 2004.03 15.00 1124.40

ELECTRIC PLANT CAPACITY/GIN = 500. K6

WEIGHTS	WGT	WT/BUCKET	WT/SHIP	CCST
WTG1	299.8	24.943	0.305	1367751.
WTG2	53.2	17.504	0.064	9324571.
WTG3	79.2	32.227	0.102	1639715.
WTG4	4.0	43.759	0.005	409050.
WTG5	102.9	29.319	0.132	1932533.
WTG6	59.6	30.503	0.124	1972311.
WTG7	6.0	46.345	0.008	518204.
SHIP	710.6	29.100	0.024	1.000 22226736. = TOTAL COST
PULL	107.4	5.403	0.123	
LUR CIL	3.8	36.320	0.004	
CEB	2.8	39.946	0.003	
PER EFF	1.6	30.946	0.002	
PER STN	12.5	15.653	0.012	
CARGO	0.0	0.0	0.0	
ARPC	3.5	30.946	0.004	
AIB CPT	9.0	48.135	0.010	
A/C PULL	15.0	4.813	0.017	
SPEED	072.1	25.920		

Information Processing Center

A MARGIN ON KG OF 0.0 PT EXISTS ABOVE THE FULL ICAD KG VALUE GIVEN

NOTE 060 MARGIN INCLUDED IN SHIP AND COST ESTIMATES BUT NOT IN INDIVIDUAL WEIGHT GROUPS
 OVERHEAD AMT PROFIT ARE INCLUDED IN INDIVIDUAL WEIGHT GROUP COSTS
 TOTAL COST INCLUDES A DESIGN COST OF 133899. ECCLARS
 A CONST SERVICES COST OF 869934. ECCLARS
 AND A MISC. ITEM COST OF 2855999. ECCLARS
 MISC. ITEM COST INCLUDES CMI OUTPUT, SEARIES, RETROFIT COSTS, AND ADMINISTRATIVE COSTS (BIO)

VOLUME BULLS, STRUTS BOX = 156625. CU FT
 VOLUME CF DECKHOUSE = 10333. CU FT

VOLUME (CU FT)	WGT/ENCLOS
MACHINERY ROOM	10602.
TANKAGE	6615.
ARRANGEMENTS	109541.
	0.064
	0.041
	0.096

Information

APPENDIX D

NAVSHIPS HULL GROUP WEIGHT CLASSIFICATION OF 1965

Group 1 - Hull Structure

- 100 - Shell Plating and Planking
- 101 - Longitudinal and Transverse Framing
- 102 - Inner Bottom
- 103 - Platform and Flats Below Lowermost Continuous Deck
- 104 - Fourth and Lower Continuous Decks
- 105 - Third Deck
- 106 - Second Deck
- 107 - Main Deck and Hangar Deck
- 108 - Forecastle and Poop Decks
- 109 - Gallery Deck
- 110 - Flight Deck, Landing Platforms, Special Purpose
Decks above Weather Deck
- 111 - Superstructure
- 112 - Foundations for Propulsion Plant Machinery
- 113 - Foundations for Auxiliary and other Equipment
- 114 - Structural Bulkheads
- 115 - Trunks and Enclosures
- 116 - Structural Sponsors
- 117 - Armor
- 118 - Aircraft Fuel Saddle Tank Structure
- 119 - Structural Castings, Forgings and Equivalent Weldments
- 120 - Sea Chests
- 121 - Ballast and Buoyancy Units, Fixed or Fluid
- 122 - Doors and Closures, Special Purpose
- 123 - Doors, Hatches, Manholes and Scuttles - Nonballastic
- 124 - Doors, Hatches, Manholes and Scuttles - Ballistic
- 125 - Kingposts and Support Frames
- 127 - Sonar Dome
- 128 - Masts, Towers, Tetrapods, and Service Platforms
- 150 - Welding, Riveting, and Fastenings
- 151 - Free Flooding Liquids

Group 2 - Propulsion

- 200 - Boilers and Energy Converters (Non-Nuclear)
- 201 - Propulsion Units
- 202 - Main Condensers and Air Ejectors
- 203 - Shafting, Bearings, and Propellers
- 204 - Combustion Air Supply System
- 205 - Uptakes (Smoke Pipes)
- 206 - Propulsion Control Equipment (Non-Nuclear)
- 207 - Main Steam System
- 208 - Feedwater and Condensate System
- 209 - Circulating and Cooling Water Systems
- 210 - Fuel Oil Service System
- 211 - Lubricating Oil System
- 212 - Nuclear Steam Generators
- 213 - Reactors
- 214 - Reactor Coolant System
- 215 - Reactor Coolant Service Systems
- 216 - Reactor Plant Auxiliary Systems
- 217 - Nuclear Power Control and Instrumentation
- 218 - Radiation Shielding (Primary)
- 219 - Radiation Shielding (Secondary)
- 250 - Propulsion Repair Parts
- 251 - Propulsion Operating Fluids

Group 3 - Electric Plant

- 300 - Electric Power Generation
- 301 - Power Distribution Switchboards
- 302 - Power Distribution System (Cable)
- 303 - Lighting System (Distribution and Fixtures)
- 350 - Electric Plant Repair Parts
- 351 - Electric Power Generator Fluids

Group 4 - Communication and Control

- 400 - Navigation Equipment (Non-Electronic)
- 401 - Interior Communication Systems and Equipment
- 402 - Gun Fire Control System
- 403 - Countermeasure Systems (Non-Electronic)
- 404 - Electron Countermeasure Systems (ECM)
- 405 - Missile Fire Control Systems
- 406 - ASW, Torpedo Fire Control Systems (Surface Ships)
- 407 - Torpedo Fire Control System (Submarine)
- 408 - Radar Systems
- 409 - Radio Communication Systems
- 410 - Electronic Navigation Systems
- 411 - Space Vehicle Electronic Tracking Systems
- 412 - Sonar Systems
- 413 - Electronic Tactical Data System
- 450 - Communication and Control Repair Parts
- 451 - Communication and Control Operating Fluids

Group 5 - Auxiliary Systems

- 500 - Heating System
- 501 - Ventilation System
- 502 - Air Conditioning System
- 503 - Refrigerating Spaces, Plant, and Equipment
- 504 - Gasoline, HEAF, All Liquid Cargo Piping, Oxygen, Nitrogen,
and Aviation Lubricating Oil Systems
- 505 - Plumbing Installations
- 506 - Firemain, Flushing, Sprinkler, Washdown, and Salt Water
Service Systems
- 507 - Fire Extinguishing Systems
- 508 - Drainage, Ballast, Trimming, Heeling, and Stabilizer
Tank Systems
- 509 - Fresh Water System
- 510 - Scuppers and Deck Drains
- 511 - Fuel and Diesel Oil Filling, Venting, Stowage and
Transfer Systems
- 512 - Tank Heating Systems
- 513 - Compressed Air System
- 514 - Auxiliary Steam, Exhaust Steam, and Steam Drains
- 515 - Buoyancy Control System
- 516 - Miscellaneous Piping Systems
- 517 - Distilling Plant
- 518 - Steering Systems
- 519 - Rudders
- 520 - Mooring, Towing, Anchor and Aircraft Handling Systems and
Deck Machinery
- 521 - Elevators, Moving Stairways, Stores Strikedown, and Stores
Handling Equipment
- 522 - Operating Gear for Retracting and Elevating Units
- 523 - Aircraft Elevators
- 524 - Aircraft Arresting Gear, Barriers, and Barricades
- 525 - Catapults and Jet Blast Deflectors
- 527 - Diving Planes and Stabilizing Fins
- 528 - Replenishment at Sea and Cargo Handling
- 550 - Auxiliary Systems Repair Parts
- 551 - Auxiliary Systems Operating Fluids, Gases, and
Stabilizer Fluids

Group 6 - Outfit and Furnishings

- 600 - Hull Fittings
- 601 - Boats, Boat Stowage, and Handling
- 602 - Rigging and Canvas
- 603 - Ladders and Gratings
- 604 - Nonstructural Bulkheads and Nonstructural Doors
- 605 - Painting
- 606 - Deck Covering
- 607 - Hull Insulation
- 608 - Storerooms, Stowages and Lockers
- 609 - Equipment for Utility Spaces
- 610 - Equipment for Workshops, Laboratories, and Test Areas
- 611 - Equipment for Galley, Pantry, Scullery and Commissary
- 612 - Furnishings for Living Spaces
- 613 - Furnishings: Offices, Control Centers, Machinery Spaces
- 614 - Furnishings for Medical, Dental, and Pharmaceutical
- 615 - Radiation Shielding for Nuclear Support Facilities
- 650 - Outfit and Furnishings Repair Parts
- 651 - Outfit and Furnishings Operating Fluids

Group 7 - Armament

- 700 - Guns and Gun Mounts
- 701 - Ammunition Handling Systems
- 702 - Ammunition Stowage
- 703 - Special Weapons, Handling and Stowage
- 704 - Rocket and Missile Launching Devices (Surface to Air, Surface to Surface, and Sub-Surface)
- 705 - Rocket and Missile Launching Devices (Anti-submarine Warfare)
- 706 - Rocket, Missile, and Components Handling Systems
- 707 - Rocket, Missile, and Components Stowage
- 708 - Torpedo Tubes
- 709 - Torpedo Handling and Stowage
- 710 - Mine Handling Systems and Stowage
- 711 - Small Arms and Pyrotechnic Stowage
- 712 - Air-Launched Weapons Handling Systems
- 713 - Air-Launched Weapons Stowage
- 720 - Cargo Munition Stowage
- 745 - General Arrangement - Armament Drawings
- 750 - Armament Repair Parts
- 751 - Armament Operating Fluids

3 DEC 93

JAN - 3 1995

MAY 10 1995

MAR 13 1995

3

GAYLORD 83

Keep this card in the book pocket
Book is due on the latest date stamped

Thesis
F5763

Fontneau

Swath design model
for Coast Guard appli-
cations.

165472

thesF5763

Swath design model for Coast Guard appli



3 2768 001 96839 9

DUDLEY KNOX LIBRARY